

# Accurate Location Prediction of Social-Users Using mHMM

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#### ABSTRACT

Prediction space of distinct check-in locations in Location-Based Social Networks is a challenge. In this paper, a thorough analysis of Foursquare Check-ins is done. Based on previous check-in sequences, next location of social-users is accurately predicted using multinomial-Hidden Markov Model (mHMM) with Steady-State probabilities. This information benefits security-agencies in tracking suspects and restaurant-owners to predict their customers' arrivals at different venues on given days. Higher accuracy and Steady-State venue-popularities obtained for location-prediction using the proposed method, outperform various other baseline methods.

KEY WORDS: Foursquare Check-ins, Hidden Markov Model, Location-Based Social Networks, Location Prediction, Temporal Context.

# **1** INTRODUCTION

LOCATION-Based Social Networks (LBSNs) like, Foursquare, are progressively becoming an important part of a social-user's life, from connecting with friends and sharing images, to discovering new geographical areas and locations. These applications help us to comprehend, investigate, explore, and geographically record the spots we live in LBSNs permit us to spatially check-in to famous places of a city, updating rich databases that hold computerized engravings of our associations at the same time. The LBSNs Application Programming Interfaces (API's) help to figure out the places where the users are present at any instant of time. This geographic information analysis can uncover the psychotopography and financial territory of social-users of a city.

LBSN users update and share what they do, where they are and how they feel at a particular time or place. In addition, users uncover when and where they are experiencing a passionate emergency, encountering their very own paradise or damnation, having a good time or a prophetically calamitous occasion. This information, with more conventional government informational indexes, reveals the manner in which the money-related occurrences are linked with these applications. It is a common fact that, more the business importance of an area, more are the number of check-ins from that place. LBSNs can notify a user about the check-in status of their friends to nearby geographical locations with the help of the network itself or by a third-party service provider. User preferences can be explored to enable personalized location-based systems by analyzing the data entered into the LBSNs.

User behavior in LBSNs is highly affected by issues like social relationships and spatio-temporal constraints (Du, Yu, Mei, Wang, Wang & Guo, 2014). (Zhao, He, Zhang, Liu, Zhai, Huang & Liu, 2016; Xiao, Lu & Liu, 2016) analyzed dynamic social-user behavior metrics using trust model and distributed parallel clustering grid respectively in different networks. User preference for various activities is based on the content and context (spatial and temporal) along with the common social interests that help in creation of social communities. The challenge is to comprehensively combine this heterogeneous information in a systematic way, to predict locationbased activities of a user. Presence of a user at a certain venue depends on his/her social relationships with the host and other nearby users. The host has a greater role to play in user's preference at a particular venue due to the location and time constraints of activities. So, the host can give better recommendation options for a particular visitor at a place. A privacy mechanism in which user's location data is altered and thus important profits for users are held back, should not be adopted by LBSNs. Users may not like their location information to be hidden from their friends who may be in their vicinity and can join them at an event. The information shared by users through

LBSNs can be used by security agencies to track a particular user on a given day at some place with the help of a prediction model.

For location-prediction, Hidden Markov Model (HMM), a generative probabilistic model, can be used in which a sequence of observations is generated by a sequence of internal hidden states and cannot be observed directly (Sutton & McCallum, 2006). The inter-state (hidden) transitions resemble first-order Markov chains that are specified by the start probability vector  $\pi$  and a transition probability matrix *A*. An observation's emission probability on a hidden state gives different distributions with parameter *B*. This observation sequence can be useful for probabilistic models in case of predicting the hidden state sequences and obtaining the Steady-State probabilities.

In this paper, we analyze LBSN user check-ins and predict the location of LBSN users accurately using multinomial-Hidden Markov Model (mHMM). The digital traces of user check-ins are analyzed to build a user-preference model based on the social relationships and spatio-temporal limits on LBSN users. In addition to user preferences, location of social users is predicted using historical user-venue state sequences. We formulate and parameterize the above elements with the help of user check-ins, into a statistical model using mHMM. It estimates the hidden information in the system by leveraging the known data. In our system, the hidden information which we are calculating, is the location-prediction of LBSN users with the help of previous check-ins. It can be really useful for security agencies in tracking suspects at a particular time based on the LBSN check-in data. At the same time, our model helps the restaurant owners to keep track of their customers' arrivals on particular days and times and also know their food choice pattern well in advance, that can save time and resources. Also, Steady-State probabilities are calculated for all the venues in the city, to formulate the chance of survival for a particular venue in the long-run. We obtain a high accuracy for location-prediction as compared to the other state-of-the-art-methods that formulate the category prediction of venues.

The rest of the paper is organized as follows: the next section includes the description of background and related work in the areas of Foursquare-LBSN and HMM. In section 3, the proposed work for the location prediction after a detailed analysis of LBSNs, is presented. Next, in section 4, the experimental evaluation and thorough result analysis is provided. The complete simulation process is depicted along with an example. Finally, we conclude our paper, along with some future directions, in section 5.

