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# Investigation of the Structure Design and Heat Transfer Characteristics of Heating Cable

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## ABSTRACT

Indoor heating with an electrical heating cable, which has no harmful emissions to the environment, is an attractive way for radiant floor heating. To improve the heat transfer efficiency, a novel structure of the heating cable was designed by proposing the concept of the aluminum finned sheath. The transient heat transfer model from the embedded heating cables to the floor is established to validate the feasibility of this novel cable. The effects of the fin number and shape on the cable's temperature and heat flux distribution were analyzed. The results show that, with the specific volume of the sheath, increasing the number of fins can enhance the thermal diffusion capacity of the heating cable and reduce its temperature. Rectangular fins exhibit higher performance for heat dissipation than triangular fins due to their larger surface area. The simulation result shows that the floor temperature above the cable rises from 5°C to 22.5°C after a 2-h heating process, which was validated with experimental results. The results and suggestions can provide reference to guide the design of the heating cable.

## KEYWORDS

Heating cable; aluminum sheath; fin structure; thermal simulation

## Nomenclature

$A$	Area (mm <sup>2</sup> )
$C$	Specific heat (J kg <sup>-1</sup> K <sup>-1</sup> )
$IH-EHC$	Indoor heating with electrical heating cable
$NiAl$	Nickel-aluminium alloy
$N$	Fin number
$S$	Surface area (mm <sup>2</sup> )
$V$	Volume (mm <sup>3</sup> )
$XPPE$	Cross-linked polyethylene



<i>XPS</i>	Extruded polystyrene board
$\lambda$	Thermal conductivity ( $\text{W m}^{-1}\text{K}^{-1}$ )
$\rho$	Density ( $\text{kg m}^{-3}$ )
$t$	Time (s)
$\theta$	Angle ( $^{\circ}$ )

### Subscripts

$s$	Sheath of heating cable
$in$	Inner radius of the fin
$out$	Outer radius of the fin

## 1 Introduction

With the development of low carbon, the traditional coal-based heating technology in China is facing huge challenges. To mitigate the emissions from coal burning, electric heating technology has developed rapidly in recent years [1]. As one of the electric heating technologies, the heating cable has no gas emissions, and is widely applied in places and objects requiring heating and heat preservation, especially for the domains in snow/ice melting of road and roof surface, indoor heating, anti-freezing and insulation of chemical pipelines [2–6]. With the improvement in living standards, there is also a demand for heating in southern cities in winter. However, winter in the South may only have a few random freezing days, and the traditional water heating system, once turned on, is usually left on for a long time, which makes it wasteful when used in the South [7]. Heating cables are considered to be a suitable method to meet short-term heating demands. Up to date, the large-scale commercial application of heating cable is greatly limited, due to the complicated heat transfer (multiphase heat transfer integrating heat conduction, convection and radiation) [8].

Extensive research has been carried out on the heat transfer performance of heating cables in various environments. Yang et al. [9] found that snow and ice melting using heating cables has less damage to the environment and higher thermal efficiency compared to traditional methods. Su et al. [10] found that when the ambient temperature was as low as  $-7.5^{\circ}\text{C}\sim-2.2^{\circ}\text{C}$ , the heating cable technology could raise the temperature of the airport pavement by  $13^{\circ}\text{C}$  within 2.5 h, effectively improving the safety of the airport runway in freezing weather. Danilovic et al. [11] showed that heating cables could be used in oil wells to solve the problem of paraffin deposition. Tan et al. [12] investigated the temperature rise and ice melting patterns of heating cables fabricated by different metal wires, which could provide references for the design of actual bridges and roads. In the construction of the 2022 Winter Olympic Village, Liu et al. [13] compared different heating methods, and finally decided to use a heating cable. Some numerical methods, such as the finite element method, are used to simulate the heat-up process of heating cables and the results of these studies guide the practical application of heating cables in the room [14–16].

The above researches illustrate the feasibility of the heating cable technique, but as seen from the structure of the heating cable, its heat transfer characteristics are limited. The heating cable is composed of heating alloy, insulation layer, and sheath [17]. At present, most of commercial heating cable uses PVC as sheath material, which is at a low price, but the performance is less than satisfactory, especially since the heat conductivity is poor. Therefore, we propose to use a metal sheath to improve its heat transfer performance, and meanwhile enhance the mechanical strength and corrosion resistance. The material of aluminum is a good choice as it is light, and has a good shielding ability from electromagnetic radiation [18], which can improve the safety of the user, especially when the heating

cables are applied in indoor heating. To further improve the heat dissipation efficiency of the heating cable, the structure of fins on the surface of the aluminum sheath is chosen to increase the heat dissipation area.

The methods to enhance heat transfer mainly include increasing heat transfer area, heat transfer temperature difference and heat transfer coefficient [19,20]. The fin is an effective way to strengthen heat transfer by increasing the heat transfer area, which is applied in heat exchangers of various industries, such as electronic components [21] and batteries [22–25]. Extensive research has been conducted to investigate the effect of different fin parameters on the heat transfer performance. The shape of the fins is an important feature that affects the heat transfer efficiency of finned heat exchangers. He et al. [26] established a heat dissipation model of the thermoelectric cooler hot side with a plate-fin sink to explore the performances of the plate-fin sink with different shapes, convection conditions and arrangements. A multi-objective optimization of the fins was proposed based on artificial neural networks (ANN) and non-dominated sorting genetic algorithm (NSGA-II) in order to optimize the fin geometry. Liu et al. [27] studied the effect of fin spacing on the heat exchange performance of finned heat exchangers, and the results showed that either too large or too small fin spacing was not conducive to the best performance of heat exchange. Yang et al. [28] studied the effect of different fin parameters on the heat transfer performance of finned tubes, and validated their effectiveness through numerical simulation and physical experiments. The results showed that the outlet temperature of the heat exchanger has increased from the previous 28.6°C to 37.2°C, and the efficiency of heat transfer has been significantly improved.

In this paper, a novel all-aluminum clad heating cable is proposed to enhance the heat dissipation efficiency and other related properties of the heating cable by improving the material and structure of the outer sheath.

