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ARTICLE



Fatigue Assessment of Large-Diameter Stiffened Tubular Welded Joints Using Effective Notch Strain and Structural Strain Approach

Dan Jiao^{1,2}, Yan Dong^{1,2,*}, Hao Xie³, Yordan Garbatov^{4,*}, Jiancheng Liu⁵ and Hui Zhang⁵

ABSTRACT: Floating offshore wind turbine platforms typically use stiffened tubular joints at the connections between columns and braces. These joints are prone to fatigue due to complex weld geometries and the additional stress concentrations caused by the stiffeners. Existing hot-spot stress approaches may be inadequate for analysing these joints because they do not simultaneously address weld-toe and weld-root failures. To address these limitations, this study evaluates the fatigue strength of stiffened tubular joints using the effective notch strain approach and the structural strain approach. Both methods account for fatigue at the weld toe and weld root and can be applied to both low-cycle fatigue (LCF) and high-cycle fatigue (HCF) regimes. Reanalyzes of a series of fatigue-tested specimens confirm the effectiveness of both approaches. The stiffener-shell fillet weld root is identified as the most critical fatigue location, which is consistent with fractographic observations. Although the brace-to-shell weld root exhibits lower stress levels in finite element (FE) models, weld quality was determined to be a crucial factor in fatigue failure. Furthermore, the results emphasise the importance of material plasticity in the LCF regime and demonstrate that full weld penetration significantly enhances fatigue strength. These findings provide valuable insights for the fatigue design of stiffened tubular joints in floating offshore wind turbine platforms.

KEYWORDS: Stiffened tubular joints; weld root; effective notch strain; structural strain; finite element analysis

1 Introduction

Current floating offshore wind turbine platform designs typically employ multiple large columns interconnected by tubular braces [1–4]. These column-brace connections feature complex geometries with stiffeners, creating potential locations of fatigue failure due to high stress concentrations [5].

Research has demonstrated that internal ring stiffeners can enhance the strength of tubular joints when strategically positioned. Ramachandra [6] found that three axially loaded stiffeners in Y and T joints effectively reduce stress concentrations. Similarly, Lee and Llewelyn-Parry [7] showed via Finite Element (FE) analysis that stiffeners placed at the saddle (rather than the crown) provide optimal strength improvement in T and DT joints. However, their results showed that the stiffened joints fail at deformation levels similar to those of their unstiffened counterparts and are therefore able to maintain their ductility. However, the use of stiffeners for structural reinforcement of large-diameter cylindrical components introduces additional



¹Yantai Research Institute of Harbin Engineering University, Harbin Engineering University, Yantai, 261400, China

²College of Shipbuilding Engineering, Harbin Engineering University, Harbin, 150001, China

³Marine Design and Research Institute of China (MARIC), Shanghai, 200000, China

⁴Centre for Marine Technology and Ocean Engineering (CENTEC), Instituto Superior Técnico, Universidade de Lisboa, Lisbon, 1649-004, Portugal

⁵China Merchants Marine and Offshore Research Institute Co., Ltd., Shenzhen, 518000, China

^{*}Corresponding Authors: Yan Dong. Email: yan.dong@hrbeu.edu.cn; Yordan Garbatov. Email: yordan.garbatov@tecnico.ulisboa.pt Received: 06 October 2025; Accepted: 27 November 2025; Published: 23 December 2025

welds in the joint region. It may result in elevated local stresses and deteriorate the joint's fatigue resistance, rendering current design standards inadequate or obsolete [8]. Although stiffeners improve static load capacity, their associated weld seams create stress risers, potentially offsetting the benefits they provide under cyclic loading. Therefore, despite their structural advantages, stiffened tubular joints require careful assessment of their fatigue life to address the trade-offs introduced by additional welds.

The fatigue strength assessment of such stiffened welded tubular joints in offshore wind turbines primarily relies on the hot-spot stress approach. The hot-spot stress of the stiffened welded tubular joints cannot be calculated using empirical equations, because these equations were developed for unstiffened tubular joints and show limitations when applied to column-brace connections, particularly when the diameter ratio $(\frac{d_{brace}}{D_{column}})$ falls below 0.2, which lies outside the validated range of existing empirical solutions [9]. The FE method can be directly used to determine the hot-spot stress for the fatigue strength assessment [10].

However, the hot-spot stress approach is limited to addressing the weld toe failures [11,12]. Fatigue cracks can also be initiated at the root of the weld. Weld root fatigue is primarily caused by incomplete welding penetration, which results in non-fused root faces acting like a crack, or by poor weld quality at the weld root due to its inaccessibility, as indicated by fatigue tests on stiffened tubular joints performed by Papatheocharis et al. [13]. The weld toe and weld root fatigue exist simultaneously, indicating the need to carry out a fatigue strength assessment using alternative approaches [14].

Several approaches are suitable for assessing fatigue at both the weld toe and the weld root [11]. Among these approaches, the present study focuses on the mesh-insensitive structural stress approach [15] and the effective notch concept [16], because they employ uniform S-N curves for the two fatigue modes. The stiffened tubular joints experimentally investigated by Papatheocharis et al. [13] were reanalyzed to verify the applicability of the two approaches when dealing with the complex, large-scale specimens. Because two out of eight specimens were subjected to significant fatigue loadings, the extended versions of the two approaches that can deal with both the high-cycle fatigue (HCF) and low-cycle fatigue (LCF), i.e., the effective notch strain approach [17] and the structural strain approach [18], were actually employed. The results of the two specimens offer a valuable opportunity to verify the two approaches in cases of significant fatigue loadings.