#### 2 BACKGROUND AND RELATED WORK

WE briefly introduce some important existing works done on LBSNs; analysis, categorization and

working with a quick grasp of the associated limitations. The focus is on related research involving Foursquare LBSNs and use of HMMs for information prediction, along with a brief look at the Steady-State probabilities using Markov chains.

# 2.1 Foursquare LBSN

Foursquare, a well-known LBSN, with the main motive of enabling its users to share their geographical-locations (Venues) with friends, has nearly 55 million monthly active users and 8 million average number of daily check-ins on the Swarm app (Foursquare stats, 2017). It has the potential to a review application along with being a social networking service. Check-in is manual and can be done even from a remote location around a city, raising some eye-balls regarding the security of the application. Checking-in at a new place gives rise to a new Foursquare Venue and this information is shared in the user-network. Foursquare categorizes its venues with a three-level hierarchical category classification with 9 main groups which are further classified into 291 categories at the second level with incomplete classifications at the third level (Aggarwal, Almeida, & Kumaraguru, 2013; Yang, Zhang, Qu & Cudré-Mauroux, 2016; Noulas, Scellato, Mascolo & Pontil, 2011). Some of the primary venues categorically recognized in Foursquare include Food, Travel-Spots, Great-Outdoors, etc. Users can earn different badges as per the number of check-ins at a particular venue. Mayor is a special badge given to the user with the most number of check-ins at a restaurant for a period of 2 months. Restaurant owners and other companies offer rewards to Foursquare members and special ones like a free appetizer to its Foursquare mayor. But this can sometimes lead to people cheating to get rewards also. Users can leave positive or negative feedback for a venue visited in the form of publicly visible Tips. For putting a tip, however, a user may or may not have to check-in to any place. These tips can help other visitors who plan to check-in to the same place.

Generic and personalized location recommendation have been studied. (Mao, Jiang, Min, Leng, Jin & Yang, 2017) summarized characteristics, design requirements, architecture and surveyed state-of-theart technologies in mobile SNs. Similarly, (Gasparetti, 2017) studied the existing and future research challenges for location search in LBSNs, which mainly focus on the accurate user preference recommendations, and privacy and serendipity issues. Public opinions for famous venues are used in generic location recommendation, where-in users receive identical suggestions as individual preference is lacking (Cao, Cong & Jensen, 2010). On the other hand, user preference is considered individually in personalized location recommendation systems like matrix factorization (Cheng, Yang, King & Lyu, 2012; Ye, Yin, & Lee, 2010; Ye, Yin, Lee & Lee, 2011) and collaborative filtering (Bao, Zheng & Mokbel, 2012;

Zheng, Zhang, Ma, Xie & Ma, 2011). (Thilakarathna, Seneviratne, Gupta, Kaafar & Seneviratne, 2017) have studied characteristics and evolution of location-based communities based on a social discovery network and geographic proximity.

The venue-location influences users' check-in behaviors (geographical influence), which in-turn helps in making location predictions with new trials to infer users' preferences. The geographical influence can be modelled as a two-dimensional check-in probability density because the probability of a location visited depends on both the location's distance and the intrinsic characteristics (Ye, Yin, Lee & Lee, 2011; Yang, Zhang, Yu & Wang, 2013). (Yang, Zhang, Yu & Wang, 2013) focused on associating location with users and content and scrutinize the potential attacks and protection techniques in GeoSNs for various privacy features including location and identity privacy. The pros and cons of information-disclosure and Privacy in LBSNs have been studied in detail by (Farrelly, 2014); Coppens, Veeckman & Claeys, 2015; Zhao, Lu & Gupta, 2012; Sun, Xie, Liao, Yu & Chang, 2017). Their findings indicate that Foursquare users sought, appreciated and made creative use of the application's geographically relevant place information, enable them to dynamically engage with the place and to create their own meanings. (Litou, Boutsis & Kalogeraki, 2017) have proposed LATITuDE system for efficient dissemination of emergency information, by selecting an appropriate subset of social-users, so that the spread of information is maximized, time constraints are satisfied and costs are considered.

#### 2.2 Hidden Markov Model (HMM)

Hidden Markov Models (HMMs) have been the most effective statistical models in computations and are used to model a lot more complex stochastic processes, as compared to a customary Markov model (Sutton & McCallum, 2006). (Baum, & Eagon, 1967; Baum, Petrie, Soules & Weiss, 1970) have published the fundamental theory related to HMM. HMM is "a doubly stochastic process with an underlying stochastic process that is not directly observable (it is "hidden") but can be observed only through another stochastic process that produces the sequence of observations" (Cappé, Moulines & Rydén, 2007). HMM has a set of countable states directed by a set of transition probabilities and an observation sequence can be generated as per an associated probability distribution for every state where only the final result is obtained with the state being invisible to the external observer (Rabiner, 1989).

