

# Construction of microstructure and nutrient transport properties of tibial segmental implant prosthesis

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## Abstract

Segmental tibial bone defects caused by bone tumors, open fractures, and non-union of large bone segments are one of the challenges in orthopedic diseases. In existing research on load-bearing implants, it has been found that stress mismatch at the bone/implant interface leading to implant loosening and biological instability due to limited depth of bone ingrowth are key obstacles to the development of tibial implants. Therefore, in this study, the mechanical properties and internal fluid properties of three existing bone scaffold microstructures were investigated by finite element analysis. Based on the requirements of tibial segmental bone defect scaffolds, a composite scaffold with a GDP pore structure is prepared. The stress transmission mechanism of its microstructure model and the influence of internal scaffold microstructure on the transport of nutrients are studied. The newly proposed GDP pore structure is suitable for segmental bone defects similar to the tibial diaphysis.

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## 1. Introduction

In recent years, research in tibial implant tissue engineering has primarily focused on the structural and functional regeneration of target tissues. Three-dimensional scaffolds with appropriate pore structures, geometric shapes, and porosity play a crucial role in achieving this goal [1-3]. The pore structure of the implant is a direct determinant of the scaffold's mechanical performance, with key parameters including pore size [4], pore connectivity, uniform distribution, pore shape, and specific surface area [5, 6]. Regions with high connectivity provide sufficient space for the migration, proliferation, and differentiation of bone cells, while regions with low connectivity provide adequate mechanical performance for bone implants [7, 8]. From a biomimetic perspective, the purpose of designing porous metals via 3D printing is to fully achieve a structure, mechanical properties, and biological effects identical to the trabecular structure in natural bone [9]. However, this presents significant challenges, primarily due to the requirement that the metal used should approximate bone in mechanical properties, and the basic units, pore size, and porosity of the pores should be similar to natural bone [10]. Additionally, the material design must satisfy mechanical anisotropy. Therefore, biomimetic bone scaffolds are often designed based on functional biomimicry of bone.

Excellent bone defect scaffolds not only need to provide good initial mechanical stability postoperatively, but also require biological stability in the later stages. Vascularization within the porous structure and the speed of bone regeneration are key factors in achieving biological stability [11]. Therefore, scaffolds

with good material transport properties are also essential for osteogenesis [12]. After implantation of the scaffold into the bone defect area, blood flow carries nutrients, oxygen, and cell-activating factors into the interior of the scaffold, which are important for early vascular regeneration within the scaffold [13]. Appropriate pore size and pore structure are necessary conditions for osteoblast adhesion within the porous scaffold, and osteogenesis and vascularization often occur in concave areas within the porous scaffold [14]. Thus, larger axial curvature regions are needed to provide more space for osteogenesis and vascularization.

Therefore, in this study, starting from the structural design of tibial segmental bone defect scaffolds, an analysis was conducted on the mechanical properties and material transport characteristics of different crystal cell structures of TPMS. Based on the analysis results, implicit function parameters were redesigned, and scaffolds were constructed. The stress transmission process between bone and scaffold was analyzed, ultimately determining the microstructure of the novel scaffold, providing reference for the design of tibial segmental bone defect scaffolds.

## 2. Methods

In this study, three types of TPMS structures were initially constructed, namely: SchwartzD (D), Gyroid (G), and SchwartzP (P), to analyze the stress-strain patterns and scaffold material transport properties of different crystal cell structures. Based on the actual bone morphology of the tibial diaphysis, a hybrid crystal cell structure scaffold was constructed. Figure 1a

illustrates the three TPMS microstructure functions. To express the variation of curvature along the scaffold axis, Figure 1b depicts the curvature expression of the G-type scaffold in the YZ section. Figures 1c and 1d represent the boundary conditions used in this study, while Figure e illustrates the experimental apparatus designed for permeability testing in this study.

