# The Influence of Gravitational Field on Generalized Thermoelasticity with Two-Temperature under Three-Phase-Lag Model 

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#### Abstract

The problem of the generalized thermoelastic medium for three different theories under the effect of a gravitational field is investigated. The LordShulman, Green-Naghdi III, three-phase-lag theories are discussed with twotemperature. The normal mode analysis is used to obtain the analytical expressions of the displacement components, force stress, thermodynamic temperature and conductive temperature. The numerical results are given and presented graphically, when the thermal force is applied. Comparisons are made with the results predicted by three-phase-lag model, Green-Naghdi III and Lord-Shulman theories in the presence and absence of gravity as well as two temperature.


Keywords: gravity, three-phase-lag, thermoelastic, thermodynamic temperature, conductive temperature, normal-mode.

## Nomenclature

$\lambda, \mu \quad$ Lame's parameter counterparts
$u, w$ displacement components
$g \quad$ gravity
$a \quad$ the volume coefficient of thermal expansion
$\delta_{i j} \quad$ Kronecker delta
$\rho \quad$ mass density
$c_{e} \quad$ specific heat at constant strain
$K(\geq 0)$ thermal conductivity
$K^{*} \quad$ material characteristic of the theory

[^0]$T$ thermodynamic temperature
$T_{0} \quad$ reference temperature
$\phi \quad$ conductive temperature
$\tau_{v} \quad$ phase lag of thermal displacement gradient
$\tau_{t} \quad$ phase lag of temperature gradient
$\tau_{q} \quad$ phase lag of heat flux
b constant material "two temperature parameter "
$\omega_{i j} \quad$ skew symmetric tensor called the rotation tensor

## 1 Introduction

The effect of mechanical and thermal disturbances on an elastic body is studied by the theory of thermoelasticity. This theory has two defects, it has been studied by Biot (1956). He deals with a defect of the uncoupled theory that mechanical causes have no effect on temperature. This theory predicts an infinite speed of propagation of heat waves which is a defect that it shares with the uncoupled theory. The first theory was studied by Lord and Shulman (1967), who formulated the generalized thermoelasticity theory involving one thermal relaxation time. The second theory was discussed by Green-Lindsay (1972). They introduced two different relaxation times in the entropy expression and stress-strain relations. The third generalization of the coupled theory of thermoelasticity introduced by Green and Naghdi (1993) whose developed different theories labeled type I, type II, and type III. The Green-Naghdi (G-N) theory of type I in the linearized theory is equivalent to the classical coupled thermoelasticity theory, the (G-N) theory of type II does not admit energy dissipation, and the third (G-N) theory of type III admits dissipation of energy and the heat flux is a combination of type I and type II. The fourth generalization of the coupled theory of thermoelasticity is developed by Tzau (1995) and Chandrasekhariah (1998) and is referred to the dual-phase-lag thermoelasticity. Abbas and Othman (2012) have studied the generalized thermoelsticity of thermal shock problem in an isotropic hollow cylinder and temperature dependent elastic moduli. Raychoudhuri (2007) has recently introduced the three-phase-lag, heat conduction equation in which the Fourier law of heat conduction is replaced by an approximation to a modification of the Fourier law with the introduction of three different phase-lag for the heat flux vector, the temperature gradient and the thermal displacement gradient. The stability of the three-phase-lag, the heat conduction equation is discussed by Quintanilla and Racke (2008). Reflection and transmission of waves from the imperfect boundary between two heat conducting micropolar thermoelastic solids by Marin (2014a). Weak solutions in elasticity of dipolar bodies with stretch were studied by Marin (2013). On temporal behav-
ior of solutions in thermoelasticity of porous micropolar bodies by Marin (2014b). The effect of initial stress on generalized thermoelastic medium with three-phaselag model under temperature dependent properties has studied by Othman et al. (2014a). Subsequently Kar and Kanoria (2009) have employed this theory of thermoelasticity with three-phase-lag to discuss a problem of thermoelastic interactions on functional graded orthotropic hollow sphere under thermal shock.
In the classical theory of elasticity, the gravity effect is generally neglected. Generalized thermoelastic medium with temperature-dependent properties for different theories under the effect of gravity field has studied by Othman et al. (2013a). The effect of gravity in the problem of propagation of waves in solids, in particular on an elastic globe, was first studied by Bromwich (1898). The influence of the gravitational field and rotation on a generalized thermoelastic medium using a dual-phase-lag model has studied by Othman et al. (2013b). Subsequently, an investigation of the influence of the gravitational field and rotation on thermoelastic solid with voids under Green-Naghdi theory was considered by Othman et al. (2013c). The effect of gravity on the surface waves, on the propagation of waves in an elastic layer has been studied by De and Sengupta (1974 and 1978). The effect of rotation on micropolar generalized thermoelasticity with two temperature using a dual-phase-lag model has studied by Othman et al. (2014b). Generalized thermoelsticity of thermal shock problem in a non-homo-geneous isotropic hollow cylinder with energy dissipation studied by Othman and Abbas (2012).