(Gambs, Killijian & del Prado Cortez, 2012) have extended a mobility model called Mobility Markov Chain (MMC) in order to incorporate the n previous visited locations for next place prediction. They have used the Phonetic, GeoLife and Synthetic datasets with 6, 175 and 1 users, respectively. They incorporated the traces per user, duration of capture, frequency and POI per user as attributes. (Mathew, Raposo & Martins, 2012) present a hybrid method for predicting human mobility as per their characteristics by training HMMs for each cluster and obtained a prediction accuracy of 13.85%, based on the geographical distance between regions over the GeoLife project. (Raghavan, Ver Steeg, Galstyan & Tartakovsky, 2014) developed probabilistic models for temporal activity of social users by incorporating the social network influence as perceived by users based on coupled-HMM.

Continuous Hidden Markov Model (CHMM) was used for developing different recognition models in Intelligent Transportation System that could distinguish regular lane keeping aim from the right and left lane change intentions (Hou, Jin, Niu, Sun & Lu, 2011). (Lane, 1999) studied the deviation from an expected human behavior to detect a malicious socialuser by user profiling, based on the posterior likelihood of the model parameters in the HMM. (Li & Li, 2014) introduce a new check-in-based HMM which analyses temporal check-in intervals of users before suggesting locations. To predict the most probable time period, the user will check in next time and also recommend a specific user group for the new entrant. Thus, it can be used to predict the user's check-in location trends with a small but valuable accuracy of 32.54%, 26.39%, and 26.74% for different variations of Gowalla dataset and similar accuracy to some degree for Brightkite datasets. (Ye, Zhu & Cheng, 2013) have used the mixed-HMM to predict the most likely location category, based on user activity at the next step in considerably condensed prediction space. They obtained the best accuracy of 44.35% for category prediction using mixed-HMM. (Gao, Tang & Liu, 2012) have proposed a socialhistorical model that assesses the role of social correlation in user's check-in behavior in forms of power-law distribution and short-term effect on LBSNs. They have obtained a location-prediction accuracy of 15% - 35% using various models on Foursquare LBSN.

Some basic types of problems that can be solved with HMM (Rabiner, 1989) include: calculating sequence state explaining the observation; probability calculation of the observation sequence for a model; and optimizing the system parameters for obtaining observations. We are trying to solve the latter type of problem in our system using mHMM. For accurate location-prediction, we have implemented mHMM that incorporates the known data of the system and uses it, to estimate the unknown information in the system. The multinomial distribution is the probability distribution of the outcomes from a multinomial experiment, where each trial has a discrete number of independent possible outcomes. We train mHMM by using the spatial and temporal information of users' activities, to further improve the model accuracy.

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HMM can be defined as  $\lambda = (S, A, B, \pi)$  having the following fundamental elements:

- (i) The total count of model-states S.
- (ii) Transitions probability Matrix  $A = \{a_{ij}\}$ .
- (iii) Observation set Matrix  $B = \{b_{jk}\}$ .
- (iv) Initial state values  $\pi = {\pi_i}$ .

# 2.3 Expectation Maximization (EM) Algorithm

The EM algorithm is an iterative algorithm to find maximum likelihood or maximum a posteriori (MAP) estimates of parameters, where each iteration includes Expectation and Maximization steps (Bilmes, 1998).

#### 1. Expectation step:

In this step, using model parameter  $\theta$ , the probability  $P(0|\theta)$  of the given observation sequence *O* is obtained using Eq. (1).

$$P(O|\theta) = \prod_{i=1}^{N} p(o_i|\theta) = L(\theta|O)$$
(1)

2. Maximization step:

In this step, we try to adjust model parameters  $\theta$  so that the above probability is maximized.

$$\theta^* = \underset{\theta}{\operatorname{argmax}} L(\theta|0) \tag{2}$$

The parameters for the new model in terms of old model can be obtained with the following equations for the mixing coefficient  $\alpha$ , mean  $\mu$  and covariance matrix  $\sum$ , where  $l \in 1, 2, ..., M$  (Component densities).

$$\propto_l^{new} = \frac{1}{N} \sum_{i=1}^N p(l|o_i, \theta^g)$$
(3)

$$\mu_l^{new} = \frac{\sum_{i=1}^N o_i p(l|o_i, \theta^g)}{\sum_{i=1}^N p(l|o_i, \theta^g)} \tag{4}$$

 $\sum_{l}^{new} = \frac{\sum_{i=1}^{N} o_i p(l|o_i, \theta^g) (o_i - \mu_l^{new}) (o_i - \mu_l^{new})^T}{\sum_{i=1}^{N} p(l|o_i, \theta^g)}$ (5)

Until the difference between the new model and the previous model parameters is less than a certain threshold, the iterations are continued. The above equations are used for both steps of EM simultaneously.