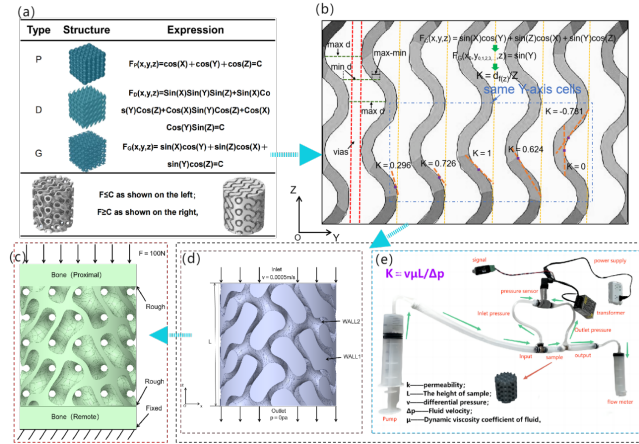


Figure 1. (a) Schematic representation and mathematical model implicit function expressions of P, D, and G models; (b) Representation and curvature calculation of the YZ interface; (c) Stress conduction boundary conditions; (d) Fluid flow boundary conditions; (e) Schematic diagram of the permeability experimental apparatus.

## 2.1 Boundary Conditions for Bone/Implant Stress Conduction Numerical Analysis

As shown in Figure 1(c), the boundary conditions for stress conduction are as follows: The material properties of the implant are defined as TC4 titanium alloy. The proximal and distal bones are defined as normal bone tissue. The mesh contact between the implant and the scaffold interface is defined as rough contact. No constraints are applied on both sides of the scaffold/implant. The upper boundary of the proximal end is defined as a compressive load of 100N. The lower boundary of the distal end is defined as a fixed constraint.

## 2.2 Boundary conditions for permeability analysis of support structures

The permeability needs to be analyzed in the corresponding fluid domain. As far as the bone scaffold is concerned, the pore area is the required fluid domain. According to the literature report [15], the permeability range of human bone is  $0.027 \times 10^{-9}m^2 - 20.000 \times 10^{-9}m^2$ . In the process of CFD analysis, the Navier-Stokes equation of incompressible steady laminar flow is described calculate [16]

$$\left\{ \begin{aligned} \rho \frac{\partial u}{\partial t} - \mu \nabla^2 u + \rho(u \cdot \nabla)u + \nabla P &= F \\ \nabla \cdot u &= 0 \end{aligned} \right.$$

In the form  $\rho$  —Fluid density

$u$  —Fluid velocity

$t$  —time

$\mu$  —Dynamic viscosity of fluid

$\nabla$  —del operator

$P$  —pressure

$F$  —Gravity or centrifugal force

The boundary conditions applied for CFD analysis are shown in Figure 1 (d), and the region with  $F \geq C$  is considered as the fluid model. The inflow surface (Inlet), outflow surface (Outlet), solid wall 1 (Wall1), and solid wall 2 (Wall2) are shown in the figure. The liquid flowing through the pore area of the scaffold is assumed to be capillary blood, with an inlet flow rate of 0.0005m/s applied on the inlet surface and 0 outlet pressure applied on the outlet surface. Wall1 and Wall2 are defined as non sliding wall surfaces, with a fluid viscosity of 4.2mPa.s. The relevant settings are summarized in Table 1.

Table 1. Related settings in permeability calculation

Permeability calculation	
analogy procedure	Single-phase flow in direction Z
metallic liquid	Capillary blood (incompressible: viscosity 0.0042kg/ms, density 1050kg/m3)
size of mesh opening	Octahedral unit $\square$ Size approx $\square$ 0.0002mm (0.002% of structural size)
boundary conditions	IN $\square$ Inlet velocity 0.0005m/s OUT $\square$ outlet pressure 0Pa
output parameter	Inlet volume flow, inlet pressure

Combined with Darcy's law, in order to measure the permeability  $k$  of the stent, figure 1 (e) is a permeability experimental device. The water from the water pump gets the pressure difference between the two sides of the bracket through the pressure difference sensor, and the bracket is wrapped in the sample warehouse made of heat-shrinkable pipe to ensure the close cooperation of the bracket and prevent the liquid from leaking from both sides. The Flowmeter is used to control the flow into the sample and finally the liquid flows out. Repeat the measurement five times for each sample.

## 3. Construction of stent for segmental bone defect of tibia and analysis of finite element results

### 3.1 Finite element results and discussion of different cell structures

#### 3.1.1 Analysis of stress and strain results of different cell structures

As shown in figure 2, the minimum equivalent stress is G-type stent and the maximum is D-type stent; the minimum displacement on the main section of YZ is G-type stent and the maximum is P-type stent; the minimum equivalent stress is G and the maximum is P-type stent. As shown in Table 2, the stress distribution of G-type support is more uniform and the axial displacement is lower under the same load. The stress of P-type stent is concentrated on the surface, and the stress distribution of P-type stent is more uniform at the same horizontal position, but the axial displacement is the largest. From the mises stress distribution of YZ cross section, it is known that the stress value of G-type single crystal is the lowest at the curvature = 1 and the maximum at the curvature of 0. Figure 3 shows the mises stress values of G-type stents with different curvature changes in the single cell.