## 2 Structure Design of Heating Cable

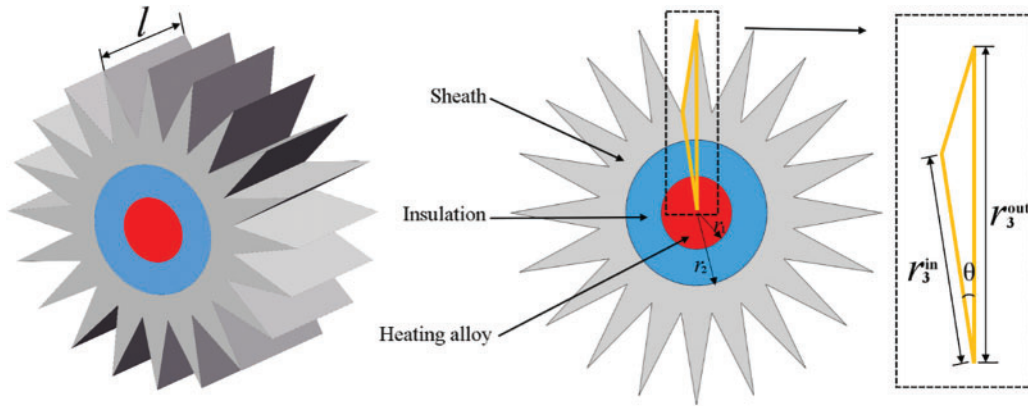
The heating cable is mainly composed of three layers, including the inner heating alloy wire, the middle insulation layer and the outer sheath. When the power turns on, heat is generated by the heating alloy wire, and then transfers to the floor through multiple layers. The newly designed heating cable is shown in Fig. 1. It includes the heating alloy, insulation and sheath with triangular fins. The dimensions of the heating cable are defined as follows. The length of the heating cable along the  $z$ -direction is defined as  $l$ . The radius of the heating alloy and insulation are  $r_1$  and  $r_2$ , respectively. The inner radius,  $r_3^{\text{in}}$  and outer radius  $r_3^{\text{out}}$ , along with the intersection angle  $\theta$ , are defined as the fin shape parameters for the triangular fin. There are  $N$  fins in total along the outer circumference of the sheath. Based on the above parameters, the volume and surface area of the sheath can be calculated by Eqs. (1) and (2), respectively,

$$V_s = l \cdot (Nr_3^{\text{in}}r_3^{\text{out}} \sin \theta - \pi r_2^2) \quad (1)$$

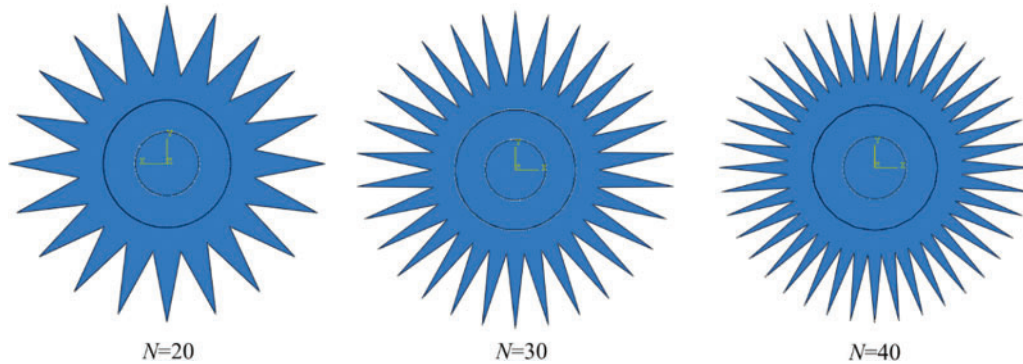
$$A_s = l \cdot \left( 2N\sqrt{(r_3^{\text{in}})^2 + (r_3^{\text{out}})^2} - 2r_3^{\text{in}}r_3^{\text{out}} \cos \theta \right) \quad (2)$$

The volume of the sheath ( $V_s$ ) determines the consumption of aluminum, and surface area  $A_s$  is the total heat dissipation area.

The influence of fin parameters on heat dissipation performance was investigated under the same volume of sheath material, in order not to increase the material cost of heating cable. As shown in Fig. 2, although the number of fins vary, the volume of the sheath is constant.



**Figure 1:** The structure of the heating cable



**Figure 2:** Geometry of heating cables with different fin numbers

### 3 Thermal Simulation of the Heating Cable

#### 3.1 Mathematical Model

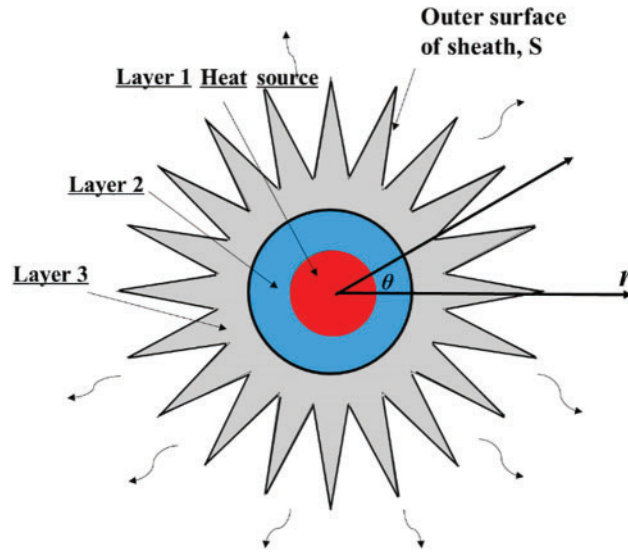
A pure heating cable that is not embedded under the floor for use was taken into consideration. The heating alloy, insulation layer and sheath materials are nickel-aluminum alloy, cross-linked polyethylene (XPLE) and 6061 aluminum alloy.

