



Optimized Tuning of LOADng Routing Protocol Parameters for IoT

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Abstract: Interconnected devices and intelligent applications have slashed human intervention in the Internet of Things (IoT), making it possible to accomplish tasks with less human interaction. However, it faces many problems, including lower capacity links, energy utilization, enhancement of resources and limited resources due to its openness, heterogeneity, limited resources and extensiveness. It is challenging to route packets in such a constrained environment. In an IoT network constrained by limited resources, minimal routing control overhead is required without packet loss. Such constrained environments can be improved through the optimal routing protocol. It is challenging to route packets in such a constrained environment. Thus, this work is motivated to present an efficient routing protocol for enhancing the lifetime of the IoT network. Lightweight On-demand Ad hoc Distance-vector Routing Protocol—Next Generation (LOADng) protocol is an extended version of the Ad Hoc On-Demand Distance Vector (AODV) protocol. Unlike AODV, LOADng is a lighter version that forbids the intermediate nodes on the route to send a route reply (RREP) for the route request (RREQ), which originated from the source. A resource-constrained IoT network demands minimal routing control overhead and faster packet delivery. So, in this paper, the parameters of the LOADng routing protocol are optimized using the black widow optimization (BWO) algorithm to reduce the control overhead and delay. Furthermore, the performance of the proposed model is analyzed with the default LOADng in terms of delay, delivery ratio and overhead. Obtained results show that the LOADng-BWO protocol outperforms the conventional LOADng protocol.

Keywords: Internet of things; optimization algorithm; routing protocol; LOADng

1 Introduction

In recent years, the IoT is being a widespread concept that has involved the concentration of the research community [1]. A vast and ubiquitous network of devices that swap over information without human intervention is referred to as the Internet of Things [2]. Smart homes and cities [3–5], smart markets [6], industrial automation [7], and physical condition systems [8] are using the networks. As the number of



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objects linked to the Internet increases, it is necessary to improve IoT network protocols. The data from these strategies should be available to relevant parties such as smartphones, Internet services and cloud resources.

Using sensors and actuators, communication among the devices is done in IoT. The sensor is used to collect, store and process data, the actuator is used to keep an alteration in a device environment, A remote server is used to store the processed data. Sometimes, IoT is limited to specific resources for storage and processing due to limitations in material size, energy consumption and computational efficiency. Includes data collection, sharing and transfer between nodes that act as hosts and routers with or without human intervention. Thus, new algorithms and adjustments to existing ones must be compatible with the new type of network due to weak processing and low-power devices in IoT.

Routing is a growing research topic in the IoT network, and research area over the past few years has seen many achievements. However, in the most routing protocols, the flood of root request packets leads to increase the overhead. Thus, the best route is determined between the source and destination based on the instructions on the route. Many researchers recently focused on designing and implementing routing algorithms to enhance the performance and longevity of the network.

The IoT network is characterized by the nature of its decentralized and regulated resources, which cause difficulties in designing the algorithms [9] that ultimately control its widespread adoption. This work focuses on improving the LOADng routing protocol for IoT displays. LOADng [10–12] is derived from AODV routing, a reactive routing protocol that relies on route detection using route requests and route response messages. In this case, if the route towards the destination is uncertain, then a new route-finding process must be initiated. LOADng removes intermediate RREPs and precursor lists, which regulates control packets and reduces their issue. There are 12 critical parameters of LOADng can be rated as optimal for adjusting the Quality of Service (QoS) in IoT. To improve the QoS and efficiency of LOADng, the following contributions are presented in this paper.

To enhance the performance of LOADng, the Black Widow Optimization (BWO) algorithm is presented. The values of LOADng protocol parameters namely, RREP_ACK_TIMEOUT, RREQ_JITTER, NET_TRAVERSAL_TIME and R_HOLD_TIME are optimally selected using this algorithm. In BWO, routing overhead and delivery ratio are considered as objective functions.

The remainder of the paper is listed as follows. Section 2 examines some current work focused on research on routing in IoT. Section 3 provides the methodology of the work. The results of the proposed work are discussed in Section 4. Finally, Section 5 concludes the paper.