The study is organised as follows. The effective notch strain approach and structural strain approach are introduced in Section 2. Section 3 describes the details of the experiments. The linear elastic finite element analyses were conducted in Section 4. The results are shown in Section 5. The conclusions are summarized in Section 6.

2 Methodology

2.1 Effective Notch Strain Approach

The effective notch stress approach assumes that the average notch stress in a line segment around the notch root controls the fatigue strength and can be simulated by the maximum stress of a corresponding notch with an enlarged fictitious radius [19]. A fictitious notch radius of 1 mm corresponds to the worst-case scenario (zero actual notch radius) for welded steel structures thicker than 5 mm, as illustrated in Fig. 1 [16]. As a consequence, the stress singularity that occurs when the actual notch radius is zero can be circumvented. At present, the effective notch stress approach has been incorporated into the recommendations issued by the International Institute of Welding (IIW) for the fatigue design of welded joints [16]. Typically, the FE method is employed to calculate the effective notch stress.

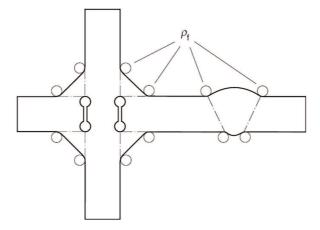


Figure 1: Fictitious notch rounding [16]

The effective notch strain method has been successfully applied to LCF [20], demonstrating its effectiveness for load-carrying cruciform joints [21]. Fricke et al. [22] adopted this approach to assess the LCF performance of welded joints in marine structures. Dong et al. [17] employed the equivalent strain energy density method as an alternative to elastic–plastic finite element analysis and applied this method to the single-sided girth welds of pipelines, in which the plastic behaviour of the weld root was investigated for a study case to justify the use of low-cycle fatigue assessment approaches [23]. Unlike conventional notch strain methods, the effective notch strain approach does not require precise local geometric details or residual stress data, and it predicts total fatigue life rather than only crack initiation life. The procedure begins with determining the effective notch stress.

In the subsequent step, the equivalent strain energy density method is employed to convert the elastic stress into elastic-plastic strain, based on the assumption of a plane strain state [24,25]. A biaxial stress condition exists at the notch root under remote loading, with the strain component parallel to the weld seam constrained to zero. The material's cyclic response is herein described by the uniaxial Ramberg-Osgood relation:

$$\varepsilon = \frac{\sigma}{E} + \left(\frac{\sigma}{k'}\right)^{\frac{1}{n'}} \tag{1}$$

where k' is the cyclic strength coefficient, n' is the cyclic strain hardening exponent, and E is the elastic modulus. According to [26], the above curve should be transformed into the plane strain curve by using:

$$\begin{cases}
\sigma_{1} = \frac{\sigma}{\sqrt{1 - \mu + \mu^{2}}} \\
\varepsilon_{1} = \frac{\varepsilon \left(1 - \mu^{2}\right)}{\sqrt{1 - \mu + \mu^{2}}} \\
\mu = \frac{1}{2} - \left(\frac{1}{2} - \nu\right) \frac{\sigma}{E\varepsilon}
\end{cases} \tag{2}$$

where stress and strain with a subscript 1 represent the first principal quantities, ν is Poisson's ratio, and μ is the generalized Poisson's ratio. The data points in the uniaxial cyclic stress-strain curve can be transformed into the data points of $(\sigma_1, \varepsilon_1)$. The plane strain curve can be fitted based on these data points, and the plane strain curve is in the form of:

$$\varepsilon_1 = \frac{\sigma_1}{E} \left(1 - \nu^2 \right) + \left(\frac{\sigma_1}{k_1'} \right)^{\frac{1}{n_1'}} \tag{3}$$

where k'_1 and n'_1 are the new material properties. The plane strain equivalent strain energy density approach can be expressed by:

$$\frac{\sigma_{eff}^2 \left(1 - v^2\right)}{2E} = \int_0^{\varepsilon_1} \sigma_1 d\varepsilon_1 \tag{4}$$

where σ_{eff} is the effective notch stress (first principal stress). The first principal notch strain ε_1 can be solved by combining Eqs. (3) and (4). The generalised Poisson's ratio μ can also be obtained. According to Eq. (2), the effective notch strain can be estimated by:

$$\varepsilon_{eff} = \frac{\varepsilon_1 \sqrt{1 - \mu + \mu^2}}{(1 - \mu^2)} \tag{5}$$

Generally, the effective notch strain range is of interest in assessing fatigue strength. The effective notch strain amplitude ε_{eff} is obtained by solving Eqs. (3)–(5), in which the σ_{eff} is the effective notch strain range is twice the effective notch strain amplitude.

The curves of the effective notch strain range $\Delta \varepsilon_{eff}$ vs fatigue life N for a survival probability of 97.7% can be expressed by:

$$\begin{cases} N_f \left(\Delta \varepsilon_{eff} \right)^{m_1} = C_1 N_f < 10^4 \\ N_f \left(\Delta \varepsilon_{eff} \right)^{m_2} = C_2 N_f \ge 10^4 \end{cases}$$
(6)

The segment of $N_f < 10^4$ is derived from the LCF test data [21], and the segment of $N_f \ge 10^4$ is derived from the S-N curve of FAT225 for the effective notch stress approach [16]. The relationship between the effective notch strain range and effective notch stress range in the elastic domain is:

$$\Delta \varepsilon_{eff} = \frac{\Delta \sigma_{eff} \sqrt{1 - \nu + \nu^2}}{E} \tag{7}$$

The values of S-N curve parameters in HCF and LCF regimes can be found in [16].