The modeling of the heated cable is performed under the following assumptions. (1) The electric heating cable is uniform along the length direction ( $z$ -axis). (2) The contact thermal resistance between different materials is ignored. The heat transfer of the heated cable was modeled as a two-dimensional transient heat conduction problem, while the heating alloy in the middle is regarded as the heat source. The energy equation in the model where the coordinate system is  $r$ - $\theta$ - $z$  in Fig. 3 can be written by using Fourier's law as follows [29]:

$$\rho_i C_i \frac{\partial T_i}{\partial t} = \frac{1}{r} \frac{\partial}{\partial r} \left( \lambda_i r \frac{\partial T_i}{\partial r} \right) + \frac{1}{r} \frac{\partial}{\partial \theta} \left( \lambda_i \frac{1}{r} \frac{\partial T_i}{\partial \theta} \right) + \Phi, 0 \leq r \leq r_3^{out}, i = 1, 2, 3 \quad (3)$$

The governing equation is subject to the following initial conditions:

$$T_i(r, \theta) |_{t=0} = T_0, i = 1, 2, 3 \quad (4)$$



**Figure 3:** The heat transfer of the heating cable

The boundary conditions are expressed by Eq. (5). The sheath has convection heat transfer with the air. The outer surface of the sheath is defined as  $S$ .

$$-\lambda_3 \frac{\partial T_3(r, \theta, t)}{\partial r} = h(T_3 - T_\infty), S \quad (5)$$

The continuous conditions between the electric heated alloy and the insulation, and between the insulation and the aluminum fin are expressed by Eqs. (6)–(9).

$$T_1 = T_2, r = r_1 \quad (6)$$

$$T_2 = T_3, r = r_2 \quad (7)$$

$$-\lambda_1 \frac{\partial T_1(r, \theta, t)}{\partial r} = -\lambda_2 \frac{\partial T_2(r, t)}{\partial r}, r = r_1 \quad (8)$$

$$-\lambda_2 \frac{\partial T_2(r, \theta, t)}{\partial r} = -\lambda_3 \frac{\partial T_3(r, \theta, t)}{\partial r}, r = r_2 \quad (9)$$

$T_i$  is the temperature of the heating cable, and  $i$  ( $i = 1, 2, 3$ ) represents the layers of heating alloy, insulation and sheath, respectively.  $\lambda_i$ ,  $\rho_i$  and  $C_i$  are the thermal conductivity, density and specific heat capacity of each material, as listed in Table 1.  $\dot{\phi}$  is the surface heat source generated by heating alloy.  $h$  is the convective heat transfer coefficient between the sheath and air.

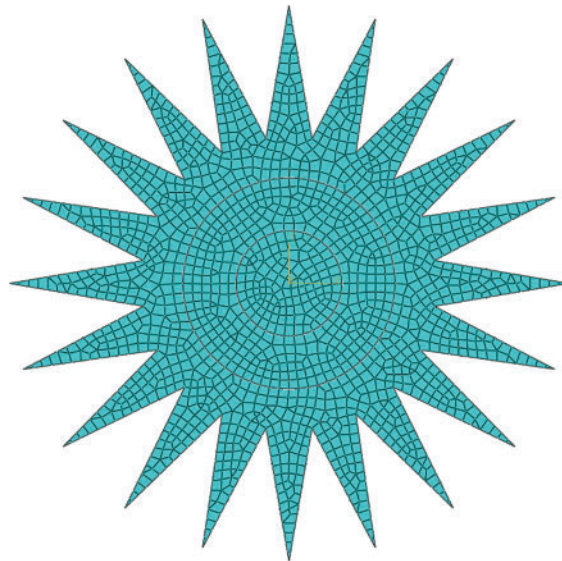
### 3.2 Thermal Simulation

The thermal simulation based on the finite element (FE) model was used to investigate the heat transfer performance of the heating cable with Aluminum finned structure through ABAQUS. According to the mathematical model, a detailed finite element model was built, as shown in Fig. 4. The 2-D geometry was meshed using the quadrilateral element. The meshes with different sizes are

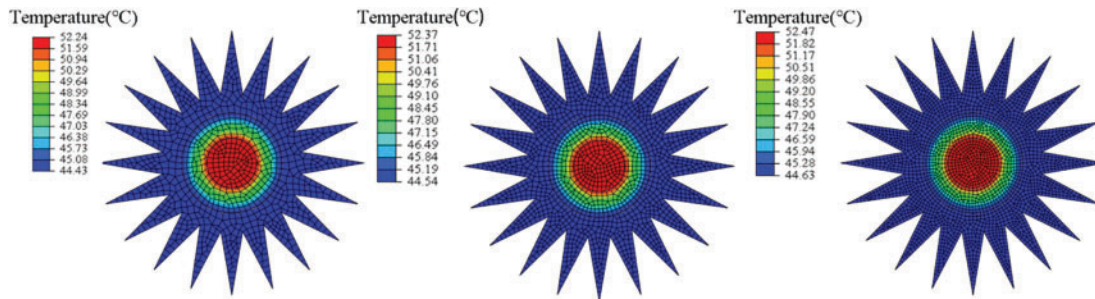
applied to perform the grid independence analysis. As shown in Fig. 5, the maximum temperature is 52.24°C, 52.37°C and 52.47°C corresponding to the grid numbers 834,1631 and 3486, which indicates the current grid density has little effect on temperature results. The grid number of 1631 is adopted for computation. For the analysis of time step independence, a series of different step sizes (5 to 40 s) are taken for calculation. The temperature difference is 0.59°C under maximum and minimum time steps. Therefore, the time step of the 20 s is selected for balancing the calculation accuracy and efficiency.

**Table 1:** The thermal properties of the materials in heating cable

Layer	Part	Material	Conductivity (W/(m·K))	Specific heat (J/(kg·K))	Density (kg/m <sup>3</sup> )
1	Heat alloy wire	<i>NiAl</i>	12.167	500	7900
2	Insulation	<i>XPPE</i>	0.4	2303	920
3	Aluminum fin	6601 aluminum alloy	155	880	2750



**Figure 4:** The FE meshing of the simulation for the heating cable



**Figure 5:** Temperature results with different mesh density



In our previous experiment, a heating cable with a length of 107 m was used, and the total power was 3 kW. Therefore, the power per volume is calculated by using the total power divided by the volume of the heating alloy, which is  $7.65 \times 10^6 \text{ W/m}^3$ . The convective heat transfer coefficient is set as  $6 \text{ W/(m}^2\text{K)}$  and the initial and ambient temperatures are  $5^\circ\text{C}$ .