The two temperature theory of thermoelasticity was introduced by Gurtin and Williams (1967), Chen and Gurtin (1968), and Chen et al. (1968), in which the classical Clausius-Duhem inequality was replaced by another one depending on two temperature; the conductive temperature and the thermodynamic temperature, the first is due to the thermal processes, and the second is due to the mechanical processes inherent between the particles and the layers of elastic material, this theory was also investigated by Ieşan (1970). The two-temperature model was underrated and unnoticed for many years thereafter. Only in the last decade has the theory been noticed, developed in many works, and find its applications, mainly in the problems in which the discontinuities of stresses have no physical interpretations. Among the authors who contribute to develop this theory, Quintanilla (2004) studied existence, structural stability, convergence and spatial behavior of this theory. Youssef (2006) introduced the generalized Fourier's law to the field equations of the two-temperature theory of thermoelasticity and proved the uniqueness of the solution for homogeneous isotropic material, Puri and Jordan (2006) studied the propagation of harmonic plane waves. Recently, Magaña and Quintanilla (2009) have studied the uniqueness and growth solutions for the model proposed by Youssef (2006).

The present paper is concerned with the investigations related to the effect of gravity with two temperature on a generalized thermoelastic medium based on three-phase-lag model by applying the normal mode analysis. Also, the effect of gravity and two-temperature on the physical quantities are discussed numerically and illustrated graphically.

## 2 Formulation of the problem and basic equations

We consider a homogeneous thermoelastic half-space with two-temperature under the influence of gravity. All the considered quantities are functions of the time variable $t$ and of the coordinates $x$ and $z$ We consider the normal source acting on the plane surface of generalized thermoelastic half-space under the influence of gravity. The system of governing equations of a linear thermoelasticity with gravity and without body forces consists of:
The stress-strain relation written as:
$\sigma_{i j}=2 \mu e_{i j}+\left[\lambda e-\gamma\left(T-T_{0}\right)\right] \delta_{i j}$.
The equation of motion in the absence of body force
$\sigma_{i j, j}+\rho g w_{, x}=\rho \ddot{u}$,
$\sigma_{i j, j}-\rho g u_{, x}=\rho \ddot{w}$.
The equation of heat conduction under three phase lag model
$K^{*} \nabla^{2} \phi+\tau_{v}^{*} \nabla^{2} \dot{\phi}+K \tau_{t} \nabla^{2} \ddot{\phi}=\left(1+\tau_{q} \frac{\partial}{\partial t}+\frac{\tau_{q}^{2}}{2!} \frac{\partial^{2}}{\partial t^{2}}\right)\left(\rho c_{e} \ddot{T}+\gamma T_{0} \ddot{e}\right)$.
Where, $\tau_{v}^{*}=\left(K+K^{*} \tau_{v}\right)$,
$T=\left(1-b \nabla^{2}\right) \phi$,
$e_{i j}=\frac{1}{2}\left(u_{i, j}+u_{j, i}\right)$,
$\omega_{i j}=\frac{1}{2}\left(u_{j, i}-u_{i, j}\right)$.
For a two dimensional problem in $x z$-plane, Eqs. (2) - (4) can be written as:

$$
\begin{align*}
& \mu \nabla^{2} u+(\lambda+\mu) \frac{\partial e}{\partial x}-\gamma\left(1-b \nabla^{2}\right) \frac{\partial \phi}{\partial x}+\rho g \frac{\partial w}{\partial x}=\rho \frac{\partial^{2} u}{\partial t^{2}}  \tag{8}\\
& \mu \nabla^{2} w+(\lambda+\mu) \frac{\partial e}{\partial z}-\gamma\left(1-b \nabla^{2}\right) \frac{\partial \phi}{\partial z}-\rho g \frac{\partial u}{\partial x}=\rho \frac{\partial^{2} w}{\partial t^{2}} \tag{9}
\end{align*}
$$