2.2 Structural Strain Approach

The mesh-insensitive structural stress method was initially introduced for assessing weld toe fatigue in the HCF range. It utilizes a reliable structural stress calculation technique that addresses the mesh size dependency issue commonly seen in the hot-spot stress approach, Additionally, it employs a unified master S–N curve derived from extensive fatigue test data covering diverse joint configurations, loading conditions, thicknesses, and other variables [15]. ASME has adopted the approach since 2007 [27].

The fatigue strength is assumed to be controlled by the through-thickness linearly distributed stress, composed of the membrane and bending components, which fulfil the requirements of the equivalent equilibrium condition. For 4-node shell elements, the nodal forces are converted into line forces using a matrix, resulting in mesh-insensitive structural stresses. In the present study, the 20-node hexahedral elements were used. The method described in [27], based on nodal forces, is employed to calculate the structural stresses.

Dong [15] proposed an equivalent structural stress concept, which consolidates a large number of fatigue test data into a single, narrow band known as the master S-N curve. This equivalent structural stress is a stress metric grounded in fracture mechanics theory, taking into account critical factors directly influencing fatigue life. The equivalent structural stress range (ΔS_s) is defined as:

$$\Delta S_s = \frac{\Delta \sigma_s}{t^* \frac{2-m}{2m} \cdot I(r)^{\frac{1}{m}}} \tag{8}$$

where $\Delta \sigma_s$ is the structural stress range, $t^* = t/t_{ref}$ with $t_{ref} = 1$ mm, m is 3.6, and I(r) is a dimensionless polynomial function of the bending ratio r (under load-controlled conditions):

$$I(r)^{\frac{1}{m}} = 0.0011 \cdot r^6 + 0.0767 \cdot r^5 - 0.0988 \cdot r^4 + 0.0946 \cdot r^3 + 0.0221 \cdot r^2 + 0.014 \cdot r + 1.2223$$
(9)

where

$$r = \frac{|\Delta \sigma_b|}{|\Delta \sigma_m| + |\Delta \sigma_b|} \tag{10}$$

The master S-N curve is given in the form of:

$$\Delta S_s = C N_f^{-h} \tag{11}$$

where *C* and *h* are the S-N curve parameters, and the values can be found in [28].

2.2.1 Pseudo-Elastic Structural Stress Calculation

Dong et al. [18] extended the structural stress method to encompass the LCF regime, leading to the development of the structural strain approach. Structural strain is obtained from elastic structural stress and can be computed analytically, relying on assumptions of a linear deformation distribution across the thickness and elastic-perfectly plastic material behaviour. Recently, the structural strain approach was further developed by Pei and Dong [29] to consider the effect of the material's nonlinear strain hardening behavior and the plane strain state. The structural strain can only be solved by a numerical approach [29].

In the present study, the structural strain approach proposed in [18] is still used to simplify the analyses. Instead of using a structural strain, a pseudo-elastic structural stress is calculated to determine the equivalent structural stress. The approach is described as follows.

After computing the elastic structural stress, two scenarios are taken into account: one involves bending-dominated loading, where plastic deformation occurs at both plate surfaces; the other involves membrane-dominated loading, with plastic deformation at just one plate surface. For the first case, the shift of the neutral axis towards the compression side e and the size of the elastic core c can be calculated by:

$$c = t\sqrt{3\left[1 - \left(\frac{\sigma_m}{S_Y}\right)^2 - \frac{2\sigma_b}{3S_Y}\right]} \tag{12}$$

$$e = \frac{\sigma_m t}{2S_V} \tag{13}$$

where S_Y represents the material's yield strength and t is the plate thickness. This elastic core then dominates the bending curvature 1/R of the member:

$$\frac{1}{R} = \frac{2S_Y}{cE} \tag{14}$$

Accordingly, the structural strains at the outer (0) and inner (i) surfaces are determined by the curvature and the distance to the neutral axis:

$$\varepsilon_0 = \frac{1}{R} \left(e + \frac{t}{2} \right) \tag{15}$$

$$\varepsilon_i = \frac{1}{R} \left(e - \frac{t}{2} \right) \tag{16}$$

Ultimately, the pseudo-elastic structural stresses employed for evaluating fatigue damage are derived by multiplying the structural strains with Young's modulus *E*:

$$\sigma_m' = \frac{E\sigma_m t}{RS_Y} \tag{17}$$

$$\sigma_b' = \frac{tE}{2R} \tag{18}$$

If the membrane stress is relatively high, plastic deformation may only occur near the outer surface. The elastic core size *c* can be expressed as:

$$c = \frac{t}{2} \left(\frac{3S_Y - 3\sigma_m - \sigma_b}{S_Y - \sigma_m} \right) \tag{19}$$

resulting in a curvature of bending as:

$$\frac{1}{R} = \frac{8\left(S_Y - \sigma_m\right)^3}{tE\left(3S_Y - 3\sigma_m - \sigma_b\right)^2} \tag{20}$$

Then, the structural strains at the outer and inner surfaces have the following expressions:

$$\varepsilon_0 = \frac{S_Y}{E} + \frac{(t - c)}{R} \tag{21}$$

$$\varepsilon_i = \frac{S_Y}{E} - \frac{c}{R} \tag{22}$$

The pseudo-elastic structural stresses become

$$\sigma_m' = S_Y + \frac{E}{2R} \left(t - 2c \right) \tag{23}$$

$$\sigma_b' = \frac{tE}{2R} \tag{24}$$

The criterion to distinguish between the two cases can be found in [30]. The above formula can be readily extended to plane strain by substituting the material yield strength with the effective yield stress.