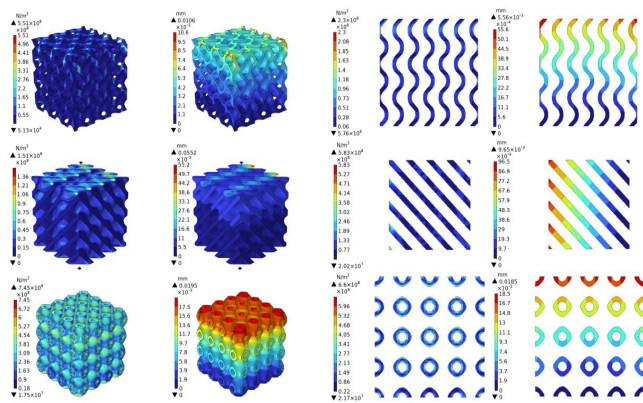


Figure 2. FEA results of scaffolds with different cell structures

Table 2. Maximum Von mises and Disp tables of different cell structures

Type	mises □N/m <sup>2</sup>	Disp □mm	YZ-mise s□N/m <sup>2</sup>	YZ-Dis p□mm
G	5.51×10 <sup>8</sup>	0.0106	2.3×10 <sup>8</sup>	0.0556
D	1.51×10 <sup>9</sup>	0.0552	5.83×10 <sup>8</sup>	0.0096
P	7.45×10 <sup>8</sup>	0.0195	6.6×10 <sup>8</sup>	0.0185

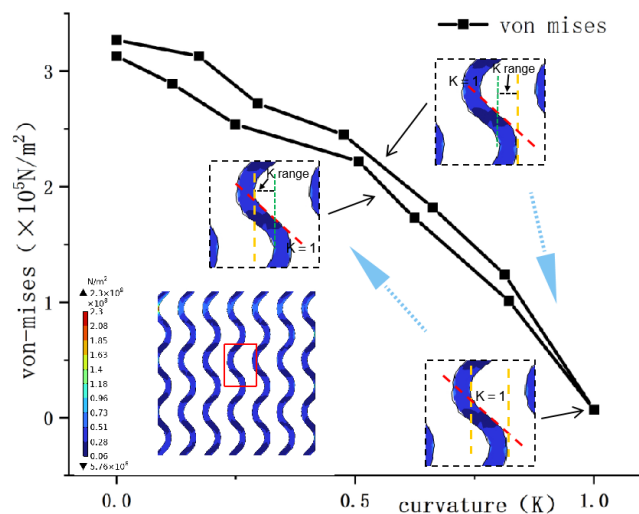


Figure 3. Mises stress values of different curvature changes in the single cell of G-type stents

### 3.1.2 Analysis of CFD results with different cell structures

Figure 4 shows the results of CFD flow velocity with different cell structures. The maximum flow velocity of G-type stent is smaller than that of other stents, which is due to the good connectivity of G-type and the formation of axial through-hole is smaller than the other two types. It can be seen that the flow velocity in the center of the channel is significantly higher than that in the surrounding area, which can transport nutrients to deeper pores, which is conducive to cell migration, proliferation and differentiation [17, 18]. Because the flow velocity in the center is higher than that on both sides, the nutrients in the center of the channel are squeezed to the surrounding area, and the

curvature of the surrounding area is large. Osteoblasts adhere to the surrounding area for osteogenesis and differentiation, and P-type scaffolds form external flow field and internal flow field. The velocity of the external flow field is obviously lower than that of the internal flow field. In the internal flow field, the velocity in the region with low curvature is obviously higher than that in the region with high curvature, and the smaller the curvature in Z direction is, the higher the velocity is. Because the curvature of P type at the cell junction is close to 0, so the velocity at the junction is abnormally high, so the nutrient flow rate of P type stent will be faster, but the efficiency of osteogenic adhesion on the surface with high curvature in Z direction will be lower. The osteogenic adhesion formed on both sides of the low curvature can not be converted into large pieces of bone between the crystal cells, so in the microstructure design of the porous scaffold, the high curvature in the Z direction should not be used to form the through hole directly, but the cross of the cell structure should be used to form the through hole. The through hole formed by the D-shaped support due to structural reasons is not a Z-direction through hole, but a 45°oblique through hole, and the surface has no curvature change. Therefore, after constructing the boundary conditions shown in figure 1 (d), it is found that there is no outflow at the bottom, and the flow velocity is concentrated on both sides of the support.

