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ARTICLE



Modeling of CO₂ Emission for Light-Duty Vehicles: Insights from Machine Learning in a Logistics and Transportation Framework

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ABSTRACT: The transportation and logistics sectors are major contributors to Greenhouse Gase (GHG) emissions. Carbon dioxide (CO₂) from Light-Duty Vehicles (LDVs) is posing serious risks to air quality and public health. Understanding the extent of LDVs' impact on climate change and human well-being is crucial for informed decision-making and effective mitigation strategies. This study investigates the predictability of CO₂ emissions from LDVs using a comprehensive dataset that includes vehicles from various manufacturers, their CO₂ emission levels, and key influencing factors. Specifically, six Machine Learning (ML) algorithms, ranging from simple linear models to complex non-linear models, were applied under identical conditions to ensure a fair comparison and their performance metrics were calculated. The obtained results showed a significant influence of variables such as engine size on CO₂ emissions. Although the six algorithms have provided accurate forecasts, the Linear Regression (LR) model was found to be sufficient, achieving a Mean Absolute Percentage Error (MAPE) below 0.90% and a Coefficient of Determination (R2) exceeding 99.7%. These findings may contribute to a deeper understanding of LDVs' role in CO₂ emissions and offer actionable insights for reducing their environmental impact. In fact, vehicle manufacturers can leverage these insights to target key emission-related factors, while policymakers and stakeholders in logistics and transportation can use the models to estimate the CO₂ emissions of new vehicles before their market deployment or to project future emissions from current and expected LDV fleets.

KEYWORDS: CO₂ emission; machine learning; modeling; prediction; performance metrics; light-duty vehicles; climate change; transportation and logistics

1 Introduction

1.1 Problem Statement

With the rapid growth of economic and social activities worldwide, Light-Duty Vehicles (LDVs), including vans, pickup trucks, and small delivery vehicles, have become essential for passenger mobility and the sustainable transport of goods [1]. LDVs, typically defined as vehicles with a gross weight rating of 10,000 pounds or less, play a crucial role in logistics and transportation systems. Their importance has grown significantly in response to the rise of e-commerce, particularly in last-mile delivery operations, where timely and high-quality delivery is paramount. However, LDVs are also among the major contributors to air pollution and environmental degradation [2]. Due to their reliance on internal combustion engines



(mainly powered by diesel and gasoline), LDVs emit substantial amounts of air pollutants such as particulate matter (PM2.5 and PM10), carbon monoxide (CO), nitrogen oxide (NOx), unburned hydrocarbons (UHC), and greenhouse gases (CO₂ and N_2O) [3]. In urban areas, where LDVs are heavily utilized, elevated CO₂ emissions, a dangerous Greenhouse Gas (GHG) and a key driver of climate change, demand urgent attention from policymakers and environmental stakeholders [4].

1.2 LDVs' CO₂ Emission Modeling

Modeling and assessing CO₂ emissions from transportation, as an essential step in the decision-making process, presents significant complexity due to the multitude of influencing factors [5,6]. Predictive models for vehicle-related CO₂ emissions can generally be categorized into statistical models and Artificial Intelligence (AI) models. Traditional statistical models, such as Autoregressive-Integrated Moving Average (ARIMA), Seasonal ARIMA with exogenous factors (SARIMAX), and the Holt-Winters model, are typically applied to annual datasets, as they primarily capture long-term trends. In addition, these models require the dataset to be stationary, limiting their flexibility and application [7]. To overcome the limitations of traditional prediction methods, AI techniques have emerged as an efficient tool offering the ability to model processes involving vast amounts of data and detect hidden patterns.

Researchers and practitioners have approached the modeling and prediction of CO₂ emissions released by LDVs from two main perspectives, depending on the datasets used and the prediction/modeling tools adopted. Some studies have focused on vehicle assessment using data collected from Portable Emission Measurement System (PEMS) devices embedded in those vehicles [8]. In contrast, other studies have utilized large-scale compiled at national or international levels, encompassing a wide variety of vehicle types and usage patterns [9]. This latter approach offers the advantage of broader applicability, as similar vehicle models tend to exhibit consistent CO₂ emission patterns across different countries, providing a more generalized understanding of emission behaviors.