$$S_Y' = \frac{S_Y}{\sqrt{1 - \nu + \nu^2}} \tag{25}$$

If von Mises' yield criterion is used, and replacing Young's Modulus E by

$$E' = \frac{E}{1 - \nu^2} \tag{26}$$

2.2.2 Weld Root Fatigue

When it comes to weld root fatigue, the focus is on the structural stress at the critical section. Wei et al. [31] put forward an analytical method to calculate the structural stress at the weld root of load-carrying cruciform welded joints, taking weld geometry effects into account. The angle of the cracking plane and the traction stress acting on it can be determined by analyzing the forces at a reference plane and applying equilibrium conditions. It is assumed that the cracking plane corresponds to the location where the traction stress attains its maximum value. Studies on load-bearing cruciform joints reveal that when the traction stress, denoted as σ'_s , reaches its peak, the cracking plane angle θ (measured from the non-loaded plate surface) is roughly 20°, and the shear stress τ'_m at this plane is approximately zero.

In this study, attention is focused on the weld root of the fillet weld connecting the stiffener and the shell. The weld penetration is usually uncertain [18], a conservative assumption of zero penetration depth is made, although the actual depth is typically greater than zero. The plate surface of the stiffener is considered the reference plane, i.e., plane OA shown in Fig. 2, because the shell plate is curved, which imposes difficulties in extracting the nodal forces. The potential crack is assumed to be initiated from the corner of the stiffener, i.e., point *O*. As a result, the gap between the stiffener and shell, *g*, is not explicitly involved in the structural stress of the potential crack plane.

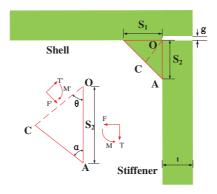


Figure 2: Analytical model for weld root cracking

The flank angle of the weld toe, α , can be calculated as:

$$\alpha = \arctan\left(\frac{S_1}{S_2}\right) \tag{27}$$

where S_1 and S_2 represent the lengths of the weld legs on the two respective plate surfaces.

Based on the equilibrium conditions, the membrane stress, bending stress and the structural stress at a plane that rotates a degree of θ from the reference plane, plane OC as shown in Fig. 2, can be obtained by:

$$\sigma_m = (\sigma_{mr}\cos\theta - \tau_{mr}\sin\theta) \frac{\sin(\alpha + \theta)}{\sin\alpha}$$
(28)

$$\sigma_b = 3 \left[\sigma_m - \sigma_{mr} \left(\frac{\sin \left(\alpha + \theta \right)^2}{\sin \alpha} \right) \right] + \sigma_{br} \left(\frac{\sin \left(\alpha + \theta \right)^2}{\sin \alpha} \right)$$
 (29)

$$\sigma_s = \sigma_m + \sigma_b \tag{30}$$

where σ_{mr} , σ_{br} , and τ_{mr} represent the membrane stress, bending stress, and shear stress of plane OA, and σ_{mr} , σ_{br} , and σ_{sr} are the membrane stress, the bending stress and the structural stress of plane OC.

The critical angle θ_c of the potential crack plane on which σ_s becomes maximum can be analytically derived as:

$$\theta_c = \frac{1}{2} \left[\arctan\left(A\right) - \alpha \right] \text{ for } A \ge 0$$
(31)

$$\theta_c = \frac{1}{2} \left[\pi + \arctan(A) - \alpha \right] \text{ for } A < 0$$
(32)

in which

$$A = \tan\left(2\theta_c + \alpha\right) = -\frac{\left(\sigma_{mr} + \sigma_{br}\right)\sin\alpha}{\left(\sigma_{br} - 3\sigma_{mr}\right)\cos\alpha - 4\tau_{mr}\sin\alpha} \tag{33}$$

3 Specimen and Test Results

The specimens experimentally investigated by Papatheocharis et al. [13] were reanalysed in the present study. As depicted in Fig. 3, the specimen consisted of tubular braces fully penetrated and welded to the shell's outer surface, complemented by internal longitudinal stiffeners (L80 \times 8) and ring stiffeners (80 \times 8 mm plates) fillet-welded to the shell interior. Due to incomplete penetration of the stiffener-to-shell welds, the weld root exists in the specimens. The specimen material is S355JR steel, with eight specimens used for fatigue tests. These specimens are divided into two types: (a) as-welded specimens (Type-A); and (b) specimens treated with high-frequency mechanical impact (HFMI) post-welding (Type-B). While HFMI post-weld treatment was applied to five specimens to reduce local residual tensile stresses, the study lacks detailed data on the precise treatment location and geometric distinctions between type-A and type-B specimens.

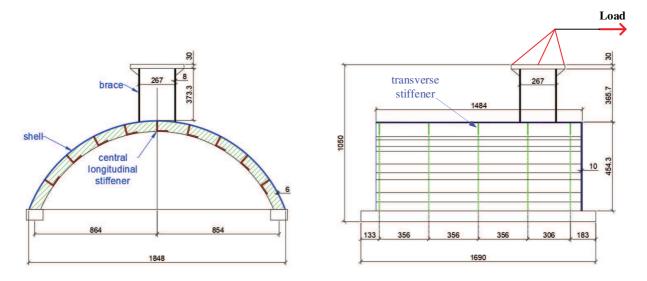


Figure 3: Specimen configuration and dimensions (in mm)

Constant-amplitude fatigue loading tests were performed on the specimens. The cyclic load was horizontally applied to the brace end using a hydraulic actuator, which was connected to the brace through a hinged joint. Meanwhile, the curved shell was secured to the testing floor with two steel support beams via bolting. Four load ranges ($\Delta P = P_{\text{max}} - P_{\text{min}}$) have been applied with a loading ratio of $R = \frac{P_{\text{min}}}{P_{\text{max}}} = 0.10$.