# 2.4 Viterbi Algorithm

Viterbi algorithm is a recursive programming algorithm that determines the most probable sequence of underlying hidden states from an observation sequence that might have generated it (Forney Jr, 2005). It finds maximum overall state-sequences possible with the help of HMM parameters. The maximum probability of reaching a particular intermediate state is defined by the partial probability  $\delta$ , ( $\delta_t(i)$  being the maximum probability of all sequences ending at state i at time t). Thus, the best state-sequence can be obtained by the following steps:

$$\begin{aligned} I. \quad Initialization \ step: \\ \delta_1(i) &= \pi(i)b_i(o_1), \qquad 1 \le i \le N \end{aligned} \tag{6}$$

Where  $b_i(o_l)$  is the probability of emitting response time  $o_l$  in state *i*.

2. Recursion step:  

$$\delta_t(i) = \max_j (\delta_{t-1}(j)) * a_{ji} * b_i(o_t)$$
(7)

The final step is to determine the arrival of the state *i* at time *t* optimally after calculating the system probability for the previous state at time t - 1. A back pointer  $\emptyset$  points to the previous state that optimally incites the current state in the termination step.

3. Termination step:  

$$\phi_t(i) = \operatorname{argmax}_j(\delta_{t-1}(j)) * a_{ji}$$
(8)

Where argmax operator selects the index *j* which maximizes the bracketed expression.

#### 2.5 Steady-State Probability

A system is said to be in a Steady-State, if the variables used to define the system-behavior, do not change with respect to time. Markov chain model can be effectively used for obtaining the Steady-State behavior of people visiting a particular venue over a longer period of time. The *n*-step transition probabilities  $r_{ij}(n)$ , can be converged to steady-state values, independent of their initial states. The rows of this limiting matrix contain the probabilities of being in the various states as time gets large. These probabilities are called Steady State (SS) probabilities (Bertsekas & Tsitsiklis, 2002). Thus, the SS probability of state *j*, for large *n*, can be interpreted as

$$\pi_j \approx P(X_n = j) \tag{9}$$

A Markov chain with recurrent aperiodic classes having *j* states with  $\pi_j$  SS probabilities has the following properties.

$$\pi_j = \sum_{k=1}^m \pi_k \cdot P_{kj} \tag{10}$$

$$\sum_{k=1}^{m} \pi_k = 1 \tag{11}$$

Eq. (10) is called the *Balance* equation and Eq. (11) is called the *Normalization* equation. The unique SS solution to the system is given by the quantity  $\pi_j$ , where j = 1, ..., m. Assuming  $\pi_j > 0$ , for all recurrent states j and  $1 \le (i, j) \le m$ , the *transition-probability* matrix is :

$$P = [p_{ij}] \tag{12}$$

Using Eq. (12), the SS probabilities for different venues can be obtained that gives the measure of the popularity of various venues surviving at a place.

#### **3 PROPOSED WORK**

IN the proposed work, we thoroughly analyze the Foursquare check-in patterns in two major world cities, New York and Tokyo in section 3.1, with extensive LBSN user count. It helps in formalizing the preferences of various social-users at different times of a day. Next, the temporal context of users is studied that gives the daily and weekly periodical patterns of their visits to different venues. Finally, we formulate our model using mHMM for location prediction in LBSNs. Our model predicts the exact venue a particular user visits. In addition, we also predict the customers visiting a particular restaurant/venue on a given day of the week. Steady-State probabilities are obtained for depicting the chance of survival of a particular restaurant or venue in the future.

# 3.1 Analyzing Foursquare check-ins expressing city pulse

Every day, millions of people check-in at Foursquare. The check-ins data for one year taken from New York and Tokyo cities is plotted on a map29 (Foursquare check-ins pulse, 2017). Interesting visualizations of ebbs and flows of the cities are generated by the start-up data. Single check-ins are represented by individual dots, while the sequential check-ins are linked by straight lines. The condensed check-ins representation shows the city appearance on a usual day. It specifies where people are present at any moment of the day and how, when, and why they're going there. LBSNs users show a more pronounced range of check-ins activity near more commercial places in cities. In the following figures, we depict the snapshots of check-ins done by New York and Tokyo Foursquare users at various times of the day that help in the analysis of the check-in patterns.

#### 3.1.1 Check-in pattern in New York City

We show instances of check-ins at four different times of a day in New York City in figure 1. Figure 1(a) shows that at 2 AM, the highest number of checkins are done at *nightlife spots* (Blue), while most of the other places remain silent. However, in figure 1(b), the image captured at 8 AM, depicts a completely different view, where more people get active at this time and check-in at *Professional and other places* (Yellow). As shown in figure 1(c) at 3 PM, *Shop and Services* (Orange) have the most number of check-ins while *General Food places* (Green) are seen abundantly at 8 PM at night in figure 1(d). It shows that once the day sets in, users prefer to go at *Professional Food places* and as the day progresses show an increased presence in outdoor places, with least amount of activity during late nights.