### 3.3 Simulation Results and Analysis

The influence of the number and shape of fins on the temperature was studied. In order not to increase the material cost, the volume of the aluminum sheath remains unchanged. The volume was set as  $178 \text{ mm}^3$ . The length of the heating cable along the axial direction is set to be  $l = 5 \text{ mm}$ . So, the area of the aluminum sheath is determined as  $35.6 \text{ mm}^2$ , which is used in the two-dimensional heat transfer problem. Therefore, when the number or shape changes, the rest of the fin shape parameters will change accordingly. The simulation duration is 10 min.

#### 3.3.1 The Effect of the Fin Number on Temperature Response

The number of fins,  $N = 20, 30$  and  $40$  are taken, respectively, and the fin Angle  $\theta (=360^\circ/2N)$  and outer radius of sheath  $r_3^{\text{out}}$  changes according to Eq. (1). Table 2 lists the fin shape parameters and the corresponding volume and surface area of sheath under different fin numbers.

**Table 2:** Fin shape parameters and corresponding volume and surface area of the sheath

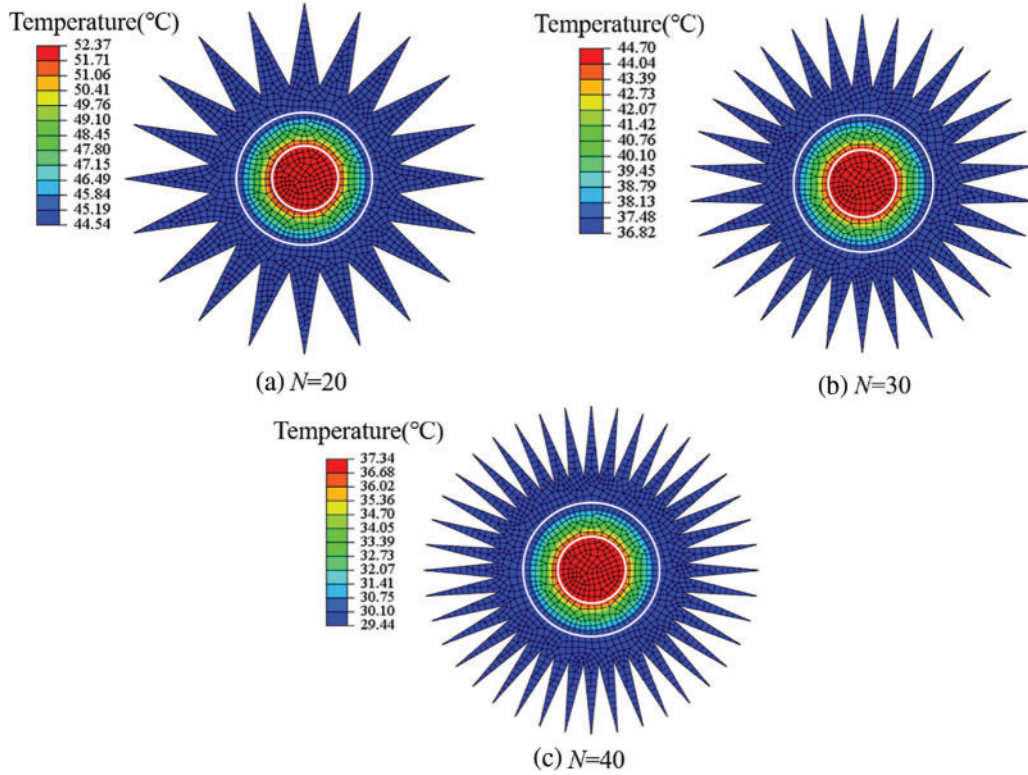
Fin shape	$r_3^{\text{in}}/\text{mm}$	$r_3^{\text{out}}/\text{mm}$	$N$	$V_s/\text{mm}^3$	$A_s/\text{mm}^2$
Triangular fin	3.0	5.355	20	178	488
	3.0	5.343	30	178	714
	3.0	5.338	40	178	944

The simulation results of different fin numbers are shown in Fig. 6. Temperature decreases as  $N$  increases. When  $N$  increases from 20 to 40, the average temperature of the heating cable declines from  $48.5^\circ\text{C}$  to  $33.4^\circ\text{C}$ . It indicates that more heat is diffused to the environment under larger  $N$ , since the total heat generation remains constant in our simulation. Therefore, a larger number of fins is beneficial to the heat dissipation of cable to the environment, and meanwhile reduces its own temperature increase, which is conducive to the anti-aging of insulation materials. The insulation of the heating cable will accelerate the aging rate under long-term high-temperature operation, which will affect the cable's operating life [30].