2 Related Works

Several recent research papers on IoT routing are discussed below;

Serhani et al. [13] developed a model based on the adaptive routing protocol (AQ-Routing) to identify the level in mobility at various points of time. In this approach, the authors introduced two models. First, the mobility level of each node was detected using Q-learning techniques. Secondly, static and dynamic routing metrics of the Q_{metric} were developed, which was connected and updated to the changing network topologies. These protocols efficiently manipulate network operation by modifying its behaviour in advance. The results of the article showed that the proposed model improved the packet delivery ratio than the existing model.

Krishnaraj et al. [14] introduced a model IoT environment, Ant Colony Optimization On-demand Multipath Distance Vector (ACOMDV) multi-homing is used for maximum power efficiency. The main aim of this method was to provide users with better energy efficiency and QoS policy. Therefore, the authors have developed an efficient routing model in the multi-homing mechanism. From the results, the proposed model achieved better energy consumption and delay, which was appropriate for multi-homing networks.

Dhumane et al. [15] presented an energy-efficient routing on IoT. This algorithm was utilized to detect the most favourable cluster head for energy efficient routing protocol in IoT networks. After this, the cluster head node was selected using Fractional Gravitational Search Algorithm (FGSA), and it was evaluated using distance, delay, connection lifetime and energy. Next, the results of the model and the effectiveness of the model were analyzed. The effectiveness of these models was analysed based on existing algorithms. From the results, the Multi-objective FGSA (MOFGSA) algorithm ensured the longevity of IoT nodes.

Chouhan et al. [16] proposed a model on IoT for multi-path routing protocol assisted by WSN networks using an optimization algorithm. In the approach, the Tunicate swarm Grey Wolf optimization (TSGWO) algorithm was used. Initially, the cluster head selection was performed using FGSA, and then the multipath routing process happened using TSGWO based on fitness parameters. In this approach, the minimum distance of the route was selected as the fitness parameter. From the results, the proposed approach achieved maximum PDR and throughput.

Jazebi et al. [17] presented a shuffled frog leaping algorithm-based routing model. In this approach, the authors had used shuffled frog leaping algorithm (SFLA). For this approach, the content-based path between the source and target nodes was determined by using SFLA on RISA. In addition, an appropriate data collection model was utilized to reduce energy consumption and enhance the network's lifetime. From the results, the proposed model achieved better performance in terms of network life, power consumption and PDR.

Khan et al. [18] introduced a model for Using distance awareness in IoT networks to optimize percentage Low-Energy Adaptive Clustering Hierarchy (PR-LEACH) routing. This approach helped to enhance the lifetime and stability of the network. In this approach, a modified PR-LEACH routing protocol was utilized. After this, the contact between the cluster head and sink was reduced to alleviate the energy wastage. It leads to increase lifetime of the sensor nodes in IoT. Finally, the proposed protocol achieved high throughput and outperformed the other parent protocols.

Hameed et al. [19] emphasized a model for IoT based on enabled sensor networks towards energy and performance-aware geographic routing. The sensor nodes' network throughput and energy consumption were focused on in this approach. To achieve these objectives, an energy-efficient geographic (EEG) routing protocol was developed. In addition, this method helps to avoid creating a vacuum in the network. Through efficient power balancing at the sensor terminals, the proposed protocol minimized the problem of power holes. Finally, the performance of the protocol was calculated using various metrics and which method achieved better energy consumption on the network, throughput and packet delivery ratio.

Lobiyal et al. [20] have proposed an optimal parameter combination for Ad-hoc on-demand multipath distance vector routing (AOMDV) for enhanced QoS in vehicle ad-hoc networks (VANETs). They have considered the VANET scenario and performed parameter optimization for the AOMDV routing protocol. The simulation results showed that the selected parameters enhanced the QoS performance parameters efficiently.

Alhammad et al. [21] have emphasized mobility management to ensure continuous communication moving from one cell to another. An optimization (ATO) algorithm is used to adapt the handover margin and triggering time. It aimed to reduce the count of handover (HO) and its failure ratio. A simulation based on the two-tier model for 4G and 5G networks has been done, and the results show that the average rates of these parameters and the number of call drops have reduced.