In this context, the main aim of the current study is to help fill the applied research gap by analyzing and comparing CO₂ emissions from various LDVs, thereby enhancing understanding of their impact on climate change and environmental issues. By utilizing a large-scale dataset that covers LDVs from different manufacturers and applying multiple ML algorithms under consistent conditions, the study evaluates the predictive accuracy of various models for CO₂ emissions and identifies the most influencing variables. In practice, such a comparative modeling approach is expected to valuable insights into CO₂ emissions across LDV types and support informed decision-making to reduce emissions in the global vehicle market [10].

1.3 Paper Outline

The remainder of this article is organized as follows. Section 2 includes an extensive literature review as well as the contributions of the paper. Section 3 explores the dataset used in addition to its exploratory analysis. Section 4 is allocated to the proposed methodology. In Section 5, the results and their discussion are provided. Finally, Section 6 includes the conclusions of the study and its perspectives.

2 Literature Review

CO₂ emissions from vehicles are classified as among the most significant GHGs and impactful contributors to climate change. Following the Paris agreement, GHG emissions are expected to be reduced by 40%, below 1990 levels by 2030 [11]. Researchers around the world were extensively interested in developing practical models to predict CO₂ emissions as correlated with many attributes, including the fuel type utilized, the engine size, the number of cylinders, etc. In addition, many CO₂ emission related studies were based on individual vehicles and therefore concentrated on immediate attributes, including driver behavior, road

conditions, and climatic factors. However, most studies focused on certain types of vehicles seen in their broader scope. In what follows, the focus will be on the studies that use AI techniques, including the main classes of methods, namely, Machine Learning (ML) and Deep Learning (DL). The focus will therefore be on the study objective, the dataset utilized, the models/methods employed, the achieved performance metrics, as well as their limitations. The main objective of this approach is to be well-situated with the contributions of the current study against existing ones on the same topic. Earlier research efforts on this topic are thoroughly summarized hereafter in Table 1.

Table 1: Literature review summary

Ref.	Objective	Location and dataset	Feature engineering	Methods techniques	Performance metrics	Limitations
[8]	Estimating CO ₂ emissions from light-duty diesel trucks using ML algorithms	The dataset was established using two LDDTs equipped with a PEMS and a GPS (China)	Correlation analysis	LSTM	RMSE and R ²	The dataset is not representative due to limitations in temporal and spatial coverage, as well as insufficient attributes to account for factors influencing emissions.
[9]	Estimating CO ₂ emissions produced by LDVs using ML algorithms	The dataset of 7384 cars gathered by the Chinese government between 2018 and 2022 (China)	Correlation analysis	Catboost (primary) compared with Gradient Boosting and LightGBM with Ridge Regression as a baseline	RMSE, MSE, MAE and R ²	The dataset is not representative due to limitations in the diversity of vehicle types, fuel consumption patterns, geographic regions, and temporal contexts.
[12]	Estimating CO ₂ emissions in Türkiye's transportation sector using ML algorithms	The dataset is collected form Türkiye's transportation sector between 1970 and 2016 (Turkey)	Correlation analysis	MLP, XGBoost, and SVM	RMSE, MSE, MAE and R ²	Study focused on a unique country using limited-size dataset (47 observations) known to be not well-suited to data-demanding ML algorithms.
[13]	Development and evaluation of an LSTM model for estimating the instantaneous CO ₂ emissions of taxicabs	One-day taxicab dataset collected using a PEMS device (Wuhan, China)	Correlation analysis between CO ₂ emission and driving conditions	LSTM DL algorithm	RMSE	Lack of generalizability since applied to specific vehicles under particular driving conditions.
[14]	Estimating CO ₂ emissions in HVs using traditional and advanced ML algorithms	The dataset comprises various parameters collected by CO ₂ sensors and vehicle's electronic control units. A total of 70,683 samples were collected from 235 min of driving was used to build the models (UK)	Correlation analysis	LR, RF, XGBoost, ANN, LSTM, and New LSTM-based model	Adjusted R ² , MAE, MSE, and RMSE	Case sensitive since it was applied to a specific case study. The accuracy of the sensors may be a limitation.