Table 1 summarises the applied fatigue loadings and corresponding test results. Both *in-situ* observations during testing and post-test fractographic analysis revealed two primary fatigue crack initiation sites: the

brace-to-shell crown and the central longitudinal stiffener underneath the crown location. These critical locations are explicitly identified in Fig. 4. These locations are:

- Location 1: Weld root of the fillet weld of the central longitudinal stiffener to the shell.
- Location 2: Weld toe of the fillet weld of the central longitudinal stiffener to the shell.
- Location 3: Weld root of the brace-to-shell weld.
- Location 4: Weld toe of the brace-to-shell weld.

Table 1: Fatigue loadings and test results

Specimen	Type of weld	Load range kN	Number of load cycles to failure N _f	Possible crack initiation location
WTJ-8	45	69,650	3	
WTJ-9	27	304,595	3	
WTJ-10	22.5	660,017	3	
WTJ-3	type-B (HFMI treated)	90	3394	2, 4
WTJ-4		45	55,605	1, 2, 3
WTJ-6		27	814,931	2, 3
WTJ-5		22.5	782,955	1, 2, 4

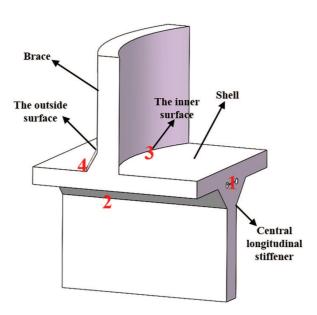


Figure 4: Critical location of the specimen

The specimens exhibited complex behaviour in terms of crack initiation and propagation. All Type-A specimens developed through-thickness cracks at the main brace-to-shell crown connection. Specifically, specimen WTJ-7 showed crack initiation at Locations 2 and 4, while other Type-A specimens primarily initiated cracks at Location 3 and propagated through the thickness of the shell. For Type-B specimens, fatigue cracks consistently initiated at both the brace-to-shell crown and the central longitudinal stiffener's

fillet weld. Crack initiation sites varied among Type-B specimens: Locations 3 for WTJ-4 and WTJ-6, and Location 4 for WTJ-3 and WTJ-5. Note that fractographic analysis, conducted only on WTJ-4 and WTJ-5, revealed Location 1 as a potential additional initiation site, suggesting similar behaviour may exist in other specimens.

4 Finite Element Modelling

The FE method was utilized to compute the linear elastic local stresses for evaluating fatigue strength. To improve the efficiency of the FE analyses, the sub-model technique was adopted, given the necessity for a fine mesh in critical areas. This section presents an overview of both the global FE model and the sub-models.

The FE analyses were performed using the commercial software ANSYS Workbench. The global FE model was constructed using 8-node shell elements (SHELL281) to represent the main structure, whereas the hydraulic actuator was modeled as a rigid rod with LINK180 elements. The mesh configuration and boundary conditions of the model are depicted in Fig. 5. The left end of the rigid bar (designated as reference point RP-1) is linked to the upper plate of the support through a revolute joint, replicating the hinge in the experimental setup and ensuring kinematic coupling. The loading applied was a static horizontal load, used at the right end of the rigid rod (RP-2). The boundary conditions specified that the bottom of the curved shell was fully restrained, whereas both RP-1 and RP-2 were allowed to move only horizontally. The mesh size was uniformly set at 8 mm based on a comprehensive convergence study. The material was modelled as linear elastic with Young's modulus of 210 GPa and Poisson's ratio of 0.3. The relationship of the load and horizontal displacement at RP-2 was obtained from the global FE model, and compared with the numerical results obtained from previous studies [13], as shown in Fig. 5b. It can be seen that the agreement is good and the global FE model is validated.

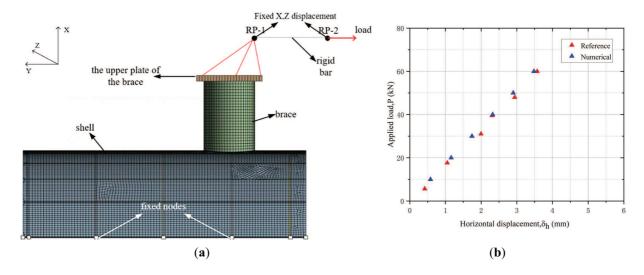


Figure 5: (a) Mesh and boundary conditions of the global model, and (b) Load-displacement data obtained from global FE model and the FE model from previous study [13]

The sub-model technique was adopted to enable a higher-fidelity representation of critical regions. The geometry of the model was based on experimental specimens, with the weld locations and weld leg lengths being consistent with the experimental setup. The 20-node quadratic solid elements (SOLID186) were used to avoid shear lock. The weld geometry was explicitly defined. The weld leg lengths of the brace-to-shell weld and the stiffener-to-shell fillet weld are assumed to be $L_1 = L_2 = S_1 = S_2 = 8$ mm, as shown in Fig. 6. The gap size between the longitudinal stiffener and the shell is assumed to be 0.4 mm.