Brisolara et al. have focused on efficient load-balancing techniques for improving network longevity. Load Balancing depends on several parameters rather than a single parameter [22]. In their work, the authors have proposed an automatic parameter selection strategy. Two bio-inspired load balancing techniques Ant-Colony and Pheromone Signalling (PS) have been utilised to implement the proposed strategy. A method to speed up the genetic algorithm was also realized for better efficiency. The experimental results showed improvement in performance in both grid and random deployment scenarios.

3 Methodology

3.1 Overview

IoT devices first collect data from the environment and send it to the destination. The data is forwarded through the intermediate devices between the sources. Therefore, routing is the main problem in IoT. In this paper, the LOADng routing protocol is used for routing, and the BWO algorithm is presented to improve the effectiveness of the LOADng. This algorithm optimizes the values of the LOADng protocol parameters NET_TRAVERSAL_TIME, R_HOLD_TIME, RREP_ACK_TIMEOUT and RREQ_JITTER to control overhead and delay. The above process represented in Fig. 1.

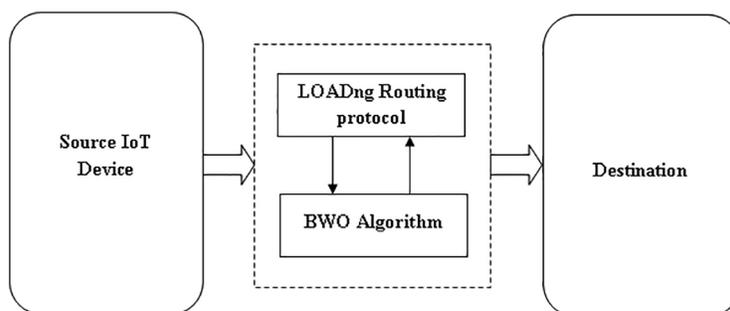


Figure 1: Structure of the proposed model

3.2 LOADng Routing Protocol

LOADng is the second version of the AODV protocol. Route-finding packets, also known as RREQs, are routed requests generated by the source device and are accompanied by targeted route responses (RREPs). Failure to connect the route links between the source and the destination in this protocol will result in a path error message, referred to as the local path repair message, i.e., the RERR message.

Under the LOADng protocol, the intermediate nodes between the source and the destination are not permitted to react to the RREQ, even if the path to the destination is active. Only targets responding to RREQ are allowed. Free RREPs can be removed when the loop freedom is confirmed as RREQ or RREP, using a unique, uniformly incremental serial number. Thus, the data packet will only be sent to the RERR source if it fails to achieve the next hop in the route.

3.2.1 Control Messages

Control messages are four types in this protocol, which are listed below;

RREQ: It is generated by the source, and is sent to the destination.

RREP: It was created by the target upon RREQ reception from the source.

RREP-ACK (RREP Acknowledgement): LOADng router creates it. The router agrees to the RREP via the RREP-ACK message after receiving the RREP from a neighbour.

RERR: It is generated by the router when a connection fails to forward the data packet.

3.2.2 Key Operations of the Protocol

The AODV route detection and route upkeep functions are listed as follows:

Route detection: The source fills in the RREQ through the network, and it is advanced until the target is reached, which is represented in Fig. 2. Furthermore, as described in Fig. 3, the target responds the source route request via route reply, which is then sent to the Unicast.

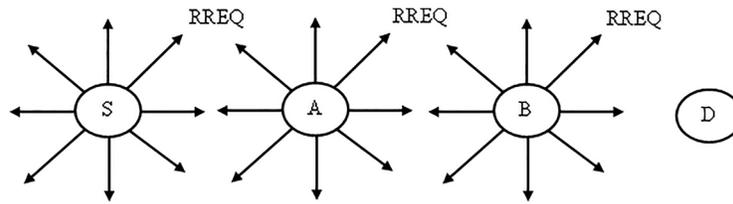


Figure 2: Route request (RREQ)

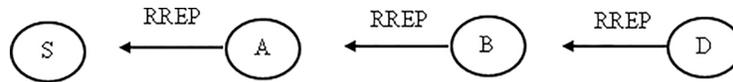


Figure 3: Route reply (RREP)

Route maintenance: Route maintenance will be enabled by the route between the source and the target in case of failure. When the route is failed, RERR is created on this protocol. This RERR is sent to the source in Unicast. The source begins to find a new way after receiving the RERR. This protocol removes the precursor list, which uses the end-to-end signal.