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Ref.	Objective	Location and dataset	Feature engineering	Methods techniques	Performance metrics	Limitations
[15]	Developing an enhanced road vehicle emission model via the integration of ML with MOVES (a simulator for assessing GHGs emission) for improving the NO and CO ₂ emissions' prediction accuracy of LDGVs in China	The dataset is established from three LDVs (China)	Feature Selection approach	RF	R ² and RMSE	Difficulty in adapting MOVES simulator to the case study of China since it was designed for USA conditions.
[16]	Estimating CO ₂ concentration to support vehicle certification process by the specialized agencies	Dataset collected from a VCA in UK	Heatmap correlation matrix	Various Regression models	MAE, RMSE, MSE and MAPE	Model features are relatively limited (Engine power, fuel consumption and engine capacity).
[17]	Forecasting of transportation CO ₂ emission explained by socio-economic inputs	Annual data of socio-economic factors influencing CO ₂ emission covering 30 countries classified into 3 classes	Pearson correlation analysis	SVM, GBR	MAE, nRMSE, MAPE and R ²	Nonlinear correlation not considered and limited dataset.
[18]	Prediction of real-driving emission of two commercial vehicles using XG-Boost ML algorithm	Data collected from real-time driving scenarios of 3.5-ton and 25-ton vehicles (Korea)	Correlation analysis between the output (CO ₂ emission) and inputs like engine load, engine speed, vehicle speed, etc.	XGBoost ML algorithm	R ² , RMSE and MAPE	The study is based on specific vehicles under particular conditions.
[19]	Use of three ML algorithms for modeling CO ₂ emissions of vehicles equipped with start-stop technology and OBD II system	3000 records from a real-time (velocity, acceleration and instantaneous CO ₂ emission) test on a vehicle under various scenarios (Poland)	No information provided	Linear regression, random forest and Gradient Boosting algorithm	R ² and MSE	The main limitation of the work is that the model was developed based only on the data of a unique vehicle equipped with start-stop technology which may not reflect the real-world situation.

Note: DTs: Decision Trees; GPS: Global Positioning System; GBR: Gradient Boosting Regressor; HVs: Hybrid Vehicles; K-nn: K-nearest neighbors; LDDTs: Light-Duty Diesel Trucks; LSTM: Long Short-Term Memory; LDVs: Light-Duty Vehicles; LDGVs: Light-Duty Gasoline Vehicles; LightGBM: Light Gradient Boosting Machine; ML: Machine Learning; MLP: Multi-layer Perceptron; MOVES: MOtor Vehicle Emission Simulator; OBD: On-Board Diagnostic; PEMS: Portable Emission Measurement System; RF: Random Forest; SVM: Support Vector Machine; VCA: Vehicle Certification Agency; XGBoost: Extreme Gradient Boosting.

Based on the summarized studies of Table 1, it can be noticed that the problem of CO₂ emission concerns researchers worldwide due to its negative effect on the climate and environment. The conducted studies have comprehensively concentrated on macroscopic and microscopic levels, respectively, considering

thorough datasets collected at national or international levels or vehicle-specific datasets collected through PEMS devices. Among the second class of works, the study in [20] assessed NOx/CO₂ emission under particular driving scenarios. The results were reported to be promising in improving air quality in Wuhan (China). In the same direction, the study carried out in [21] investigated the ability to estimate the CO₂ emissions for two vehicles based on PEMS data and Long Short-Term Memory (LSTM). Although they are relevant to the current topic, the two research works have the limitation of being applied to specific case studies and therefore, they lack generalization ability with case-sensitive findings. Moreover, a few studies have considered annual datasets analyzing the effect of socio-economic factors impacting transportation's CO₂ emission. A common practice was to consider feature engineering based on the well-known Pearson (linear) correlation. Meanwhile, none of the studies have considered nonlinear correlation indices such as Spearman and Kendall. The developed prediction/modeling techniques were found to range from simple regression to sophisticated ML algorithms. The performance indicators obtained were found to be casesensitive depending on the size of the dataset, the techniques/methods employed, and the computational resources. In terms of limitations, the common one was the special cases of particular vehicles' difficulty generalizable to other ones under different conditions. In addition, in most cases, the size of the dataset was limited which may not provide high accuracy when ML/DL algorithms were employed as they are known to be data-hungry. In line with the above literature review, the present paper focuses on the prediction/modeling of LDVs-related CO₂ emissions based on six, complementary, ML algorithms and a comprehensive dataset including several LDVs from various brands and sizes. Therefore, this work aims to fill specific research and methodological gaps in the literature. Specifically:

- 1) Various models for CO₂ emissions worldwide have been investigated in the literature, ranging from simple linear to highly non-linear approaches. This work aims to explore the capabilities of six models, including some additional ones that have not been previously examined.
- 2) Numerous feature engineering techniques combined with data-driven models have been proposed and validated in the literature for predicting CO₂ emissions worldwide, offering comprehensive frameworks for tackling this prediction task. This work seeks to contribute to the body of knowledge by introducing an additional predictive modeling framework that accurately addresses CO₂ prediction. It explores various ML models, ranging from linear to non-linear, that complement those previously studied in the literature, ensuring proper hyperparameter optimization. Additionally, it incorporates linear and non-linear correlation (Spearman and Kendall), evaluates performance metrics, and statistically analyzes the influence of different vehicle attributes on CO₂ emissions.

3 Data Description

The dataset, sourced by¹, has been investigated in this work to address the work's objectives. The dataset was obtained from Kaggle and cross-referenced with the Canadian Government's open data portal. The dataset comprises 7385 vehicles, each with various attributes/features relevant to its specification (e.g., vehicle manufacturer), performance (e.g., number of cylinders), fuel efficiency (e.g., fuel consumption), and environmental impact (e.g., CO₂ emission).

The dataset used in this study represents a wide range of manufacturers and LDV brands commonly used worldwide. Our analysis is based on the assumption that, in general, new LDVs exhibit consistent CO_2 emission behavior regardless of the location/country in which they are operated. As a common practice, after a certain period of use, and subsequently at regular intervals, (depending on the country (regional level) local standards), LDVs undergo inspection, and any violations must be addressed by the vehicle owner according

¹https://www.kaggle.com/datasets/debajyotipodder/co2-emission-by-vehicles (accessed on 03 June 2025)

to the local regulations. Therefore, the dataset is used to model the CO₂ emission levels based on the selected features, assuming that new vehicles have similar emission patterns regardless of location. Local or regional regulations should be applied systematically and regularly after the LDV is being used. Notably, the dataset used in this study contains no missing data.

Note here that the dataset does not include the vehicle usage conditions, such as mileage, road conditions and climate. Although those conditions are known to have a high impact on CO_2 emission and this effect may be explored by collecting real datasets of specific vehicles as carried out in many papers among those we cited in this paper (examples can be found in [12–14]). However, in the current study, this is considered a limitation since it covers only specific vehicles under specific conditions which therefore lacks generalization ability. Meanwhile, our paper covers several brands from many manufacturers while focusing on the technical specifications of the investigated vehicles as well as their effect on CO_2 emission patterns. This may allow far away better generalization. In conclusion, the vehicle usage conditions, and the vehicle technical specifications are conceptually different although tackling the same problem of CO_2 emission.

For clarity, the attributes/features are detailed in Table 2. The fuel consumption in combined conditions represents a standardized approximation of an average driver's typical usage pattern, with a ratio of 55% City and 45% Highway driving.

Attribute/Feature	Notation	Unit	Description
Vehicle manufacturer	V_{Ma}	_	Indicates the vehicle's brand
Vehicle model	V_{Mo}	_	Indicates the vehicle's specific model
Vehicle class	V_C	-	Indicates the vehicle's size/type
Engine size	V_{ES}	L	Indicates the engine's displacement
Number of cylinders	V_{CY}	_	Indicates the engine's number of cylinders
Type of transmission	V_{TR}	_	Indicates the vehicle's gear mechanism
Fuel type	FT	_	Indicates the vehicle's fuel type
Fuel consumption in city	FC_{City}	L/100 km	Indicates the vehicle's fuel consumption in
			urban conditions
Fuel consumption on	$FC_{Highway}$	L/100 km	Indicates the vehicle's fuel consumption at
highway			steady highway speeds
Fuel consumption in	FC_{CCL}	L/100 km	I. di
combined conditions			Indicates the vehicle's fuel consumption
Fuel consumption in	FC_{CCM}	mpg*	considering both city and highway
combined conditions			conditions
CO ₂ emissions	E_{CO_2}	g/km	Indicates the vehicle's the amount of CO ₂
			produced per kilometer

Table 2: List of attributes/features available in the dataset under study

Note: *mpg: miles per imperial gallon.