$K^{*} \nabla^{2} \phi+\tau_{v}^{*} \nabla^{2} \frac{\partial \phi}{\partial t}+K \tau_{t} \nabla^{2} \frac{\partial^{2} \phi}{\partial t^{2}}=\left(1+\tau_{q} \frac{\partial}{\partial t}+\frac{\tau_{q}^{2}}{2!} \frac{\partial^{2}}{\partial t^{2}}\right)\left[\left(\rho c_{e}\left(1-b \nabla^{2}\right) \ddot{\phi}+\gamma T_{0} \frac{\partial^{2} e}{\partial t^{2}}\right]\right.$.

For the purpose of numerical evaluation, we introduce dimensions variables $\left(x^{\prime}, z^{\prime}\right)=\frac{\omega^{*}}{c_{0}}(x, z), \quad\left(u^{\prime}, w^{\prime}\right)=\frac{\rho c_{0} \omega^{*}}{\gamma T_{0}}(u, w)$,
$\sigma_{i j}^{\prime}=\frac{1}{\gamma T_{0}} \sigma_{i j}, \quad\left(t^{\prime}, \tau_{v}^{\prime}, \tau_{q}^{\prime}, \tau_{t}^{\prime}\right)=\omega^{*}\left(t, \tau_{v}, \tau_{q}, \tau_{t}\right)$,
$\left[T^{\prime}, \phi^{\prime}\right]=\frac{1}{T_{0}}[T, \phi], \quad c_{0}^{2}=\frac{\lambda+2 \mu}{\rho}, \quad e=\frac{\gamma T_{0}}{\rho c_{0}^{2}} e^{\prime}, \quad g^{\prime}=\frac{g}{c_{0} \omega^{*}}$
$\omega^{*}=\frac{\rho c_{e} c_{0}^{2}}{K}, \quad \nabla^{2}=\frac{\omega^{* 2}}{c_{0}^{2}} \nabla^{\prime 2} \quad \gamma=(3 \lambda+2 \mu) \alpha_{t}$
Using the above dimensions quantities, Eqs. (8) - (10) become
$\left(\frac{\mu}{\lambda+2 \mu}\right) \nabla^{2} u+\left(\frac{\lambda+\mu}{\lambda+2 \mu}\right) \frac{\partial e}{\partial x}-\left(1-b^{*} \nabla^{2}\right) \frac{\partial \phi}{\partial x}+g \frac{\partial w}{\partial x}=\frac{\partial^{2} u}{\partial t^{2}}$,
$\left(\frac{\mu}{\lambda+2 \mu}\right) \nabla^{2} w+\left(\frac{\lambda+\mu}{\lambda+2 \mu}\right) \frac{\partial e}{\partial z}-\left(1-b^{*} \nabla^{2}\right) \frac{\partial \phi}{\partial z}-g \frac{\partial u}{\partial x}=\frac{\partial^{2} w}{\partial t^{2}}$,
$\varepsilon_{1} \nabla^{2} \phi+\varepsilon_{2} \nabla^{2} \dot{\phi}+\tau_{t} \nabla^{2} \ddot{\phi}=\left(1+\tau_{q} \frac{\partial}{\partial t}+\frac{\tau_{q}^{2}}{2!} \frac{\partial^{2}}{\partial t^{2}}\right)\left[\left(1-b^{*} \nabla^{2}\right) \ddot{\phi}+\varepsilon_{3} \ddot{e}\right]$.
Where, $\varepsilon_{1}=\frac{K^{*}}{\rho c_{e} c_{0}^{2}}, \varepsilon_{2}=1+\varepsilon_{1} \tau_{\nu}, \varepsilon_{3}=\frac{\gamma^{2} T_{0}}{\rho^{2} c_{e} c_{0}^{2}}, b^{*}=\frac{b \omega^{* 2}}{c_{0}^{2}}$.
We define displacement potentials $q$ and $\psi$ which relate to displacement components $u$ and $w$ as,
$u=q_{, x}-\psi_{, z}, \quad w=q_{, z}+\psi_{, x}$.
Using Eq. (14) in Eqs. (11)-(13), we obtain:
$\nabla^{2} q-\left(1-b^{*} \nabla^{2}\right) \phi+g \frac{\partial \psi}{\partial x}=\frac{\partial^{2} q}{\partial t^{2}}$,
$a_{1} \nabla^{2} \psi-g \frac{\partial q}{\partial x}=\frac{\partial^{2} \psi}{\partial t^{2}}$,
$\varepsilon_{1} \nabla^{2} \phi+\varepsilon_{2} \nabla^{2} \dot{\phi}+\tau_{t} \nabla^{2} \ddot{\phi}=\left(1+\tau_{q} \frac{\partial}{\partial t}+\frac{\tau_{q}^{2}}{2!} \frac{\partial^{2}}{\partial t^{2}}\right)\left[\left(1-b^{*} \nabla^{2}\right) \ddot{\phi}+\varepsilon_{3} \nabla^{2} \ddot{q}\right]$.
Where, $a_{1}=\frac{\mu}{\lambda+2 \mu}=\frac{1}{\beta^{2}}$.