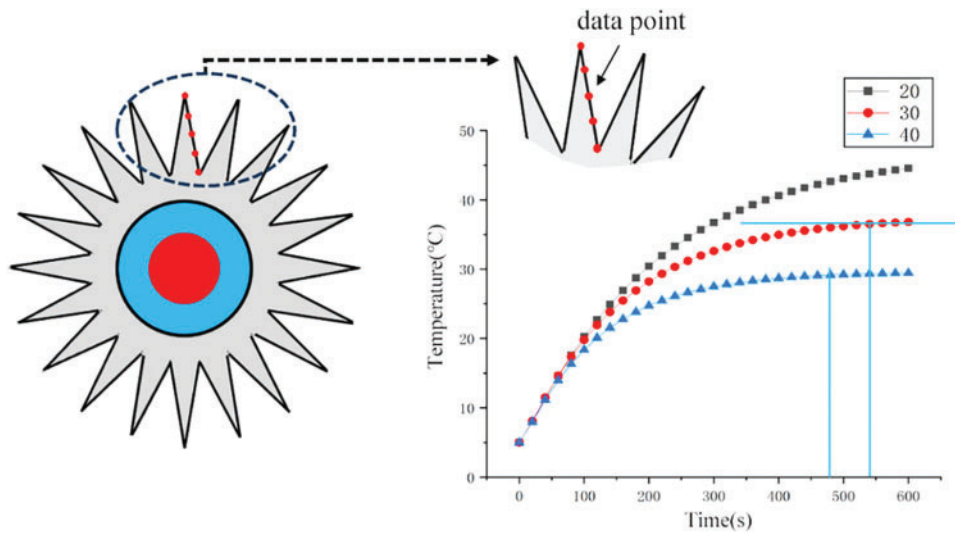
Due to the radial symmetry of the heating cable in geometry and boundary conditions, each fin has the same temperature distribution. To investigate the effect of  $N$  on transient fin temperature, five points were depicted from the root to the top of the fin, as shown in Fig. 7, which were used to calculate the average fin temperature. It is noted that although the length of the fins varies with its number to ensure the same volume, the five points are all chosen equidistant from the root to the top of the fin.

In Fig. 7, it can be observed that the fin temperature rises rapidly at first, and then tends to be stable. That is, the heating process changes from a non-steady state to a steady state. It is worth noting that, under different fin numbers, the time when the fin temperature reaches the steady state is different. For  $N = 20$ , the heating process did not reach the steady state when  $t = 600 \text{ s}$ . For  $N = 30$  and  $N = 40$ , the steady state is achieved at about  $t = 500 \text{ s}$  and  $t = 400 \text{ s}$ . The reason for this phenomenon is that the surface area of the fin changes with  $N$ . When  $N$  increases from 20 to 40, the surface area increases

from 488 to 944 mm<sup>2</sup>, which makes the fin to dissipate the heat more efficiently, to reach the thermal equilibrium faster.



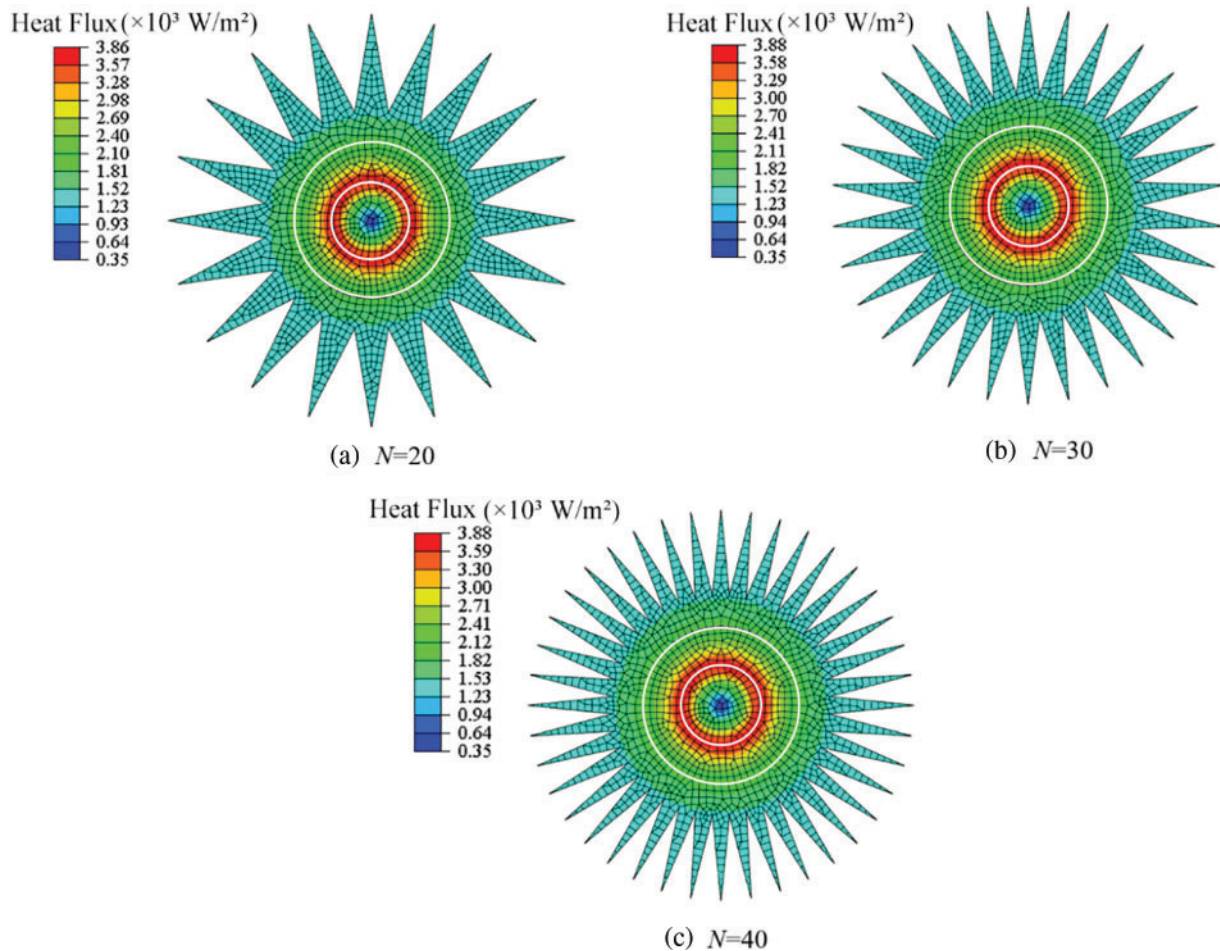
**Figure 6:** The effect of  $N$  on the temperature distribution of the heating cable



**Figure 7:** The effect of  $N$  on fin temperature



The heat flux of the heating cable under different fin numbers is shown in Fig. 8. It is the heat flux of the system at the isothermal surface. As to the distribution of heat flux, the inside and outside of the heating alloy show different rules. In the 2-D heat transfer model, the heating alloy is considered as a surface heat source, so the magnitude of heat flux inside the heating alloy increases with its area. However, outside the heating alloy, the magnitude of heat flux is inversely proportional to the area of heat flow, so it decreases from the insulation layer to the fin layer along the radial direction.