Among the 12 available attributes/features, there are 5 categorical variables and 7 numerical variables. Specifically, the vehicle manufacturer (comprising 42 unique brands), model (comprising 2047 specific models), class (comprising 16 sizes/types), type of transmission including the number of gears (comprising 27 transmission types), and fuel type (comprising 5 specific fuel types) are categorical variables whereas the remaining 7 are numerical variables, whose values vary based on the nature of each attribute/feature.

For instance, among the available categorical variables, examples include ACURA, AUDI, BMW, VOLVO, and TOYOTA (for the vehicle's manufacturer); ILX, A4, 320i, CAMRY, and S60 (for vehicle's model); COMPACT, MID-SIZE, SUV-SMALL, and FULL-SIZE (for vehicle's class); Automatic with Select Shift (AS), Manual (M), and Continuously Variable (AV), including number of gears (from 3 to 10) (for vehicle's transmission type); and Regular Gasoline (X), Premium Gasoline (Z), and Diesel (D) (for vehicle's fuel type). It is worth mentioning that the categorical attributes were encoded into numeric values using label encoding to ensure compatibility with the ML models used in the subsequent prediction analysis. For clarity, Figs. 1–5 illustrate the distribution of these five categorical variables in order. Although there are 2047 unique vehicle models, only the top 50 most frequent ones are shown in Fig. 2 for better readability.

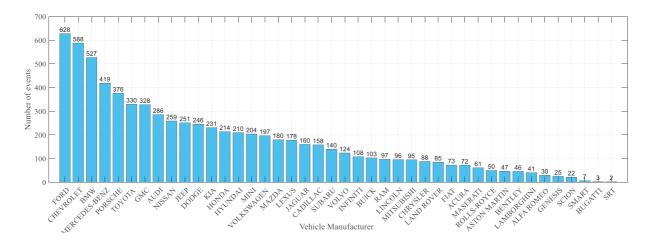


Figure 1: The number of events distributed by vehicle's manufacturer

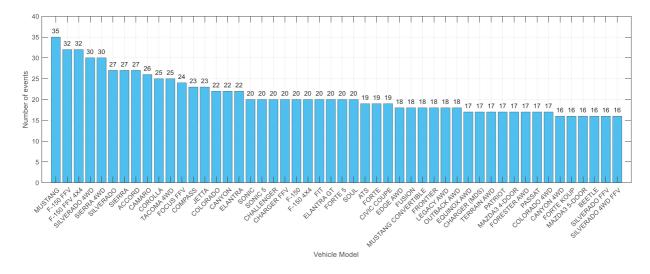


Figure 2: The number of events distributed by vehicle model. The highest 50 events are shown for clarity