## 3 Normal mode analysis

The solution of the considered physical variable can be decomposed in terms of normal modes as the following form
$\left[u, w, e, T, \phi, q, \psi, \sigma_{i j}\right](x, z, t)=\left[u^{*}, w^{*}, e^{*}, T^{*}, \phi^{*}, q^{*}, \psi^{*}, \sigma_{i j}^{*}\right](z) \exp [i(\omega t+a x)]$.

Where, $\omega$ is the complex time constant and $a$ is the wave number in $x$-direction.
Using (18) in Eqs. (15)-(17), we obtain
$\left(D^{2}-A_{1}\right) q^{*}-\left(A_{2}-b^{*} D^{2}\right) \phi^{*}+A_{3} \psi^{*}=0$,
$\left(a_{1} D^{2}-A_{4}\right) \psi^{*}-A_{3} q^{*}=0$,
$\left(A_{5} D^{2}-A_{6}\right) \phi^{*}+A_{7}\left(D^{2}-a^{2}\right) q^{*}=0$.
Where, $A_{1}=\left(a^{2}-\omega^{2}\right), A_{2}=1+b^{*} a^{2}, A_{3}=i a g, A_{4}=a^{2} a_{1}-\omega^{2}$,
$A_{5}=\varepsilon_{1}+i \varepsilon_{2} \omega-\tau_{t} \omega^{2}-b^{*} \omega^{2}\left[1+i \tau_{q} \omega-\frac{\tau_{q}^{2}}{2!} \omega^{2}\right]$,
$A_{6}=\left(\varepsilon_{1} a^{2}+i \varepsilon_{2} \omega a^{2}-\tau_{t} \omega^{2} a^{2}\right)+\left(\omega^{2}+a^{2} \omega^{2} b^{*}\right)\left[1+i \tau_{q} \omega-\frac{\tau_{q}^{2}}{2!} \omega^{2}\right]$,
$A_{7}=\varepsilon_{3} \omega^{2}\left[1+i \tau_{q} \omega-\frac{\tau_{q}^{2}}{2!} \omega^{2}\right]$.
Eliminating $\phi^{*}$ and $\psi^{*}$ between Eqs. (19) - (21), we get
$\left[D^{6}-A D^{4}+B D^{2}-C\right]\left\{q^{*}(z), \phi^{*}(z), \psi^{*}(z)\right\}=0$.
Where,
$A=\frac{A_{4} A_{7} b^{*}+b^{*} a^{2} a_{1} A_{7}-a_{1} A_{2} A_{7}-A_{4} A_{5}-a_{1} A_{6}-a_{1} A_{5} A_{1}}{b^{*} a_{1} A_{7}-a_{1} A_{5}}$,
$B=\frac{-a_{1} A_{1} A_{6}-A_{1} A_{4} A_{5}-A_{4} A_{6}+A_{2} A_{7} a^{2} a_{1}+A_{2} A_{4} A_{7}+b^{*} A_{4} A_{7} a^{2}-A_{3} A_{3} A_{5}}{b^{*} a_{1} A_{7}-a_{1} A_{5}}$,
$C=\frac{-A_{1} A_{4} A_{6}+A_{2} A_{4} A_{7} a^{2}-A_{3} A_{3} A_{6}}{b^{*} a_{1} A_{7}-a_{1} A_{5}}$,
$\mathrm{D}=\frac{\mathrm{d}}{\mathrm{d} z}$.
The solution of Eq. (22) has the form
$q^{*}=\sum_{n=1}^{3} M_{n} e^{-k_{n} z}$,
$\psi^{*}=\sum_{n=1}^{3} H_{1 n} M_{n} e^{-k_{n} z}$,
$\phi^{*}=\sum_{n=1}^{3} H_{2 n} M_{n} e^{-k_{n} z}$,
$T^{*}=\sum_{n=1}^{3} H_{3 n} M_{n} e^{-k_{n} z}$.
Where, $M_{n}(n=1,2,3)$ are some constants, $k_{n}^{2}$ are the roots of the characteristic equation of Eq. (22).
Dimensionless variables of the stress components yields the following,
$\sigma_{x x}=u_{, x}+\left(1-\frac{2}{\beta^{2}}\right) w_{, z}-T$,
$\sigma_{z z}=w_{, z}+\left(1-\frac{2}{\beta^{2}}\right) u_{, x}-T$,
$\sigma_{x z}=a_{1}\left[u_{, z}+w_{, x}\right]$.
Using Eq. (14) and Eqs. (23)-(26) in (27)-(29)
$u=\sum_{n=1}^{3} H_{4 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$,
$w=\sum_{n=1}^{3} H_{5 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$,
$\sigma_{x x}=\sum_{n=1}^{3} H_{6 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$,
$\sigma_{z z}=\sum_{n=1}^{3} H_{7 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$,
$\sigma_{x z}=\sum_{n=1}^{3} H_{8 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$,
$T=\sum_{n=1}^{3} H_{3 n} M_{n} e^{i(\omega t+a x)-k_{n} z}$.
Where,
$H_{1 n}=\frac{A_{3}}{\left(a_{1} k_{n}^{2}-A_{4}\right)}, \quad H_{2 n}=\frac{-A_{7}\left(k_{n}^{2}-a^{2}\right)}{\left(A_{5} k_{n}^{2}-A_{6}\right)}, \quad H_{3 n}=H_{2 n}\left[1-b^{*}\left(k_{n}^{2}-a^{2}\right)\right]$,
$H_{4 n}=\left(i a+k_{n} H_{1 n}\right), \quad H_{5 n}=\left(-k_{n}+i a H_{1 n}\right)$,
$H_{6 n}=\left[i a H_{4 n}-\left(1-\frac{2}{\beta^{2}}\right) k_{n} H_{5 n}+H_{3 n}\right]$,
$H_{7 n}=\left[-k_{n} H_{5 n}+i a H_{4 n}\left(1-\frac{2}{\beta^{2}}\right)-H_{3 n}\right]$,
$H_{8 n}=\frac{1}{\beta^{2}}\left(-k_{n} H_{4 n}+i a H_{5 n}\right)$.