(a) 2 AM



(b) 8 AM



(c) 3 PM



 $(d) \ 8 \ PM \label{eq:product}$  Figure 1. Check-in patterns in New York City.

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#### 3.1.2 Check-in pattern in Tokyo City

In the following four visualizations of check-ins at Tokyo City (figure 2), it can be clearly seen that most of the check-ins during the whole day occur at venues like *Travel and Transport places* (Green) followed by *Food places* (Indigo). Major activity pattern at the initial part of the day shows great rush at the Travel and Transport places and there is slow but steady increase in the user-activity at other Food places as the day progresses.



(a) 1 AM



(b) 8 AM



(c) 3 PM



(d) 8 PM

Figure 2. Check-in patterns in Tokyo City.

# 3.2 Temporal context

The check-in patterns studied in previous section showed the time-based daily visiting frequency of LBSN users. The temporal context depicts the periodical patterns of user check-ins, where they can show strong daily and weekly periodical affinity for various venues that can help in location prediction. The locations or venues a social-user visits in day-today life, generally display a cyclic phenomenon over days of the week. The user preference to different venues can be calculated using the day of the week factor  $P_u(v)$  in the following Eq. (13):

$$P_u(v, v_i) = \begin{cases} 1, d(t_v) = d(t_{v_i}) \\ 0, d(t_v) \neq d(t_{v_i}) \end{cases}$$
(13)

where  $d(t_v)$  represents the day when the user visited venue v in the week, and  $d(t_{vi}) \in \{\text{Sunday}, \text{Monday}, \}$ ...., Saturday}. Figure 3 shows the venues with the highest number of visits during weekdays and weekends for first 15 users in New York and Tokyo datasets. It depicts the difference between the patterns of visits. For example, at New York, user-1 visits bar more often over the weekend as compared to weekdays. Similarly, user-2 prefers Coffee Shop during weekdays that can be located near his workplace and goes to the gym more on weekends. In case of Tokyo, user-2 visits office more in the weekdays and goes to train-station on weekends. For user-14 the scenario is almost reverse, showing more visits to the train-station on weekdays and electronics-store at the weekend.









(c)



(d)

Figure 3. Temporal Context in Check-in patterns in New York and Tokyo Cities over Weekdays and Weekend.

# 3.3 mHMM for user location prediction in LBSNs

The proposed model predicts the location of LBSN users with the help of their sequence of visits on previous occasions to particular places. Most of the existing work deals with clustering the venues based on their type or specialty and then predicting the category where the user can visit (Ye, Zhu & Cheng, 2013; Gao, Tang & Liu, 2012). We, in our proposed approach, try to predict the exact location of a user and not the category, as proposed in previous works and obtain a much better prediction accuracy. It makes easier to predict, where a user can visit in an unambiguous way using the proposed model. It is important because in most of the cases of Foursquare venues, multiple venues can exist under same foodcategory. Therefore, the exact location of a suspect at a particular time, can help the security agencies to track the person efficiently. In addition, by interchanging the parameters of our model, it can be used by the restaurant owners to know the arrival of their customers on a particular day and time. They can know their customer's food choice and patterns to prepare themselves, well in advance, which can save time and resources. Our model also obtains the SS probabilities that define the survival possibility of a venue over a longer time in future. To the best of our knowledge, our work is the first in the domain of location prediction for users on venue basis of LBSNs.

Our model can be stated by following four parameters:

- *R*: set of LBSN restaurants or venues.
- *A*: matrix of transition probability. {*a<sub>ij</sub>*} represents the probability of going from venue (*i*) to venue (*j*).
- **B**: matrix of observation-sequences. {*b<sub>jk</sub>*} is the observation that a particular user visits a particular place on a given day of the week (this is the unknown parameter to be obtained).
- *π*: initial state of the system. We assume constant initial values to the venue-relationships. We obtain the respective probabilities using the mHMM for our system in the following manner.
  - (i) *N* is the Restaurants' (states) count. We designate the set of Restaurants

$$R = \{R_1, R_2, \dots, R_n\}$$
(14)

where  $R_i$ , i = 1, 2,..., N, is a distinct Restaurant.

(ii) *M* is the number of Days of Week (observation symbols) for every *Restaurant*. We denote the set of symbols

$$V = \{V_1, V_2, \dots, V_M\}$$
 (15)

where  $V_i$ ,  $i = \{S, M, T, W, T, F, S\}$ , is an observation symbol (Day of Week).



Figure 4. Proposed mHMM for location-prediction.