In the IoT, LOADng supplies efficient routing; however, its effectiveness can be enhanced using routing overhead and delay. Table 1 shows the optimization parameters. The BWO algorithm [23] is presented to optimize the parameters of LOADng. The most favourable part of the morals of the LOADng parameters with BWO is described in the following section.

Table 1: Parameters of LOADng

Parameters	Description
NET_TRAVERSAL_TIME	In the network, the maximum time packets take to travel between two ends (1–10 s)
RREQ_JITTER	Maximum time-lapse for RREQ transfer at node (0–1 s)
RREP_ACK_TIMEOUT	Minimum time to wait for an RREP_ACK, before considering unidirectional connection (1–10 s)
R_HOLD_TIME	The minimum time for a route will be placed after the last update in the routing table (1–10 s)

3.3 LOADng Protocol Parameter Tweaking Using Metaheuristic Optimization

Although LOADng protocol offers simplicity and flexibility in the control messages than traditional AODV protocol, there is a scope for improving the performance of it. The choice of the control parameters can significantly depict inconsistency in the protocol’s performance. Discovering the optimal values of these factors and analyzing their impact on performance is challenging. Additionally, the need for tuning these parameters arises due to indistinct default values. The range of these parameters is given in Table 1. This set of parameters is considered as solution in the algorithm. Thus, the optimal selection of values can yield better performance rather than that with the default ones. The below section presents the overview of various optimization algorithms used for tweaking the parameters of LOADng routing.

3.3.1 Black Widow Optimization

The black widow spider’s mating characteristics can be used to define this algorithm. The critical phase of the exclusive phase is called cannibalism in the BWO algorithm. Spiders can be thought of as air-breathing

arthropods with venomous teeth on all eight legs. Each spider in the BWO algorithm describes a solution, and the algorithm starts with a population of spiders. As part of the reproduction process, these early spider pairs go for creating a new generation. During and after mating, the female black widow noshes the male spider. Then, the female produces black widow eggs in sacks. The new generation of spider eggs hatches after 11 days. The process of cannibalism involves the eating behaviour of the spider. The main stages of BWO are discussed below;

Initial population: Black widow spiders are considered as a solution to every problem, are used in the BWO algorithm to measure the probable answers to each problem. Eq. (1) represents the initial population of the BWO;

$$W = [X^1, X^2, \dots, X^{N^{Var}}] \quad (1)$$

where, N^{Var} is described as a dimension of parameters, X^1, X^2 can be considered as the floating-point number and can be defined as follows:

$$X^N = \{B_1, B_2, B_3, B_4\}^N \quad (2)$$

where, B_1 represents the NET_TRAVERSAL_TIME with [1–10 s] rang, B_2 describes the RREQ_JITTER with [0–1 s] rang, B_3 represents the RREP_ACK_TIMEOUT with [1–10 s] rang and B_4 represents the R_HOLD_TIME with [1–10 s] rang.

Fitness calculation: Every solution is calculated based on the fitness function after the solution initialization. Eq. (3) represents the fitness function.

$$F(W) = f[X^1, X^2, \dots, X^{N^{Var}}] \quad (3)$$

A candidate widow matrix is created by the spider's early population. After that, the parent couple was arbitrarily assigned to carry out the reproductive process through reproduction, which is affected by the female before and after the male black widow.

The solution is evaluated by the following fitness function to attain the optimal LOADng parameters.

$$F(W) = MAX (w_1 * PDR - w_2 * RO) \quad (4)$$

where, the packet delivery ratio is represented as $PDR = (Number\ of\ pkts\ delivered / Number\ of\ pkts\ sent\ from\ source)$, the routing overhead is represented as RO which is defined the quantity of routing packets sent for maintenance and also for route discovery and the weight parameter are represented as w_1 and w_2 . RO is denoted with a negative sign because Eq. (4) indicates the maximum function. According to Eq. (4), the solution with the maximum fitness value was selected as the optimal solution. Otherwise, the solution will be updated until an optimal solution is found.