## 4 Boundary conditions

The boundary conditions on the plane surface $z=0$ are:
$\sigma_{x x}(x, 0, t)=\sigma_{x z}(x, 0, t)=0, \quad T=P e^{i(\omega t+a x)}$.
Using Eqs. (32), (34) and (35) in boundary conditions (36), we get three equations in three constants $M_{n}(n=1,2,3)$ as:
$\sum_{n=1}^{3} H_{6 n} M_{n}=0$,
$\sum_{n=1}^{3} H_{8 n} M_{n}=0$,
$\sum_{n=1}^{3} H_{3 n} M_{n}=P$.
Solving Eqs. (37)-(39) the constants $M_{n}(n=1,2,3)$ are defined as follows:
$M_{1}=\frac{\Delta_{1}}{\Delta}, \quad M_{2}=\frac{\Delta_{2}}{\Delta}, \quad M_{3}=\frac{\Delta_{3}}{\Delta}$.
Where,
$\Delta=H_{61}\left(H_{82} H_{33}-H_{83} H_{32}\right)-H_{62}\left(H_{81} H_{33}-H_{83} H_{31}\right)+H_{63}\left(H_{81} H_{32}-H_{82} H_{31}\right)$,
$\Delta_{1}=P\left(H_{83} H_{62}-H_{63} H_{82}\right), \quad \Delta_{2}=P\left(H_{63} H_{81}-H_{61} H_{83}\right)$,
$\Delta_{3}=P\left(H_{61} H_{82}-H_{62} H_{81}\right)$.

## 5 Numerical results

To study the effect of gravity and two-temperature, we now present some numerical results. For this purpose, copper is taken as the thermoelastic material for which we take the following values of the different physical constants.
$\lambda=7.7 \times 10^{10} N . M^{-2}, \quad \mu=3.86 \times 10^{10} \mathrm{Kg} \cdot \mathrm{m}^{-1} \cdot \mathrm{~s}^{-2}, \quad K=300 \mathrm{w} \cdot \mathrm{m}^{-1} \cdot \mathrm{~K}^{-1}$,
$\alpha_{t}=1.78 \times 10^{-5} \mathrm{~K}^{-1}, \quad \rho=8954 \mathrm{Kg} . \mathrm{m}^{-3}, \quad c_{e}=383.1 \mathrm{~J} . \mathrm{Kg}^{-1} \mathrm{~K}^{-1}$,
$T_{0}=293 K, \quad a=2.5, \quad \omega=\omega_{0}+i \xi, \quad \omega_{0}=-3, \quad \xi=3.6$,
$K^{*}=2.97 \times 10 \wedge 13, \quad x=0.5, \quad t=0.3, \quad P=0.05$,
$\tau_{\nu}=0.2, \quad \tau_{t}=0.6, \tau_{q}=0.8$.
The numerical technique, outlined above, was used for the distribution of the real part of the temperature $T$, the displacement components $u, w$ and the stress components $\sigma_{x x}, \sigma_{z z}, \sigma_{x z}$ for the problem. There are three lines expressing theories are, the "solid line" expresses the 3PHL theory, the "cross line" expresses the L-S theory, and the "dashed line" expresses the G-N III theory. Figs. 1(a,b)-6(a,b) show the distribution of the physical quantities based on L-S, G-N III and 3PHL in the case of $g=0,9.8$ respectively. Fig. $1(a, b)$ depict that the displacement component $u$ increases with the increase of gravity in the three theories. In the absence and presence of gravity (i.e. $g=0,9.8$ ), $u$ begins to increase then smooth decreases and takes the form of wave and try to return to zero. Fig. 2(a,b) exhibit that the displacement component $w$ increases with the decrease of gravity, and takes the form of a wave until it develops to zero, that's mean that the displacement $w$ is inversely proportional with gravity. Fig. 3(a,b) demonstrate that the behavior of temperature $T$ decreases for $g=0,9.8$ and takes the form of a wave until it develop to zero. Fig. $4(\mathrm{a}, \mathrm{b})$ show that the stress component $\sigma_{x z}$ increases with the increase of gravity $g$ in L-S, and decreases with the decrease of the gravity in G-N III and 3PHL and takes the form of the wave until it develop to zero. Fig. 5(a,b) depict that the stress component $\sigma_{x x}$ begins from the value zero and satisfies the boundary condition at $z=0$ in the three theories. The stress component $\sigma_{x x}$ decreases with the increase of gravity in L-S and 3PHL, and decreases during the period $0 \leq z \leq 1$, then increasing and takes the form of the wave until it develop to zero at $g=9.8$ in G-N III, while increases in the period $0 \leq z \leq 1$, then decreasing and takes the form of the wave until it develop to zero at $g=0$ in G-N III. Fig. $6(a, b)$ explain that the stress component $\sigma_{z z}$ decreases in the case of $g=0,9.8$ and decays to zero.
Figs. 7(a,b)-12(a,b) exhibit the distribution of the physical quantities based on L-S, G-N III and 3PHL in the case of $b=0,0.1$. Fig. 7(a,b) show that the displacement component $u$ increases with the increase of $b$ in G-N III and L-S theories, while,
it decreases with the increase of $b$ in 3PHL theory, and try to return to zero at infinity in three theories. Fig. 8(a,b) demonstrate that the displacement component $w$ increases at $b=0.1$, in three theories, in the range $0 \leq z \leq 1$, while decreases at $b=0$, in 3PHL theory, then, increases at $b=0$, in the range $0 \leq z \leq 0.5$, in G-N III and L-S theories, and takes the form of the wave until it develop to zero in three theories. Fig. $9(a, b)$ explain that the temperature satisfies the boundary conditions at $z=0$ and decreases, in the three theories to a minimum value in the range $0 \leq z \leq 1$, at $b=0.1$, while, increases for $z \geq 0.75$, at $b=0$, then, it decays to zero in the two cases. Fig. $10(\mathrm{a}, \mathrm{b})$ explain that the stress component $\sigma_{x z}$ decreases at $b=0.1$, in the range $0 \leq z \leq 0.5$ of the three theories, while decreases in the range $0 \leq z \leq 0.5$ for $b=0$ in the two theories L-S and 3PHL, but it increases for $b=0$ in G-N III, and takes the form of the wave until it develop to zero in L-S and G-N III and 3PHL theories. Fig. 11(a,b) show that the stress component $\sigma_{x x}$ satisfies the boundary condition and decreases to a minimum value in the range $0 \leq z \leq 1$, and increases in the range $1 \leq z \leq 2$, but, decays to zero in the three theories, for $b=0.1$, while, increases in the range $0 \leq z \leq 0.5$ for $b=0$ in 3PHL and G-N III theories and decays to zero, then, decreases in the range $0 \leq z \leq 0.5$ for $b=0$, and increases in the range $0.5 \leq z \leq 1$ for $b=0$ until it develop to zero in L-S theory. Fig. 12(a,b) show that the stress component $\sigma_{z z}$ decreases for $b=0.1$, in the three theories, and it decreases for $b=0$, in L-S and G-N III, but increases for $b=0$, in 3PHL then, decays to zero.