(iii) The transition probability matrix of restaurants

$$A = \{a_{ij}\}\tag{16}$$

where  $a_{ij} = P(q_{t+1} = R_j | q_t = R_i), 1 \le i, j \le N; t = 1, 2, \dots$ ; for all *i*, *j* and  $\sum_{i,j=1}^{N} a_{ij} = 1$  and  $q_t$  indicates the restaurant (state) at time instant *t*.

(iv) The probability matrix of observation symbol

$$B = \{b_{ikl}\} \tag{17}$$

where  $b_{jk} = P(V_k | R_j), 1 \le j, k \le N, M \text{ and } \sum_{k=1}^{M} b_{jk} = 1, 1 \le j \le N.$ 

(v) The initial state probability vector

$$\boldsymbol{\pi} = \{\boldsymbol{\pi}_i\} \tag{18}$$

where  $\pi i = P(q_1 = R_i), 1 \le i \le N$  and  $\sum_{i=1}^N \pi_i = 1$ . (vi) The observation sequence

$$O = O_1, O_2, \dots, O_L$$
 (19)

where each observation  $O_t$  is one of the days of week from V and L is total count.

# Algorithm *mHMM*:

Input: Foursquare dataset.

- 1. Calculate *initial probabilities* of all venues using their membership values.
- 2. Assign the constant values obtained for transition probabilities to all the venues.
- 3. Calculate *emission probabilities* as the actual transition count from all the venues (i.e., probability of each venue getting a particular user on a particular day).
- 4. Input these probability values to the *mHMM* for obtaining the final probabilities of the hidden states (Venues).
- 5. For all the user-day/venue-day pairs, predict the hidden state sequence based on the actual state sequence.

Output: Particular venue for input user-day pairs.

LBSN user generally follows a trend in the places he visits, as given in detail by (Noulas, Scellato, Mascolo & Pontil, 2011). On weekdays, he will most probably visit the restaurants near his work place as compared to the places visited on weekends. We consider the sequence of places visited by a particular user on a particular day of a week. To map the user locations detection in terms of mHMM, we consider the 7 days of a week as the observation symbols in our model. We quantize the observed values into M days, forming the observation symbols  $V_1$ ,  $V_2$ , ...,  $V_M$ , where  $V_i$ , i = {S, M, T, W, T, F, S}, making M = 7. Social users on Foursquare give their check-in information at a particular venue. The sequence of the states is hidden from the observer as he is only able to see the final outcome (place visited). The set of all possible types of restaurants visited, forms the set of hidden states in the mHMM.

The next step after deciding the symbol and state representations, is to determine the probability matrices *A*, *B*, and  $\pi$ . We use *Viterbi* algorithm and *Multinomial-HMM* to determine these three model parameters in training phase of our proposed work.

As shown in figure 4,  $R_1$ ,  $R_2$ ,...,  $R_n$  denote the various restaurants (hidden states). The transition probabilities are given by  $a_{ij}$ , where (i, j) = 1, 2, ..., N. The transition  $a_{11}$  denotes the probability of a user visiting the same venue  $(R_1)$ . Similarly,  $a_{12}$  denotes the *transition probability* of a user in moving from restaurant  $R_1$  to  $R_2$ .  $V = \{S, M, T, W, T, F, S\}$  represents the observation symbols from each hidden state. The emission probabilities are given by  $b_{jk}$ , where  $1 \le j$ ,  $k \le N$ , M. The first emission  $b_{R1S}$  represents the emission probability of restaurant  $R_1$  on Sunday and  $b_{R2W}$  represents the emission probability of restaurant  $R_2$  on Wednesday. We consider the special case of fully-connected mHMM, where-in, the reachability of every state is at a single hop from every other state in the model.

In a similar way, we reverse the inputs to the model for obtaining the prediction information for the restaurant owners about the user-visits. We formed the Venue-day pairs and these input parameters are given to the mHMM, as in the previous case to obtain the respective transition and emission probabilities. This time, we obtain the output as the predicted set of users visiting a particular venue on a particular day of a week. This can help the restaurant-owners to prepare themselves for the upcoming guests and customers, based on their number and the type of food-choices they make.

# 4 EXPERIMENTAL EVALUATION AND RESULTS

IN the following section, we give the detailed experimental procedure and result analysis for our proposed work.

#### 4.1 Dataset description

Foursquare check-ins data for 4 months ranging from 24 October 2011 to 20 February 2012 is used for the experimentation purpose (Yang, Zhang, Zheng & Yu, 2015). Noise and invalid data are filtered during the preprocessing. Personal check-in information is not available publicly and can only be accessed from one's own social circle. Only active users with at least one check-in per week are considered and all the check-ins from the "sudden-move" users are eliminated. The category information of some Foursquare venues is unavailable as these cannot be resolved by Foursquare venue API.