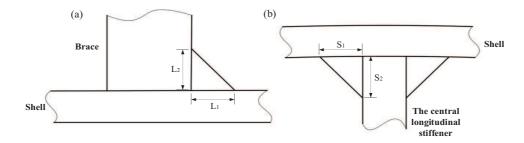


Figure 6: Weld leg length: (a) Brace-to-shell weld, and (b) The stiffener-to-shell fillet weld

The mesh conditions of the sub-model are different for the determination of the two types of local stresses. For the determination of the effective notch stresses, fictitious notch radii were incorporated at four critical locations, as shown in Fig. 7. According to IIW guidelines [16], the mesh size at both the weld toe and root notch regions was refined to be less than 0.25 mm.

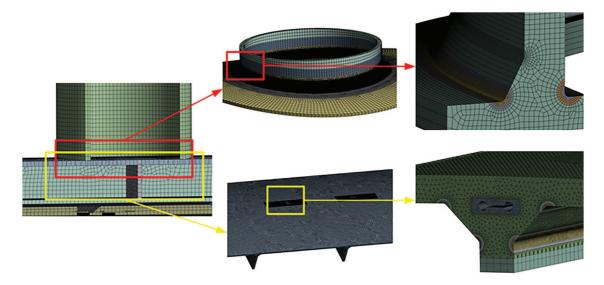
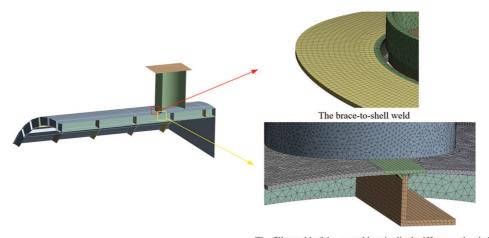


Figure 7: Mesh conditions of the sub-model for the determination of the effective notch stress

The mesh conditions for the sub-model used to determine structural stress are illustrated in Fig. 8. The nodal forces on the potential crack path (or the reference plane for weld root fatigue) were extracted to calculate the structural stresses. The reference plane for location 1 is the surface of the stiffener, i.e., OA in Fig. 2. The potential crack path for location 2 crosses through the stiffener thickness at the weld toe. The potential crack paths for locations 3 and 4 cross through the shell thickness at the weld root and toe, respectively. Along the potential crack path, the mesh size was set to 2-3 mm to ensure at least three layers of elements.



The fillet weld of the central longitudinal stiffener to the shell

Figure 8: Mesh conditions of the sub-model for the determination of the structural stress

Despite the HFMI treatment of Type-B specimens, the FE modelling approach treated all specimens identically, as no published data were available to quantify the treatment's influence on the geometry.

5 Fatigue Strength Assessment

5.1 Effective Notch Strain Approach

Fig. 9 presents the effective notch stresses under a load of 13.5 kN horizontally applied at RP-2 as shown in Fig. 5a. The results indicate that the maximum notch stress occurs at the weld root of the stiffener-to-shell fillet weld (Location 1). Secondary stress concentrations are found at the fillet weld toe (Location 2). The brace-to-shell weld toe (Location 4) and the brace-to-shell weld root (Location 3) correspond to the third and fourth highest stresses, respectively. This distribution suggests that, under idealised conditions (e.g., defect-free welds), the fillet weld between the central longitudinal stiffener and the shell is the most likely site for fatigue crack initiation. Due to geometric constraints, direct monitoring of Location 1 during fatigue testing was not feasible. Fractographic examinations of two representative specimens nevertheless confirmed crack initiation at this critical location.

It can be observed that the critical location for the stiffened tubular joint is not the brace-to-shell weld, which is a key concern for the fatigue strength of its traditional unstiffened counterpart. Neglecting stress concentrations beneath the shell surface may lead to non-conservative estimates of fatigue strength.

Notably, crack initiation was observed at Location 3, even though it ranked lowest in effective notch stress among the four monitored sites. This unexpected outcome is attributed to local weld imperfections: whereas the FE model assumed an idealised 90° notch opening angle, the experimental specimens exhibited sharper notches with smaller angles, likely caused by overlap defects, as shown in the figures provided in [13]. These geometric discrepancies underscore the crucial role of weld root geometry in determining fatigue performance.

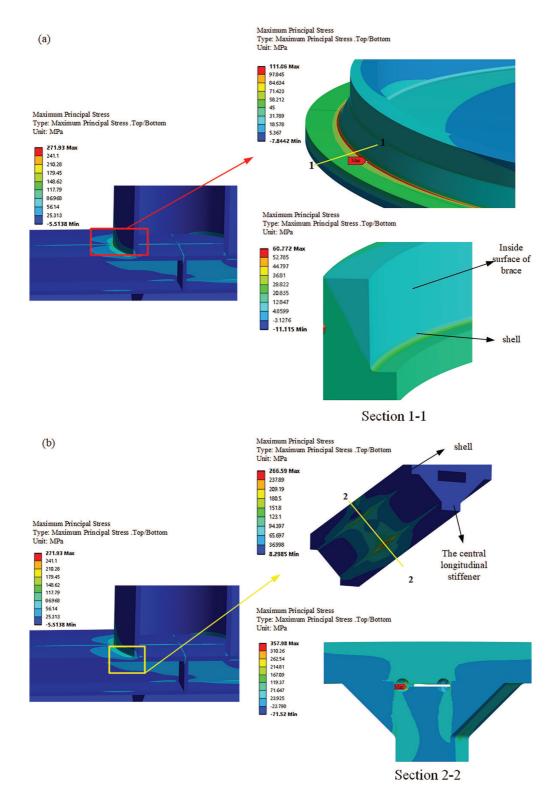


Figure 9: Effective notch stresses around the critical locations: (a) Brace-to-shell weld, and (b) Weld of the fillet weld of the central longitudinal stiffener to the shell

The effective notch stress approach is validated in the HCF regime ($N > 10^4$ cycles). the fatigue strength of specimens WTJ-3 and WTJ-7 cannot be evaluated using the method. Instead, the effective notch strain approach, outlined in Section 2, was utilized to assess the fatigue strength of the stiffened tubular joints. The benefit of employing the effective notch strain approach lies in its ability to evaluate fatigue strength across both LCF and HCF regimes. To convert elastic stresses into elastic-plastic strains, the cyclic stress-strain curve of the material at the crack initiation site is necessary. For evaluating the fatigue strength of welded joints, the material in the heat-affected zone (HAZ) or weld metal (WM) is generally more appropriate. In this study, the cyclic stress-strain curves for the base metal (BM) and HAZ of S355NL determined by Kucharczyk et al. [32] were utilized, as depicted in Fig. 10.