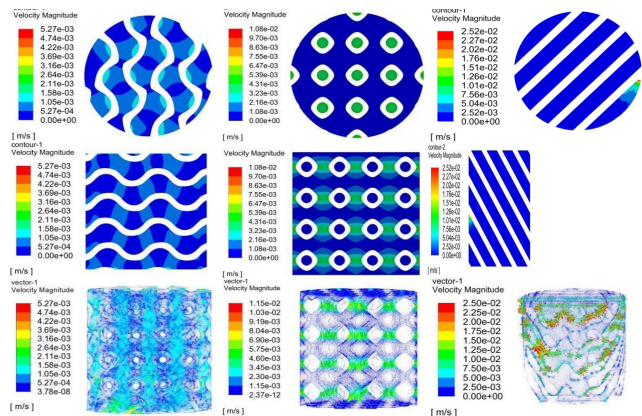


Figure 4. CFD Velocity results with different Cell structures

Figure 5 shows the CFD flow pressure results for different crystal cell structures, where the flow pressure results are directly proportional to the flow velocity results. Both G-type and P-type scaffolds exhibit the formation of two flow domains within the scaffold, with significant differences in flow velocity and pressure drop between the two domains, particularly evident in the P-type scaffold. The D-type scaffold forms multiple flow domains.

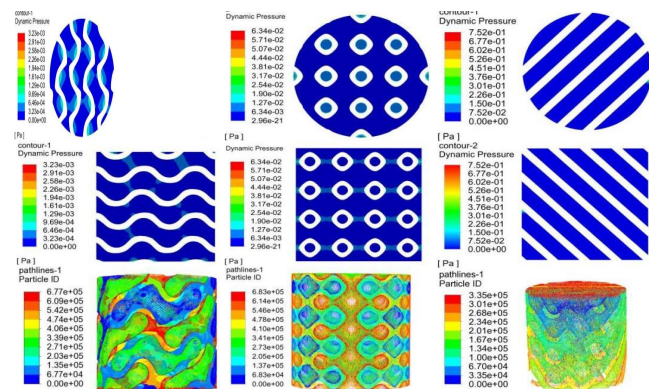


Figure 5 Results of CFD flow pressure with different cell structures.

### 3.2 Construction and Finite Element Results of Tibial Segmental Bone Defect Scaffold

A hybrid scaffold structure was designed from a functional perspective. The finite element results mentioned above indicate stress concentration on the "tooth surface" of the D-type scaffold. Utilizing this phenomenon, it can be advantageous for the initial stability of the bone defect scaffold. The stress distribution on the same XY section of the P-type scaffold is uniform. Therefore, we assumed a composite bone scaffold, with the G-type scaffold as the main body. The D-type scaffold is integrated axially proximally to the scaffold, providing initial mechanical fit with its unique "tooth surface". The P-type bone scaffold is integrated axially distally to the scaffold to ensure a larger contact area at the bone/scaffold interface.

When constructing the mixed cell structure, when observing the G, D and P models [19-21], it is found that the function of the D type structure can be changed into the similar structure of the G P type under certain conditions. when Z, X and Y are 0 respectively, the D structure becomes:

$$F_D(x,y)=\sin[X]\cos[Y]+\cos[X]\sin[Y]$$

$$F_D(y,z)=\sin[Y]\cos[Z]+\cos[Y]\sin[Z]$$

$$F_D(x,z)=\sin[X]\cos[Z]+\cos[X]\sin[Z]$$

In this case, the D structure is similar to the G function to some extent. According to this phenomenon, we establish the D function to rotate its x, y, z, that is:

$$x \rightarrow \text{tran}[1], y \rightarrow \text{tran}[2], z \rightarrow \text{tran}[3]$$