**Figure 8:** The effect of  $N$  on heat flux of heating cable

The maximum heat flux appears at the inner side of the insulation layer. When the thermal system is in a steady state, the maximum heat flux can be calculated by dividing the total heat generation of the heating alloy by the area of the inner surface of the insulation, that is  $q_{\max} = \dot{\Phi} \times \pi r_1^2 l / 2\pi r_1 l$ . It is observed in Fig. 8b,c that the maximum heat flux is equal, which reveals that both have reached the steady state for fin numbers  $N = 30$  and  $N = 40$ . For  $N = 20$ , the magnitude of heat flux is a bit smaller, which means the heat emitted outward is less than the total heat, so the system has not reached a steady state, and the temperature of the heating cable itself will increase. These findings from heat flux results further verify that a larger  $N$  helps the thermal system reach a steady state.

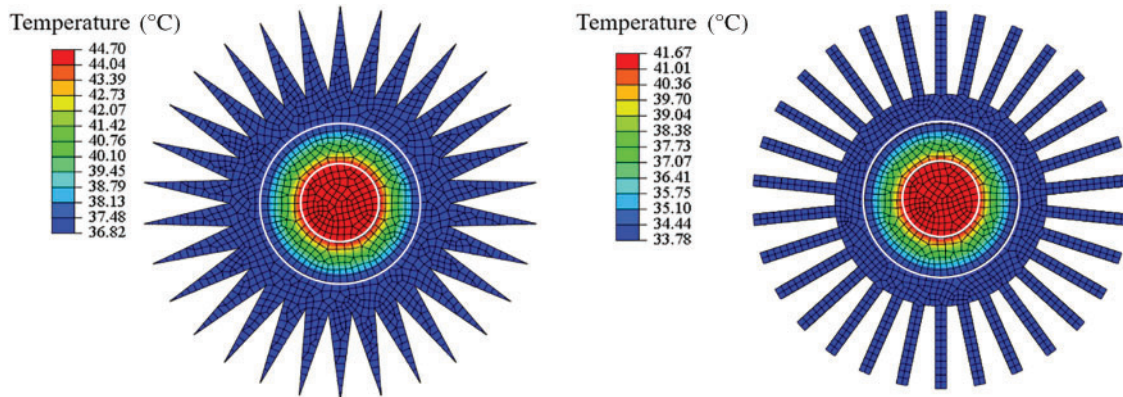
### 3.3.2 The Effect of Fin Shape on Temperature Response

The fins of different shapes, rectangular and triangular, were designed to investigate the effect of fin shapes on the heat transfer performance of heating cables. The volume of the sheath is maintained constant for both types of fins. Taking into account of the manufacturing issue, the spacing of rectangular fins is set as  $\pi/10$ . The fin shape parameters, the corresponding surface area and the volume of the sheath are listed in Table 3.

**Table 3:** Geometric parameters of rectangular and triangular fins

Fin shape	$r_3^{\text{in}}/\text{mm}$	$r_3^{\text{out}}/\text{mm}$	N	Fin spacing /mm	$A_s/\text{mm}^2$	$V_s/\text{mm}^3$
Triangle	3.0	5.343	30	0	714	178
Rectangle	3.0	5.337	30	$\pi/10$	795	178

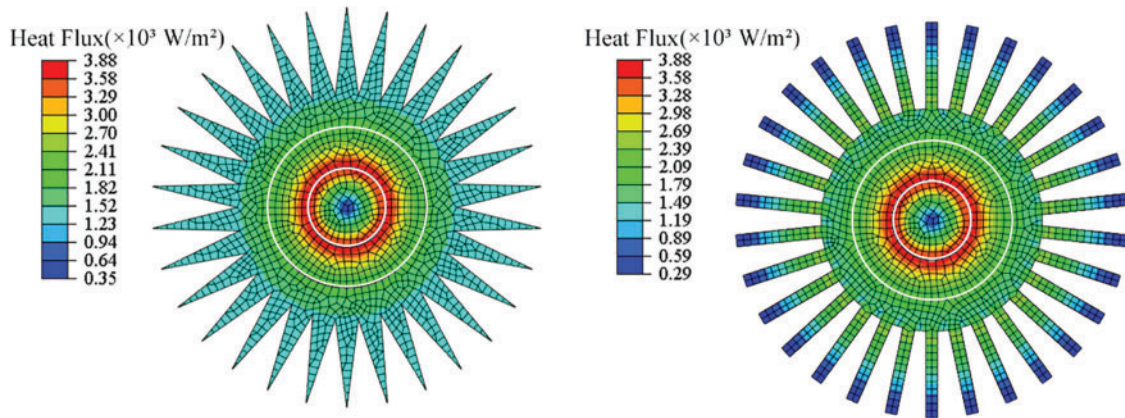
In Fig. 9, the average temperature of the rectangular fin is 37.7°C, lower than that of the triangular fin 40.8°C. It indicates that the rectangular fin has a better heat dissipation effect due to a larger surface area (shown in Table 3). The corresponding heat flux distribution is shown in Fig. 10. The magnitude and distribution of these two heat fluxes are close. For the rectangular fin, it is observed that the heat flux in the tip of the fin is smaller than the triangular fin, which is mainly attributed to the longer length of the rectangular fin.