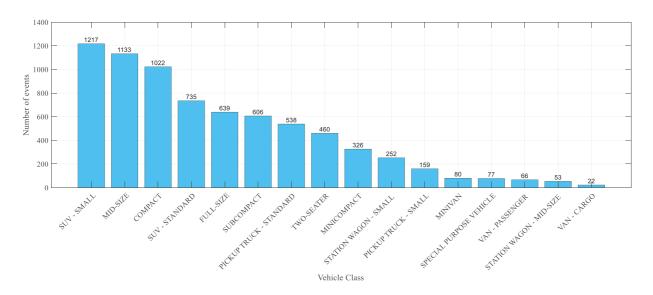


Figure 3: The number of events distributed by vehicle's class

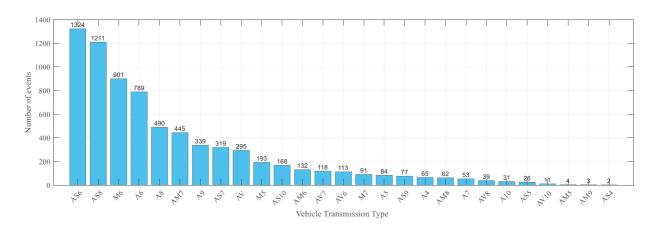


Figure 4: The number of events distributed by vehicle's transmission type

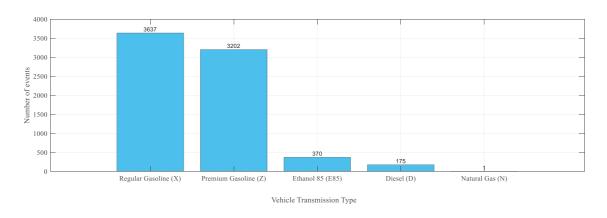


Figure 5: The number of events distributed by vehicle's fuel type

Similarly, among the available numerical variables, the ranges of values include [0.9-8.4] (for engine size), [3-16] (for number of cylinders), [4.2-30.6] (for fuel consumption in city), [4-20.6] (for fuel consumption on highway), [4.1-26.1] (for fuel consumption in combined conditions, measured in L/100 km), [11-69] (for fuel consumption in combined conditions, measured in mpg), and [96-522] (for CO₂ emissions). For clarity, Figs. 6-11 illustrate the histograms of these seven numerical variables in order.

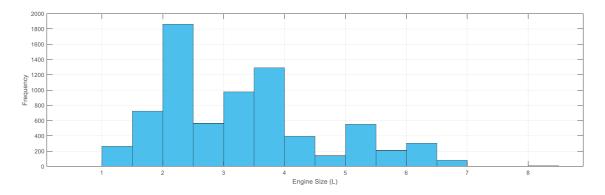


Figure 6: The histogram of the "engine size"

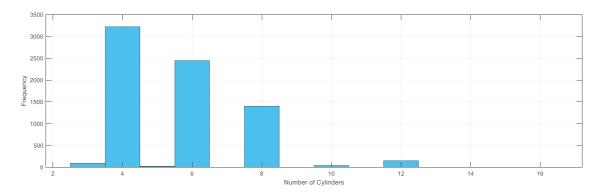


Figure 7: The histogram of the "number of cylinders"

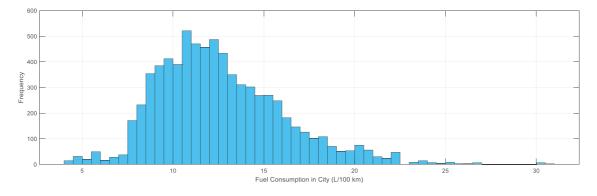


Figure 8: The histogram of the "fuel consumption in city"

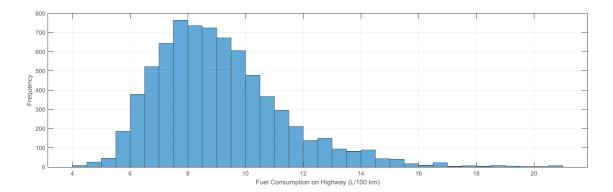


Figure 9: The histogram of the "fuel consumption on highway"

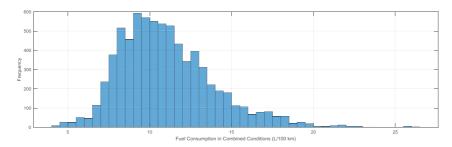


Figure 10: The histogram of the "fuel consumption in combined conditions, measured in L/100 km"

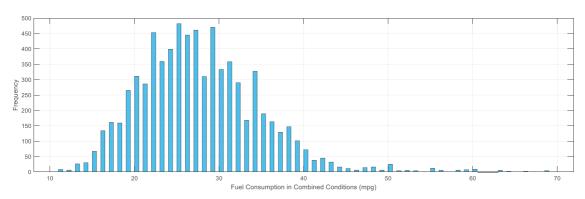


Figure 11: The histogram of the "fuel consumption in combined conditions, measured in mpg"