$\text{tran}=\text{EulerMatrix}\{x,y,z\}$

Where EulerMatrix represents the rotation matrix Euler rotation angle, on this basis, another rotation under the current coordinate axis, that is,

$$x \rightarrow \text{tran}_1, y \rightarrow \text{tran}_2, z \rightarrow \text{tran}_3$$

When the rotation returns the Z axis to its original position, the function becomes:

$$F_{GDP}(x,y,z)=\sin[AX+BY]\sin[BX-AY]\sin[Z]+\sin[BX-AY]\cos[AX+BY]\cos[Z]+\cos[BX-AY]\sin[AX+BY]\cos[Z]+\cos[BX-AY]\cos[AX+BY]\sin[Z]=C$$

Where An and B are constants and  $A^2+B^2=1$ . As shown in Fig. 6 are the orthographic, upper and lower diagrams of the constructed function, respectively, in which the upper surface is similar to the G structure, the upper surface is similar to the D structure, and the lower surface is similar to the P structure, so the model of this mixed microstructure is defined as GDP scaffold.

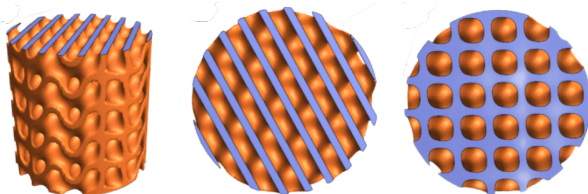


Figure 6. Front View, Top View, Bottom View of the GDP Scaffold

Figure 7 displays the finite element analysis results of the GDP scaffold. The GDP scaffold meets the preliminary design requirements for tibial scaffold. The proximal interface exhibits

a tooth-like structure to provide initial mechanical bonding, while the distal interface offers a larger bone contact area, thus confirming the initial assumption.

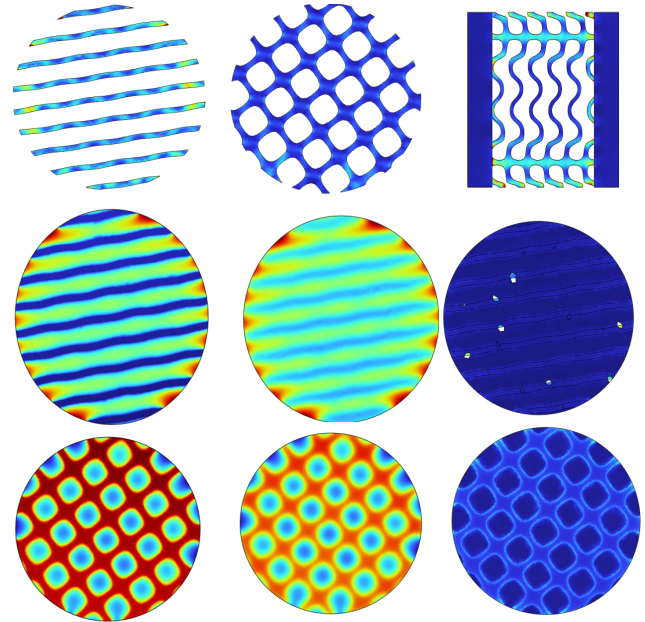


Figure 7. Finite Element Analysis Results of the GDP Scaffold

Figure 8 shows the fluid analysis results of the GDP pore scaffold. There is a greater difference in flow velocity between the center of the channels and the surrounding areas. In the Z-direction, the fluid exhibits a "gourd" shape, and it is observed that the middle flow velocity of the GDP pore scaffold is faster. This is mainly because the design parameters of the GDP pore scaffold include the P structure, where the sides of the P structure are in a closed state, resulting in larger diameters of the central channels. Additionally, the curvature of the triply periodic minimal surface (TPMS) around the channels in the peripheral area of the flow is lower due to the presence of the P structure, and the connectivity of the P structure is not as strong as that of the G structure. Therefore, owing to the presence of the G structure elements, the scaffold exhibits higher flow velocity regardless of whether it is viewed from the Y-axis or Z-axis in the YZ direction. Since the flow velocity on the outer side of the scaffold is lower, bone ingrowth is more likely to occur on the inner walls of the holes on the outer side. This further confirms that the GDP pore scaffold is more suitable for large segmental defects of the tibial diaphysis.