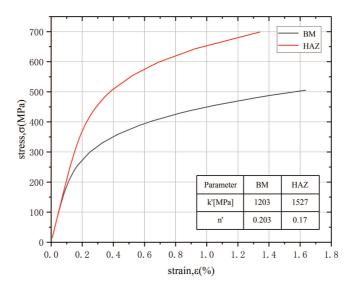


Figure 10: Cyclic stress-strain curves of BM and HAZ for S355NL steel [32]

The effective notch strain ranges are plotted alongside the fatigue test results in Fig. 11, together with the effective notch strain-life curves outlined in Section 2.1.

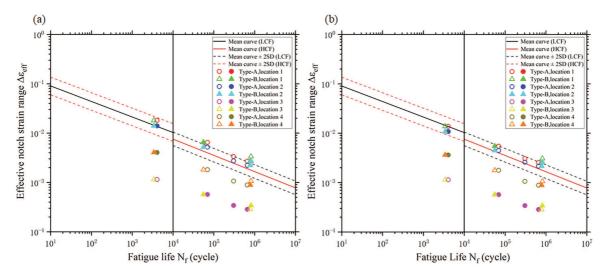


Figure 11: Effective notch strain determined assuming (a) BM and (b) HAZ against fatigue life along with the S-N curves [16] (Filled marks represent the data points where experimental crack initiation took place)

Data points associated with locations 1 and 2 consistently lie above the mean-2SD curve, demonstrating the validity of the effective notch strain method in evaluating the fatigue strength of the stiffened tubular joint. The effective notch strain approach effectively evaluates the fatigue strength of the stiffened tubular joint, as evidenced by the fact that the data points representing the maximum effective notch strain among all four critical locations lie above the strain-life curves.

When the effective notch stress is considerable, the influence of the material on the effective notch strain estimation becomes apparent. The effective notch strains for locations 1 and 2 under fatigue loading of 45 and 90 kN, based on the BM assumption, are evidently higher than those based on the HAZ assumption. The reason is that the BM shows more significant plasticity under high stresses, as shown in Fig. 10. For welded joints, selecting the material with the lowest yield strength among the BM, WM, and HAZ provides a conservative estimate of fatigue strength.

5.2 Structural Strain Approach

The linear elastic structural stresses were also calculated for the four critical locations. The potential crack plane at location 1 and the corresponding structural stresses were determined using the method introduced in Section 2.2.2. It has been shown that the critical angle of the potential crack plane with respect to the reference plane is approximately 67°, which is consistent with the results of load-carrying welded cruciform joints analysed by Wei [31]. The structural stresses of other locations were calculated at the assumed potential crack plane. The structural stress analysis yielded the same ranking of stress magnitudes at the four critical locations as the notch stress results. The consistency further confirms that the fillet weld between the central longitudinal stiffener and the shell is the preferred site for fatigue crack initiation.

The pseudo-elastic structural stress was calculated when the linear elastic structural stress exceeded the yield stress of the BM, assuming a plane strain state. The applied load is the amplitude of the cyclic loads. The yield stress in plane strain state is 438 MPa according to Eq. (24), based on the uniaxial yield stress of 390 MPa reported by Papatheocharis et al. [13].

The equivalent structural stress ranges for the four critical locations are plotted against the experimental fatigue lives along with the master S-N curves, as shown in Fig. 12. For the cases with $\Delta P = 90 \, \text{kN}$, the structural stress at the weld root of the fillet weld between the central longitudinal stiffener and the shell failed to result in a reasonable elastic core size. It indicates that the weld root is subjected to plastic collapse under a significant load. The pseudo-elastic structural stress at the weld root approaches infinity. The linear elastic result was still used for this special case.

Similar to the results of the effective notch strain approach, the data points associated with locations 1 and 2 also lie above the mean \pm 2SD curve. The performance of the structural strain approach in evaluating the fatigue strength of the stiffened tubular joint is validated. The structural strain approach is more conservative than the effective notch strain approach because the data points associated with location 1 lie much higher with respect to the S-N curve. One reason is that the elastic and perfectly plastic material behavior is assumed, leading to an overestimation of the equivalent structural stress range. The deviation of the data points associated with location 1 from the S-N scatter band, as shown in Figs. 11 and 12, is caused by the conservative assumption of zero weld penetration depth. As shown in the figures provided in [13], the penetration depth is generally positive and subjected to significant uncertainty. However, the exact value of penetration depth was not reported. Zero weld penetration depth is a relatively conservative assumption.

In previous studies on the effective notch strain approach and structural strain approach, fatigue test data for validating the two approaches were generally obtained from small-scale and straightforward specimens. The present study confirms that the two approaches can be effectively applied to relatively complex specimens

with multiple potential sites for crack initiation. Their residual stress state and weld quality level are similar to those in the actual structures. It brings confidence to the application of these two approaches in the fatigue strength assessment of large-scale and complex welded joints.