To effectively present the statistical distribution of the available attributes/features, Fig. 12 illustrates the boxplot of all normalized features in order, including CO₂ emissions. From Fig. 12, it is evident that CO₂ emissions and the corresponding fuel consumption features exhibit significant variability and numerous outliers compared to other features, such as engine size. This indicates potential correlations between CO₂ emissions and other features, which will be explored later in subsequent sections of this work. To effectively address the correlations between variables, outliers were eliminated using the Interquartile Range (IQR) method. Outliers are typically defined as data points that fall below the 1st Quartile (Q1) or above the 3rd Quartile (Q3) by more than 1.5 times the IQR. As a result, 960 data points were excluded from the subsequent analysis, leaving a total of 6425 data points.

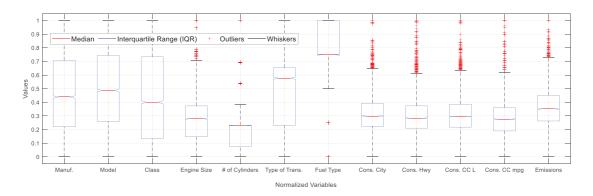


Figure 12: Boxplots of the whole variables in the dataset

4 The Proposed Methodology

This section presents the methodology proposed in this work to develop a predictive model for the CO_2 emissions (g/km) based on the historical recorded vehicle design, models, performance, fuel consumption, and their associated CO_2 emissions of the case under study. The refined version of the dataset, after excluding the 960 outlier data points and transforming the categorical attributes into numeric format, is referred to as $\mathbf{X}_{\text{red}_1}$, with a size of 6425 × 12.

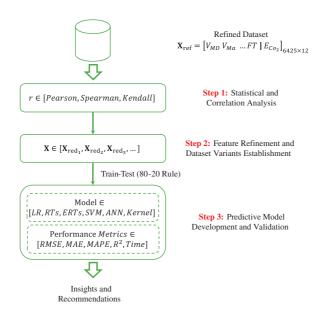


Figure 13: The proposed predictive modelling approach of CO₂ emissions

Specifically, the proposed methodology is structured in three systematic and chronological steps, as depicted in Fig. 13. Specifically, it begins with statistical and correlation analysis to better understand the association levels and impact of each attribute on CO_2 emissions, while also refining the dataset by eliminating potentially redundant or irrelevant features (Step 1). Once these association levels are identified and the dataset is refined, the methodology progresses to establish dataset variants, aiming to comprehensively determine the set of attributes that maximize the predictability of CO_2 emissions (Step 2). To achieve this,

the six investigated ML models are developed and properly optimized using each dataset variant while computing various performance metrics from the literature (Step 3). In detail:

Step 1. Statistical and Correlation Analysis. This step entails statistically analyzing the historically available dataset to better understand the association level and impact of each attribute on CO₂ emissions. To this aim, the distributions of the emissions per unique values of the input attributes are to be identified and the correlation (*r*) between them is to be computed. For this latter, three correlation metrics are employed to compute the association levels with the emissions, aiming to effectively identify the set of attributes that largely affect the CO₂ emissions while developing the predictive models. Specifically, Pearson [22], Spearman [23], and Kendall [24] correlation coefficients are investigated to compute the relationships and gain a comprehensive overview of the interdependencies among the combined categorical and numerical attributes/features. Practically the Pearson correlation is effectively used for numerical attributes in which the relationship is crucial, whereas Spearman and Kendall are more suitable for ordinal data or nonlinear relationships, as they assess the strength and direction of monotonic associations. Last, based on the computed correlation metrics, correlation heatmaps are established to visually interpret the attribute/feature relationships and to initially identify attributes/features exhibiting high multicollinearity, for establishing dataset variants (Step 2) aimed at effective CO₂ emissions prediction (Step 3).