In the dataset, we represent a check-in by a quadruple *user-time-location-activity*, where users are uniquely identified by the IDs. User check-ins serve as an indicator of user activities in LBSNs. An activity is represented by venues corresponding to the check-in with the exact geographical coordinates and time. The spatial and temporal dimensions of check-in data are discretized according to the aforementioned LBSN scenario. After preprocessing, the New York City dataset includes 1083 users and 227428 check-ins performed over 251 venues. Similarly, 2293 users registered 573703 check-ins over 247 venues in Tokyo City dataset.

We give the graphical representation of the user check-ins count over the given time period for the two cities in figure 5. It shows the total number of visits a particular user makes during the given duration. For example in New York, *user-293* has the highest number of check-ins (2697) and *user-18* the lowest check-ins (100), with an average of 210 check-ins. Similarly in Tokyo, *user-822* has the highest number of check-ins (2991) and *user-43* the lowest check-ins (100), with an average of 297 check-ins over the given time period.



Figure 5. User check-ins count for New York and Tokyo cities.

# 4.2 Experimental setup (Observation symbol generation)

For each social-user, we train and maintain mHMM and find the respective observation symbols, after pre-processing. All the user-ids from the New York (1083) and Tokyo (2293) cities' datasets were used for our experimentation. 7 individual runs were made for each day of the week for all the 3376 user-ids in both datasets. We separately calculate the transition and emission probabilities for the social users to obtain the accuracy in location prediction. In the following steps, we show sample results obtained using our proposed model for *user-1214* from Tokyo City dataset with *127* check-in entries in *33* different venues and show the sample mHMM output probabilities in 5 venues for the same user in table 1.

Table 1. Sample mHMM probabilities in 5 venues for user-1214

Venue	Entries count	SP	TP	EP
Food & Drink Shop	0,1,0,0,0,0,0	0.0078	0.030303	0.0, 1.0, 0.0, 0.0, 0.0, 0.0, 0.0
Fast Food Restaurant	0,1,0,0,1,0,0	0.0159	0.030303	0.0, 0.5, 0.0, 0.0, 0.5, 0.0, 0.0
Japanese Restaurant	3,2,4,1,1,8,0	0.1508	0.030303	0.158, 0.105, 0.21, 0.053, 0.053, 0.42, 0.0
Shrine	0,0,0,0,0,1,0	0.0078	0.030303	0.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0
Airport	1,0,2,0,3,0,0	0.0476	0.030303	0.166, 0.0, 0.33, 0.0, 0.5, 0.0, 0.0

- Combinations: It is the list of the user-day pairs for all user-ids in the datasets. {['1214', 'Wed'], ['1214', 'Sun'], ['1214', 'Thu'], ['1214', 'Mon'], ['1214', 'Fri'], ['1214', 'Tue'], ['1214', 'Sat']}
- Entries: It contains the count of visits by a user to a particular venue on each day of the week. As an example, the user visits the Japanese Restaurant 8 times on Tuesdays and Airport thrice on Fridays.

Final Probabilities using mHMM

3. *Start Probability (SP):* It is calculated by the individual membership value for each restaurant given all entries of the user. It is given by following Eq. (20).

$$SP = \frac{Individual \ venue \ count}{Total \ venue \ count}$$
(20)

4. Transition Probability (TP): This is the probability of a user switching between venues, i.e., probability of user going to a restaurant after visiting a particular restaurant or venue (Eq. (21)). The mHMM is built for each location with transitions to every other location. TP is set to zero, if the user did not travel between two venues. If the model is trained on the states of link l and its neighbor links in time interval t, the state of link l at time t + l is independent from all other current link states, all past link states, and all past observations.

$$TP = \frac{Trans. from venue_i to venue_j}{Total trans. from venue_i}$$
(21)

5. *Emission Probability (EP):* This is the probability of each venue getting a particular user on each day of the week. It is calculated by the following Eq. (22).

$$EP = \frac{Entry\_value}{Total\_entry\_sum}$$
(22)

# 4.3 Sample output results

The results obtained are in the form of venuenames associated with a particular user for a particular day. We provide the user-id of the social-user, whose location we want to predict along with the day, to get the predicted place of his visit on that given day. We give some sample outputs as follows, where *Bob* is the enquirer (input) and *Alice* is the responder (output).

Bob says: Wed Alice hears: *Ramen / Noodle House*. Bob says: Sun Alice hears: *Japanese Restaurant*. Bob says: Fri Alice hears: *Train Station*.

#### 4.4 Result analysis and discussion

We conducted the experimentation on real world datasets for New York and Tokyo cities. We show the final accuracy comparison of results obtained using mHMM for different fractions of training dataset in figure 6. Further, in table 2, we give the minimum, maximum and the average of accuracy results obtained for the various partitions of the datasets. The accuracy varies between 29% to 41% in New York City, with an average of 35% location prediction accuracy. For Tokyo dataset, we obtain a much better accuracy range between 45% to 61%, with the average being 55% accurate location prediction. These results are much better as compared to the other contemporary works in the field of location prediction for LBSNs.