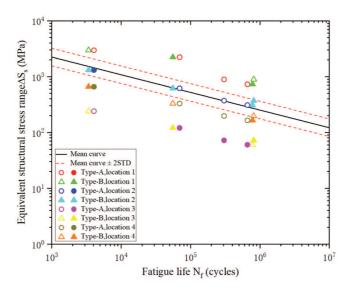


Figure 12: Equivalent structural stress range against fatigue life (Filled marks represent the data points where experimental crack initiation took place)

5.3 Effects of Weld Geometry

To enhance the fatigue performance of stiffened tubular joints, several measures may be implemented, including stricter weld quality control, increased penetration depth of the stiffener-to-shell fillet weld, and optimised weld leg length. These measures may reduce the effective notch stress concentrations at locations 1 and 2, resulting in an improved overall fatigue strength of the tubular joint.

In practice, incomplete weld penetration is usually eliminated because weld root fatigue is more dangerous than weld toe cracks. The fatigue crack initiation from the weld root cannot be detected until it has grown through the entire weld thickness. Most post-weld treatment methods cannot be used to improve the fatigue strength of weld roots.

In the present study, the effect of weld penetration on local stresses and strains is evaluated. With the increase in weld penetration, the local stress and strain at locations 1 and 2 decrease continuously. If the weld root is eliminated, weld root fatigue will not occur, and the most critical location becomes location 2. The fillet weld, without the weld root (i.e., full weld penetration), is modelled to determine the local stresses and strains. The effective notch strain range and the structural stress range at location 2 are compared and shown in Fig. 13. It can be seen that the fatigue strength of the weld toe can be significantly improved by eliminating the weld root. The maximum effective notch strain range is reduced by 24%, and the maximum structural stress range decreases by 28% compared with the model with the weld root. The results demonstrate the effectiveness of eliminating the weld root in improving the fatigue strength of the stiffened tubular joint.

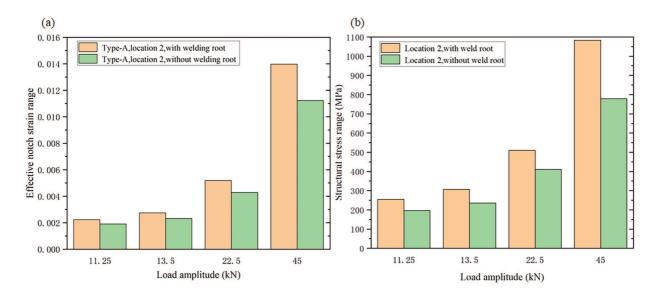


Figure 13: Effect of weld root on (a) Effective notch strain range and (b) Structural stress range of weld toe (location 2)

The effect of weld leg length on local stress is further investigated using the model with full weld penetration. It is assumed that the four weld leg lengths shown in Fig. 6 vary from 6 to 10 mm. Only the structural stress range under the cyclic load of $\Delta P = 90 \, \text{kN}$ was calculated. The results are shown in Fig. 14.

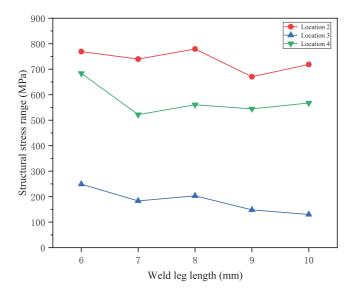


Figure 14: Structural stress range as a function of weld leg length under the cyclic load of $\Delta P = 90 \text{ kN}$

It can be seen that increasing weld leg length from 6 to 10 mm generally reduces structural stresses, indicating improved fatigue resistance. However, the change in the structural stress range of location 2 is not as significant as that of other places. It suggests that increasing the weld leg length at the stiffener-to-shell weld may not be highly effective.

6 Conclusions

- The effective notch strain approach and the structural strain approach are both effective for assessing the fatigue strength of stiffened tubular joints in floating offshore wind turbine platforms. Both methods can address weld toe and weld root fatigue and apply to both LCF and HCF regimes.
- Assuming conservatively zero weld penetration at the stiffener-shell fillet weld, local stress/strain results
 indicated that the weld root of this fillet weld is the most critical site for fatigue crack initiation, which
 is consistent with fractographic analyses conducted on two specimens.
- For the stiffened tubular joints analysed in this study, the stiffener–shell fillet weld is the primary fatigue-critical region, rather than the brace-to-shell weld that is typically of concern in conventional unstiffened tubular joints.
- Although the brace-to-shell weld root exhibits the lowest local stress/strain based on FE analyses, it was also observed as a fatigue-critical location due to poor weld quality. This discrepancy arises from idealisations in FE modelling, highlighting the key role of weld quality in fatigue strength.
- In the LCF regime, material behaviour strongly affects local strain responses. Materials with lower yield strength can be adopted to provide a more conservative fatigue strength assessment.
- The presence of a weld root at the fillet weld significantly increases stress concentrations at both the weld root and toe, thereby reducing overall fatigue resistance. Full weld penetration is an effective measure to improve fatigue strength, whereas further increasing the leg length of fully penetrated fillet welds proves less effective.
- Idealised weld geometries limit the present study. Future work may incorporate more realistic weld profiles and weld quality obtained from experiments to enhance the fatigue strength assessment.

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Ethics Approval: This article is based on previously conducted studies and does not contain any new studies with human participants or animals performed by any of the authors.

Conflicts of Interest: All authors declare that there are no relationships or activities that could have appeared to influence the work reported in this paper.

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