Update the solution: In this algorithm, the following processes are used to update the solution.

Procreate: The spiders begin to mate on their web to reproduce a new generation. More than 1000 eggs are laid in each mating process in real-world applications. An array (α) is formed of random numbers (widow array) to create a new population. The offspring is created by using α and pairs (X^1 and X^2), which is described in Eq. (5);

$$\begin{cases} Y^1 = \alpha * X^1 + (1 - \alpha) * X^2 \\ Y^2 = \alpha * X^2 + (1 - \alpha) * X^1 \end{cases} \quad (5)$$

This process can be repeated at different times with randomly selected numbers that are not copied. To sort the array, fitness parameters and ratings of cannibalism are considered. In addition, solutions suitable for newly created people are collected.

Cannibalism: Three different types of cannibalism are presented in the BWO algorithm. The process by which a lady widow disconnects her spouse before and after reproduction is called sexual cannibalism. The weak sibling spiders are eaten by the sibling cannibalism process. The mother may be eaten by spiders in some cases of cannibalism. The fitness value affects the weak or strong spider determination.

Mutation: Mute pop numbers are automatically selected with the population during this process. The two components in the array structure were approximately replaced by each solution. The mutation rate is calculated based on the mute pop.

Convergence: To verify the final position, the algorithm can go through three steps, such as

- 1-Achieving a certain level of accuracy,
- 2-Ensuring that there is no variation in fitness value, and
- 3-Multiple iterations.

To select the optimal parameters of LOADng, an adaptive projected method is used. By using the fitness function, the BWO algorithm is enhanced to ensure the highest PDR and lowest routing load by selecting the best loading parameter.

Algorithm: Selection of optimal LOADng parameters using BWO algorithm

Input: LOADng parameters, procreate rate, cannibalism rate and mutation rate

Output: Optimal LOADng parameters

1. Initialize the widow or candidate solutions.
2. Calculate fitness for each solution using (4).

Procreating and Cannibalism

3. Choose two solutions as parents randomly from population 1.
4. Produce children based on Eq. (5).
5. Demolish father.
6. Demolish some of the children depend on the cannibalism rate
7. Store the rest of the solutions in population 2.

Mutation

8. Determine the number of mutation children depending on the mutation rate.
9. Choose a solution from population 1.
10. Mutate the solution's one chromosome and produce a new solution
11. Store the new solution into population 3.

Updating

12. Update the solution as population = population 2 + population 3
13. Steps 2–12 are continued until finding the optimal solution or optimal parameters of LOADng.
14. Otherwise, the algorithm terminated based on the convergence.

3.3.2 Particle Swarm Optimization

Particle Swarm Optimization (PSO) involves random number generation. The performance of the PSO algorithm is influenced by the size and the quality of these numbers. PSO is an advantageous algorithm as it can run the global and local searches in parallel efficiently. To find the optimal results from an extensive vector range, each particle can be updated simultaneously, and the updated values are extracted at once per iteration. The prior iteration starts with searching the entire vector space. The significant steps involved in the PSO algorithm are:

- i) Generate ‘M’ particles in the given search space and assign random positions and velocities to them.
- ii) Compute the fitness function value using Eq. (2) for the corresponding swarm particles.
- iii) Associate this fitness value as the current pbest for the particle.
- iv) In each round the pbest values will be compared and will be updated if the current pbest value is better than the previous one. The position and velocity of particles are revised at every iteration according to Eqs. (6) and (7), respectively.

$$X_n(i+1) = X_n(i) + V_n(i+1) \quad (6)$$

$$V_n(i+1) = w_i V_n(i) + c_1 r_1 (pbest_n - X_n(i)) + c_2 r_2 (gbest_n - X_n(i)) \quad (7)$$

where c_1 & c_2 are local and social constants, r_1 and r_2 are random numbers between 0 & 1 and w_i is the inertia weight constant.

- v) Afterwards, assign the fitness value with the previous overall best. Thus, $pbest_i$ gives the best-fitted value for the i^{th} particle.
- vi) Ascertain the particle in the vicinity with the best attainment so far, and allot its position to the variable g . Finally, $gbest$ gives the best-fitted value as explored by all the particles in the set.