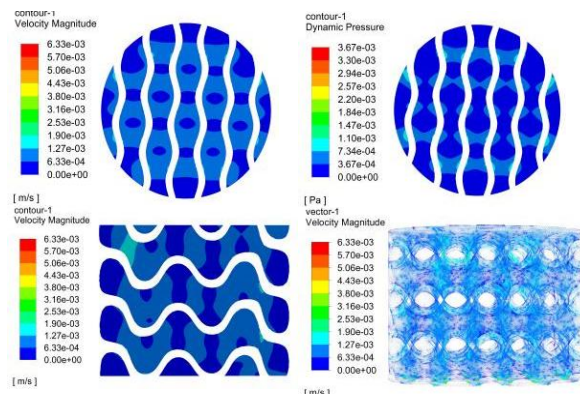


Figure 8. CFD Finite Element Analysis Results of the GDP Scaffold

Figure 9 depicts the stress conduction process of the GDP scaffold. The stress variations of the bone and scaffold at the proximal end during the first, second, and third elastic stages are relatively close, indicating a good fit between the proximal interface bone and scaffold. After the third elastic deformation, the stress values within the bone decrease and gradually approach those of the distal scaffold. The Mises stress transfer process in the distal bone of the GDP scaffold exhibits a more stable range of variation. After the third elastic deformation, the Mises stress of the scaffold begins to stabilize, while the proximal bone continues to undergo 8 deformations after the third elastic deformation before reaching stability, due to its integration with the scaffold. Therefore, the stress conduction process of the GDP scaffold demonstrates optimal mechanical performance. The fitting mechanism at the proximal bone interface provides assurance for later mechanical stability, while the stable stress changes in the distal bone provide a platform for further bone ingrowth into the scaffold.

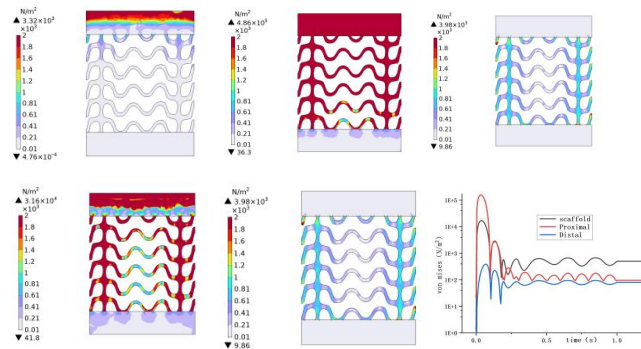


Figure 9. Stress Conduction Process of the GDP Scaffold

As shown in Figure 10, the calculated elastic modulus and compressive strength of the support are 7.38Gpa and 326Mpa, and there is no excess deviation of the support during the compression process.

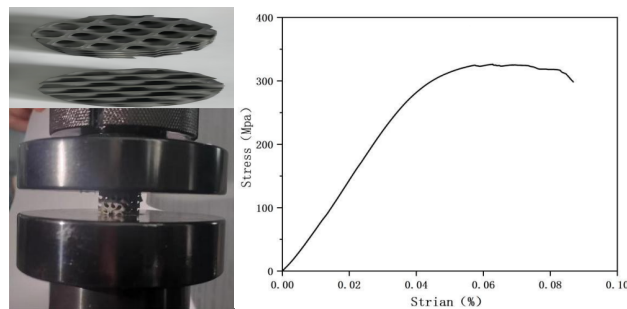


Figure 10. 3D printing of GDP bracket and its mechanical properties

#### 4. Conclusion

In this study, the microstructure design of tibial segmental implant scaffolds was the focus of research. Finite element analysis was initially conducted on three scaffold structures. The results showed that the structural performance of the G-type scaffold was more stable, with a uniform distribution of Mises stress. Within the microscale curvature range of 0-1, the Mises stress decreased as the curvature increased. When the curvature was 1, the local Mises stress value was  $0.07 \times 10^8 \text{ N/m}^2$ . The G-type scaffold had the lowest flow velocity compared to the P and D-type scaffolds, but it exhibited better fluidity, making it suitable for inward bone tissue ingrowth. Based on these findings and considering the mechanical and biological requirements of tibial implant scaffolds, a composite

scaffold structure, termed GDP, was constructed. Through finite element analysis and discussion, it was concluded that the GDP scaffold meets the design requirements of the tibial diaphysis.

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