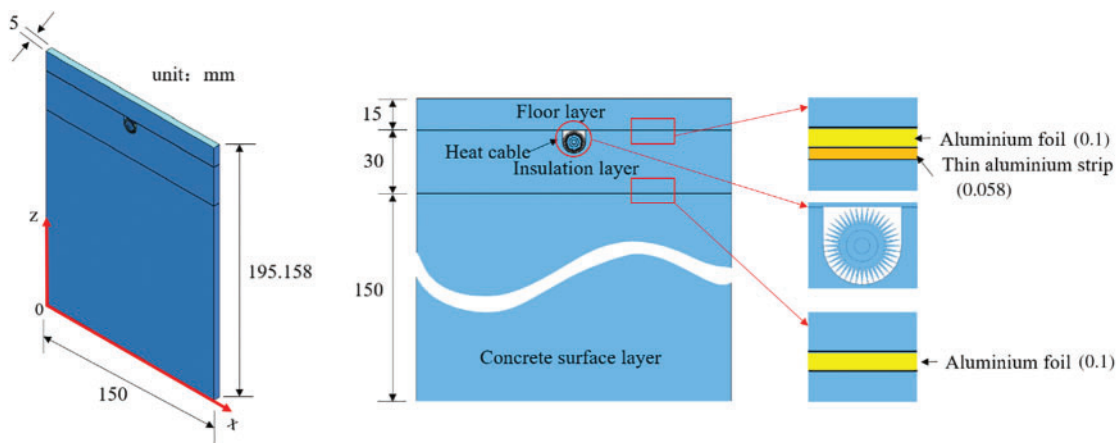
**Figure 9:** The effect of fin shape on the temperature of the heating cable

## 4 Thermal Simulation of the Cable-Heated Floor

To investigate the temperature of the cable-heated floor, the structure of indoor heating with electrical heating cable (IH-EHC) is established, as shown in Fig. 11. The heating cables are embedded in the prefabricated hole of the insulation layer. The floor layer, which is made of wood, is located on top of the heating cables. The concrete layer is located at the bottom. The upper and lower surfaces of the insulation layer are covered with a small thickness of aluminum foil and thin aluminum strips, which are used as a cable shielding material to resist electromagnetic waves, radio frequency interference and noise. It is noted that only triangular fins can be manufactured now due to the limitation of the equipment. Therefore, triangular fins are applied here to validate with the experimental results.



**Figure 10:** The effect of fin shape on heat flux of heating cable



**Figure 11:** The simplification of the structure of IH-EHC

The thermal modeling is performed under the following assumptions: (1) The bottom boundary is adiabatic because the concrete surface layer is under the thermal insulation layer. (2) The top surface has a convective and radiative boundary condition with the room air. (3) The contact thermal resistance between different layers is ignored. The convective heat transfer coefficient is set at  $6 \text{ W}/(\text{m}^2\text{K})$ , the radiation coefficient of the floor surface is 0.82, and the ambient temperature is  $5^\circ\text{C}$  [31]. The thermal properties of different materials in IH-EHC are shown in Table 4.

**Table 4:** Thermal properties of materials used in IH-EHC

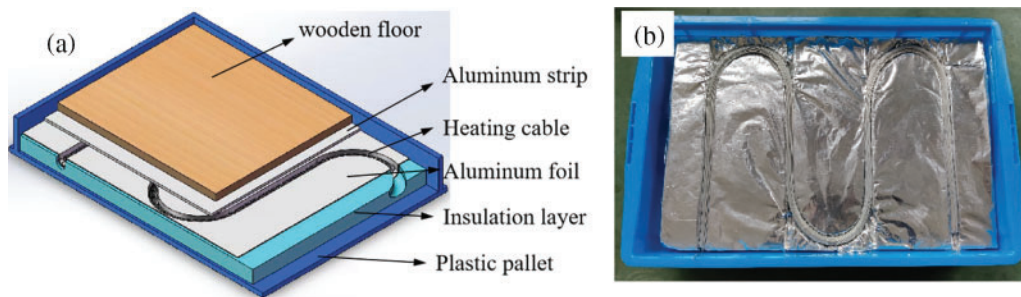
Structure	Material	Conductivity ( $\text{W}/(\text{m}\cdot\text{K})$ )	Specific heat ( $\text{J}/(\text{kg}\cdot\text{K})$ )	Density ( $\text{kg}/\text{m}^3$ )
Floor	Solid wood	0.1389	2512	500
Thin aluminium strip	Al	155	880	2750
Aluminum foil	Al	155	880	2750

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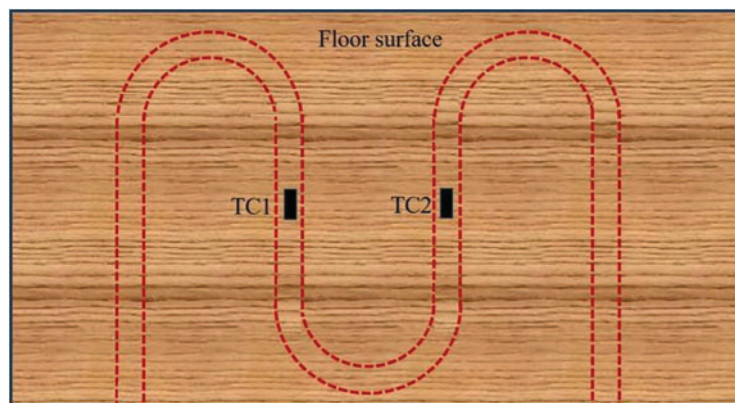
**Table 4 (continued)**

Structure	Material	Conductivity (W/(m·K))	Specific heat (J/(kg·K))	Density (kg/m <sup>3</sup> )
Insulation layer	XPS	0.03	1380	35
Floor slab level	Reinforced concrete	1.74	920	2500

To verify the numerical result, an experimental setup was established (as shown in Fig. 12), and the materials were laid in accordance with the simulation model. A floor layer, a thin aluminum strip, a heating cable, an aluminum foil, an insulation board and a plastic pallet are stacked from the top to bottom. Since the heat is almost controlled in the thermal insulation layer, it will not cause errors to use the plastic pallet to substitute the concrete layer. Two thermocouples are placed on the floor surface directly above the heating cable to measure the temperature rise, as shown in Fig. 13.



**Figure 12:** Experimental (a) design, and (b) set up for indoor heating with an electrical heating cable



**Figure 13:** Thermocouples arranged on the floor surface

The simulated temperature distribution of IH-EHC after 2 h is shown in Fig. 14. The temperature is symmetrically distributed along the center line in the width direction. The heating cable has a maximum temperature of 55°C, which is lower than the melting point of the materials of the heating cable, including the nickel-aluminum alloy, cross-linked polyethylene, and 6061 aluminum alloy, and



can ensure the safety of the cable. The bottom surface of the insulation layer has the minimum temperature, indicating the insulation layer has a good thermal insulation effect, and little heat is transferred down to the cement layer.