4 Results and Discussions

In this part, the effectiveness of the suggested LOADng-BWO is evaluated. The proposed model is simulated in NS2. The simulation setting of the proposed model is shown in Table 2. 100 numbers of nodes are deployed in the simulation area with a size of 1000 m × 1000 m. In addition to this simulation, 802.11 MAC standard and constant bit rate (CBR) based traffic source is also used. The data transmission rate of 500 kbps is taken and with each packet of 512 bytes. The LOADng routing protocol is utilized for routing the data packet and every approach simulation time is 100 s. These values are defined in [19].

Table 2: Simulation setting

Parameters	Assumptions
Number of nodes	50–100
MAC	802.11
Area	1000 m × 1000 m
Rate	500 Kbps
Traffic source	CBR
Simulation time	100 s
Propagation	TwoRayGround
Packet size	512 byte

(Continued)

Table 2 (continued)

Parameters	Assumptions
Antenna	Omni antenna
Routing protocol	LOADng-BWO
BWO algorithm	
Procreate rate	0.6
Cannibalism rate	0.44
Mutation rate	0.4
PSO algorithm	
Local coeff c_1	2
Social coeff c_2	2
Inertia weight w_i	0.5

4.1 Evaluation Metrics

The effectiveness of the suggested model is calculated using delivery ratio, overhead and delay. These performance metrics are described as follows,

$$\text{Packet delivery ratio(PDR): } PDR = \frac{\text{number of received packets at the destination}}{\text{number of transmitted packets from the source}}$$

Delay: It is described as the mean time taken for data transmission from source to destination.

Overhead: It is described as the no. of control messages forwarded for route discovery and its maintenance.

4.2 Performance Analysis

The performance of the proposed scheme is analyzed under two scenarios that are the point-to-point scenario (P2P) traffic and the multipoint-to-point scenario (MP2P) traffic. The proposed model's effectiveness is calculated using delay, delivery rate and control overhead. In addition, the suggested model is compared with the traditional LOADng routing protocol.

4.2.1 Scenario 1: Point to Point (P2P) Traffic

In this scenario, single source and single destination with 30 pairs are considered. Figs. 4–6 shows a comparative analysis of different routing protocol in terms of the delay, distribution rate, and overhead of the various nodes. Fig. 4 shows the comparison of delay of different routing algorithms.

According to Fig. 4, the proposed approach achieved minimum delay at the maximum number of nodes as compared to other LOADng models. As depicted in the figure, the delay of the BWO-LOADn is decreased to 28% and 12.4% than that of LOADng and PSO-LOADng respectively. In Fig. 5, various routing protocols are compared based on the delivery ratio. According to the figure, all algorithms reach almost similar values at various numbers of nodes. Fig. 6 shows the comparison of overhead of different routing algorithms. According to the figure, the overhead of proposed system is reduced to 15% and 11.8% than that of LOADng and PSO-LOADng respectively. To decrease the no. of conflicts and control packets, RREQ_JITTER and R_HOLD_TIME should be set to a value that reduces overhead control.