Figure 1: Distribution of displacement component $u$ in the presence and absence of $g$.


Figure 2: Distribution of displacement component $w$ in the presence and absence of $g$.


Figure 3: Distribution of the temperature $T$ in the presence and absence of $g$.


Figure 4: Distribution of the stress component $\sigma_{x z}$ in the presence and absence of $g$.


Figure 5: Distribution of the stress component $\sigma_{x x}$ in the presence and absence of $g$.


Figure 6: Distribution of the stress component $\sigma_{z z}$ in the presence and absence of $g$.


Figure 7: Distribution of displacement component $u$ in the presence and absence of $b$.


Figure 8: Distribution of displacement component $w$ in the presence and absence of $b$.


Figure 9: Distribution of the temperature $T$ in the presence and absence of $b$.


Figure 10: Distribution of the stress component $\sigma_{x z}$ in the presence and absence of $b$.


Figure 11: Distribution of the stress component $\sigma_{x x}$ in the presence and absence of b.


Figure 12: Distribution of the stress component $\sigma_{z z}$ in the presence and absence of b.

## 6 Conclusion

By comparing the figures obtained under the three theories, important phenomena are observed:

1. Analytical solutions based upon normal mode analysis of the thermoelastic problem in solids have been developed.
2. The method that is used in the present article is applicable to a wide range of problems in hydrodynamics and thermoelasticity.
3. There are significant differences in the field quantities under GN-III, 3PHL and L-S theories.
4. The presence of the gravitational field and two-temperature plays a significant role on all physical quantities.
5. The comparison of the three theories of thermoelasticity, Lord-Shulman theory, three-phase-lag model and Green-Naghdi III is carried out.
6. The value of all the physical quantities converges to zero, and all the functions are continuous.

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