Table 2. Overall Accuracy of venue-prediction.

City	Min.	Max.	Avg.	
New York	0.29	0.41	0.35	
Tokyo	0.45	0.61	0.55	

Table 3. Overall Accuracy of user-prediction.

City	Min.	Max.	Avg.	
New York	0.194	0.31	0.257	
Tokyo	0.193	0.29	0.258	

In figure 7, we show the output results obtained for predicting users visiting a particular restaurant or venue on a given day using mHMM for varying training sets. Table 3 gives the minimum, maximum and the average of accuracy results. On analyzing the results, we understand that user-prediction is a difficult task as compared to venue-prediction. It is because of more number of users than the number of venues due to which the probability of accuracy prediction suffers. Nevertheless, this information is important for the restaurant owners to plan the foodpreference patterns for particular customers visiting their places on particular days in advance. This gives a completely different view-point for using our model that can be beneficial in both ways. It can predict the location of a user and by interchanging the parameters, it can be beneficial for restaurant-owners to know the details of their customers visiting on any given day.

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![](_page_10_Figure_1.jpeg)

Figure 6. Accuracy of venue-prediction using mHMM.

![](_page_10_Figure_3.jpeg)

Figure 7. Accuracy of user-prediction using mHMM.

Figure 8 shows the SS probabilities obtained for all venues present in New York and Tokyo City Foursquare datasets. We list SS probabilities of all venues that predict their chance of survival in the future. Out of a total of 251 venues in New York, it can be observed that the best SS probability obtained is for the Bar (0.068251) and the least for Photography Lab (0.0000042). We list the best five venues in terms of their SS probabilities in table 4. In similar terms, we obtain the SS probabilities for all 247 venues in Tokyo dataset and give the best five venues in terms of SS probabilities in Table 5. Here, we observe that the venue Train-Station has the best SS probability (0.34018) among all the venues which makes it the best venue to survive over a long period of time as compared to all other venues in the city. The venue Afghan Restaurant (0.0000017) has the least SS probability in Tokyo. This analysis gives the SS probability of the venues present in the two cities which can help in establishing their surviving capacity and popularity over a long period of time. We can observe that Train-Station is the single most-popular venue in Tokyo and the popularity distribution in New York is quite evenly distributed among some famous venues.

![](_page_10_Figure_6.jpeg)

![](_page_10_Figure_7.jpeg)

![](_page_10_Figure_8.jpeg)

Figure 8. Steady-State probability comparison of venues for New York and Tokyo cities.

We obtained accuracy of 41% to 61% for the venue-prediction, which is comparatively higher than other existing related works, given in section 2. In our work, we also predicted the user presence at a particular venue for the first time, where accuracy is 30%.

Table 4. Top 5 SS probability venues for New York.

Venue Id	Venue	SSP
22	Bar	0.068251
122	Home (private)	0.065552
166	Office	0.054219
224	Subway	0.039614
115	Gym / Fitness Centre	0.039168

Table 5. Top 5 SS probability venues for Tokyo.

Venue Id	Venue	SSP
236	Train Station	0.34018
221	Subway	0.07086
186	Ramen / Noodle House	0.02979
63	Convenience Store	0.028932
128	Japanese Restaurant	0.026902

# 5 CONCLUSION AND FUTURE DIRECTIONS

LBSNs are used to share locations and events in a participatory fashion. Their popularity is increasing everyday due to the advent of smart-phones. In this paper, mHMM is implemented as a prediction model. Foursquare user check-in datasets for New York and Tokyo cities are used to train the mHMM for qualitative and quantitative evaluation and trendanalysis. The experimental results show that the proposed model performs accurate predictions of user locations. The obtained accuracy of locationprediction of particular venues, in place of categories of LBSNs, using mHMM is very high and outperform the results of various baseline methods. This work will be very useful for security purposes in which the exact location of a user, after frequent transitions between different venues, can be traced on a particular day or time. In addition, the restaurant owners can keep track of their customers' arrivals on a given day. They get to know their food choice well in advance, that saves time and resources. Also, Steady-State probabilities are obtained, that define the popularity and chance of survival of venues in the future based on the user check-ins. To the best of our knowledge, our work is the first in the domain of location prediction for users on venue basis with such high accuracy results.

In future, we plan to extend the work to capture user behavior in other LBSNs like Facebook, Twitter and Gowalla. Also, we plan to use multi-stage HMM for prediction and compare the results to obtain the best location-prediction. Combination of unstructured information like user-tips along with the temporal activity patterns can result in better predictive performance.

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#### 7 DISCLOSURE STATEMENT

NO potential conflict of interest was reported by the authors.

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# **10 NOTES ON CONTRIBUTORS**

![](_page_13_Picture_2.jpeg)

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![](_page_13_Picture_5.jpeg)

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![](_page_13_Picture_8.jpeg)

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