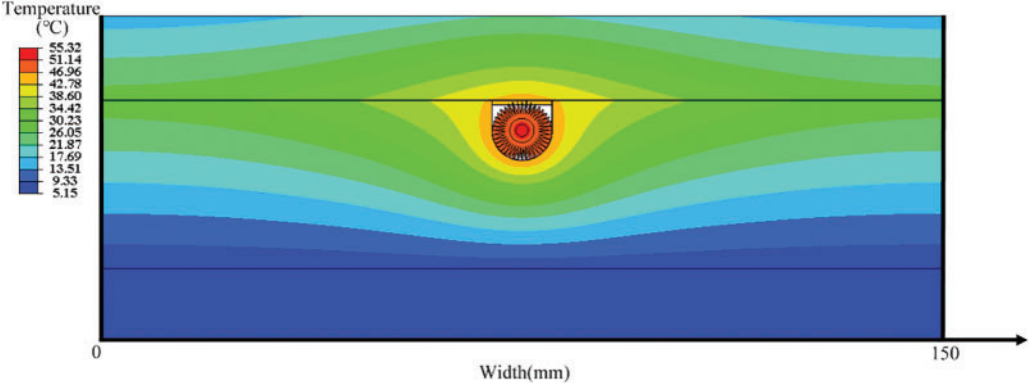


Figure 14: Floor temperature field with built-in heating cable

The heat generated by the cable is gradually transferred to the floor. After 2 h, the peak temperature on the floor surface is 22.5°C, appearing right above the heating cable. This numerical result is compared by experimentally measured temperature, as shown in Fig. 15. The temperature difference is lower than 2°C, which verifies the accuracy of the thermal model. As to the floor temperature distribution along the width direction, an uneven temperature field was observed in Fig. 16. This is a normal phenomenon since the volume of the heating cable is relatively small compared to the floor. Therefore, when the heating cable is used in indoor floor heating, the laying interval of the cables needs to be carefully considered.

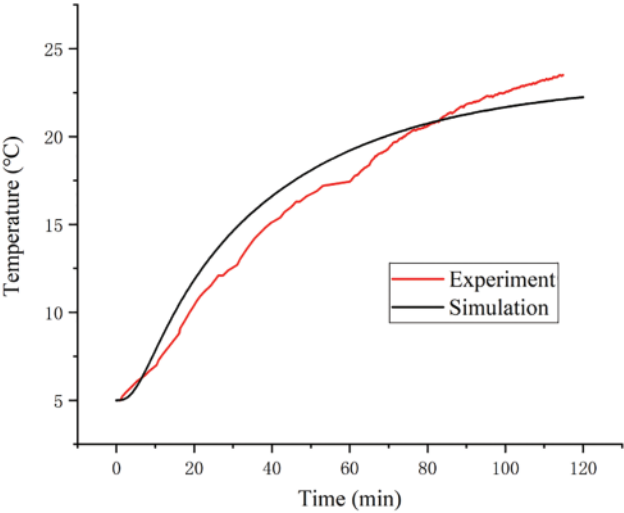
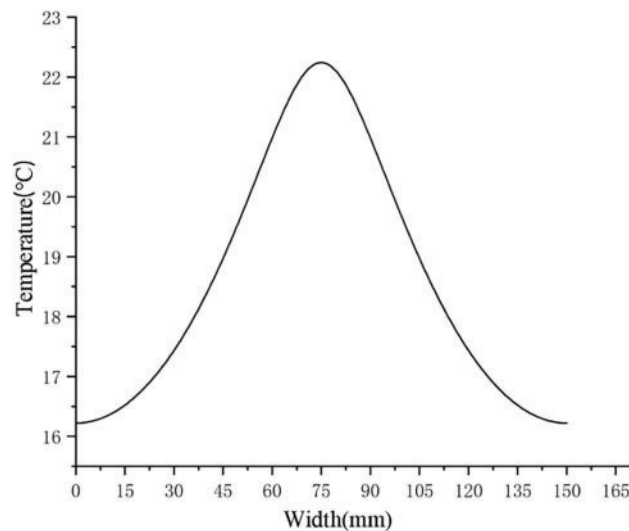


Figure 15: Experimentally measured and simulated temperature in the center of the floor surface





**Figure 16:** Temperature distribution across the floor surface

## 5 Conclusions

In this study, a novel structure of heating cable with finned aluminum sheath is proposed. The heat transfer characteristics of heating cables are investigated by constructing a 2D FEM. The main conclusions are as follows:

1. The number of fins on the sheath affects the heat transfer efficiency. The more fins, the faster the thermal system reaches thermal equilibrium.
2. The design of rectangular fins has larger surface areas than the triangular fins for the same volume of the sheath. Therefore, rectangular fins are more conducive to heat dissipation under natural convection conditions.
3. The triangular fins have a good heating effect on the floor, which is validated with experimental results. Under the initial temperature of 5°C, the maximum temperature on the floor surface rises to 22.5°C within only 2 h.

In this study, the indoor heating with one heating cable is investigated. In the future, a three-dimensional thermal model for the whole floor will be established. Due to the uniformity of floor temperature along the width direction, the pavement style and depth of the heating cables need to be carefully considered. The finned sheath can perform better in forced convection environments, numerical and experimental studies will also be done to further improve the heat transfer efficiency of this newly designed heating cable.

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Yanmin Zhang. Analysis and interpretation of results: Lihui Zhang; draft manuscript preparation: Lihui Zhang, Huichuang Yang. All authors reviewed the results and approved the final version of the manuscript.

**Availability of Data and Materials:** Data will be made available on request.

**Ethics Approval:** Not applicable.

**Conflicts of Interest:** The authors declare that they have no conflicts of interest to report regarding the present study.

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