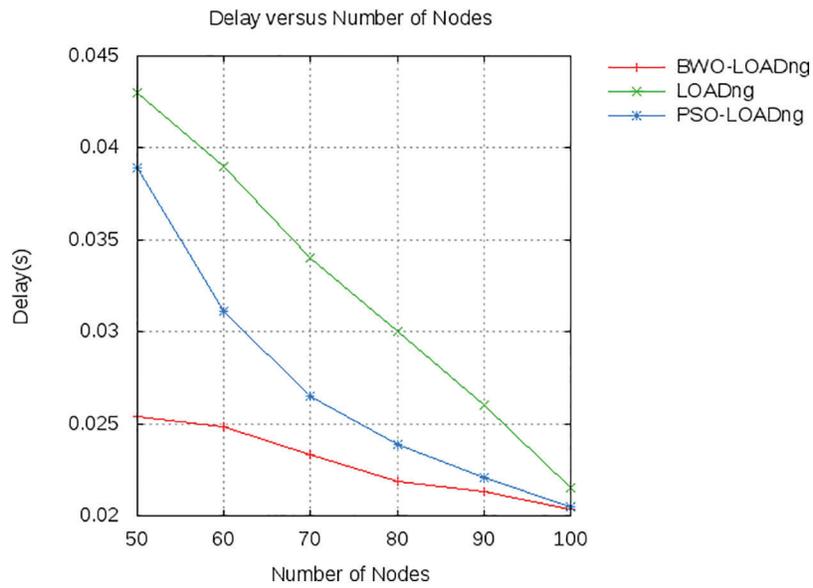


Figure 4: Comparison analysis based on delay

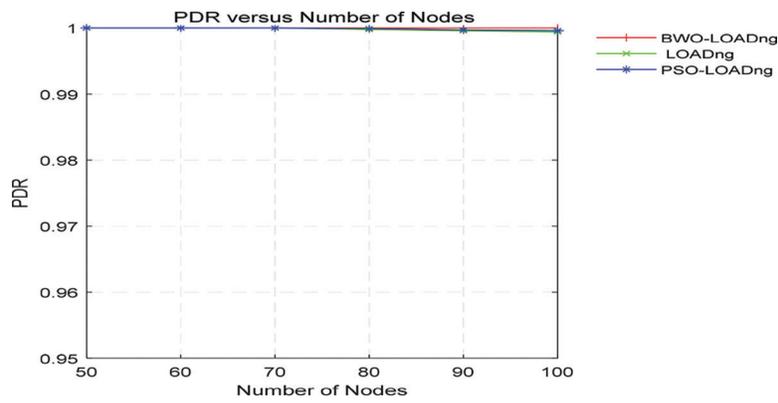


Figure 5: Comparison analysis based on delivery ratio

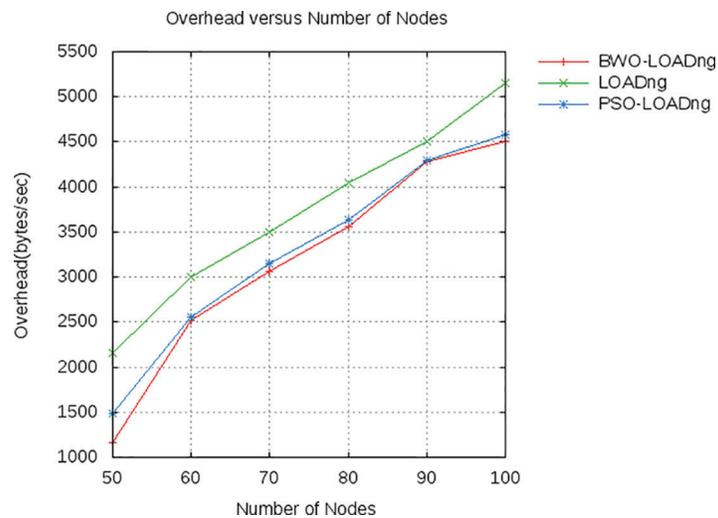


Figure 6: Comparison analysis based on overhead

4.2.2 Scenario 2: Multipoint to Point (MP2P) Traffic

In this scenario, multiple source nodes and a single destination are considered. Fig. 7 shows the comparison of delay of different routing for varying numbers of nodes.

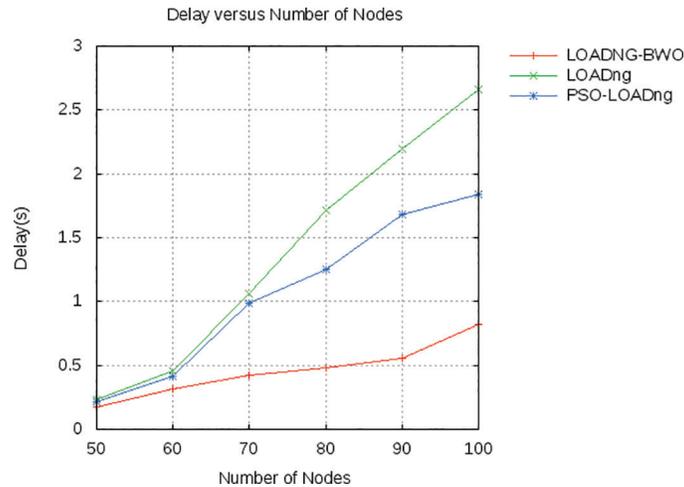


Figure 7: Comparison analysis based on delay

According to the figure, the proposed approach achieved improved delay value, which is decreased by 67% in the case of BWO and 23.33% for PSO than the default LOADng protocol. With LOADng, the RREQ_JITTER parameter is improved using BWO. When analysing Fig. 8, the proposed model’s delivery ratio is increased by 14% for BWO and around 6% for PSO than that of LOADng. In Fig. 9, the overhead of different routing algorithms is compared to different nodes. When analyzing the figure, the BWO achieved the minimum of 56% and PSO achieved 49.5% of overhead than the LOADng protocol.

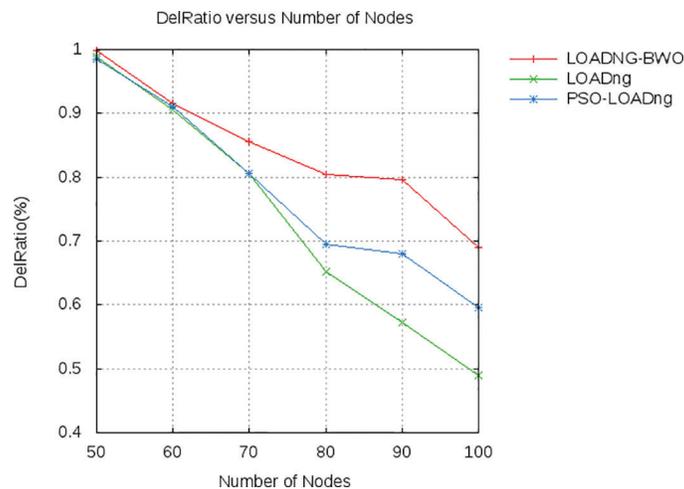


Figure 8: Comparison analysis based on delivery ratio

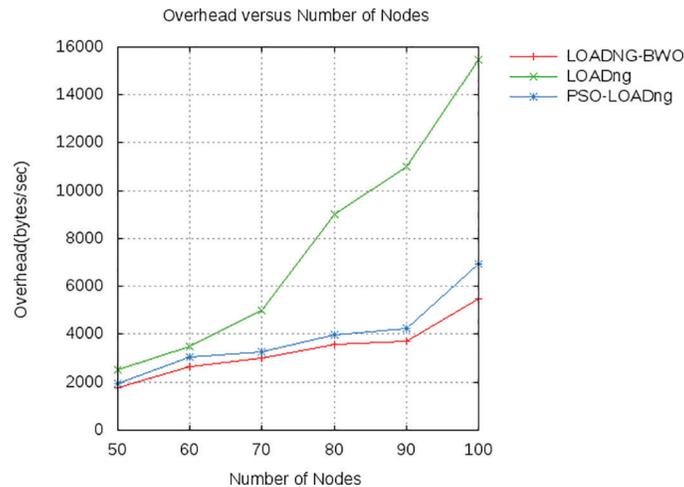


Figure 9: Comparison analysis based on overhead

5 Conclusion

In this paper, an optimized LOADng is presented for IoT. The BWO and PSO algorithm have been used to auto-tune parameters such as RREQ_JITTER, NET_TRAVERSAL_TIME, RREP_ACK_TIMEOUT, and R_HOLD_TIME. Various scenarios, such as P2P and MP2P, are utilized to calculate the optimal LOADng performance. The performance of the proposed auto-tuned LOADng has been analyzed various metrics. Simulation outcomes showed that the proposed model achieved enhanced delay and overhead of 28% and 15%, respectively, under the P2P scenario compared with default-LOADng. Furthermore, the proposed LOADng-BWO routing protocol achieved a delay of 67%, a delivery ratio of 14% and an overhead of 56% under the MP2P scenario. Besides, the performance of BWO outperformed that of PSO. Using the optimal parameters, LOADng routing can be efficiently applied to IoT-based network applications. The limitation of this study is less energy efficiency and unaware of security. Thus, in the future, the energy efficiency and security of the network are to be enhanced by presenting clustering and cryptography algorithms.

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