Step 2. Feature Refinement and Dataset Variants Establishment. Once the correlation metrics are computed in Step 1, the established correlation heatmaps are initially used to visually identify and remove highly correlated independent attributes/features from the overall dataset. Subsequently, a Variance Inflation Factor (VIF) analysis is performed on the reduced dataset to confirm that multicollinearity has been effectively eliminated and that the remaining attributes/features offer independent predictive power. Once the refined feature set is finalized, one can establish dataset variants to effectively identify the set of attributes/features that might have an impact on the predictability of CO_2 emissions for any type of vehicle. Specifically, the retained attributes after correlation- and VIF-based filtering are to be used to establish a reduced-version dataset (\mathbf{X}_{red_1}). From this reduced-version dataset, additional reduced-version dataset variants are established by progressively excluding features one by one, i.e., \mathbf{X}_{red_2} , \mathbf{X}_{red_3} , and so on, upon reaching a dataset that contains the attribute of the largest impact on CO_2 emissions. The objective is to establish dataset variants that strike a balance between feature complexity and the predictive performance of CO_2 emissions in the next step (i.e., Step 3). It is worth mentioning that the categorical attributes were converted to numeric indices within each dataset variant to ensure their effective utilization in the ML models' development of of Step 3.

Step 3. Predictive Model Development and Validation. For each established dataset, a set of data-driven models are investigated to accurately estimate the CO₂ emissions based on a set of selected attributes identified in each dataset variant. The models range from simple Linear Regression (LR) models to more advanced non-linear models, including Regression Trees (RTs), Ensemble of Trees (ETs), Kernel Approximation Models (Kernel), Support Vector Machines (SVMs), and Neural Networks (NNs). The models are built while investigating various potential configurations to ensure they have the optimal configuration (i.e., hyperparameters) of each model. That is, the models are optimized in terms of their internal configurations (i.e., hyperparameters), resorting to Bayesian Optimization (BO) optimizer. Specifically, Table 3 summarizes the set of parameters to be optimized while developing the prediction models. The LR models include identifying the best LR scheme among Linear, Interactions, Robust, and Stepwise LR variants. Last, the Regression Learner Application available in MATLAB[®] is being used to devise the models².

²https://www.mathworks.com/help/stats/regression-learner-app.html (accessed on 03 June 2025)

Model	Hyperparameters
RTs	Minimum Leaf Size
ETs	Ensemble Method (Bag and LSBoost) Minimum Leaf Size Number of Learners
E 18	Learning Rate Number of Predictors to Sample
	Learner (SVM and Least Squares Kernel) Number of Expansion Dimensions ([100,
Kernel	10,000]) Regularization Strength (i.e., Lambda) Kernel Scale ([0.001, 1000])
	Epsilon Standardize Data (Yes or No)
SVMs	Kernel Function (Gaussian, Linear, Quadratic, and Cubic) Box Constraint ([0.001,
3 v 1v13	1000]) Kernel Scale ([0.001, 1000]) Epsilon Standardize Data (Yes or No)
	Number of Fully Connected Layers (1, 2, or 3) Layers size ([1, 300]) Activation
NNs	Function (ReLU, Tanh, Sigmoid, and None) Regularization Strength (i.e., Lambda)
	Standardize Data (Yes or No)

Table 3: The set of parameters to be optimized for each prediction model

Each dataset variant is divided following 80–20 rule for the train and test portions. The 80% portion will be subjected to a 5-fold cross validation approach to ensure robustness while developing the prediction models. The 80–20 portions will be the same among the whole dataset variants for a fair comparison with the sole difference in the number of attributes to be used as inputs to the prediction models. Furthermore, the impact of attribute standardization (zero-mean normalization) has also been investigated across the evaluated models.

Further, the models are compared against each other through a set of standard performance metrics, including the Root Mean Square Error (RMSE) (in g/km) (Eq. (1)), Mean Absolute Error (MAE) (in g/km) (Eq. (2)), Mean Absolute Percentage Error (MAPE) (in %) (Eq. (3)), Coefficient of Determination (R²) (in %) (Eq. (4)), and Computational Time (in seconds).

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} \left(E_{CO_2}^i - \hat{E}_{CO_2}^i \right)^2}$$
 (1)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} \left| E_{CO_2}^i - \hat{E}_{CO_2}^i \right| \tag{2}$$

$$MAPE = \frac{100}{n} \sum_{i=1}^{n} \left| \frac{E_{CO_2}^i - \hat{E}_{CO_2}^i}{E_{CO_2}^i} \right|$$
 (3)

$$R^{2} = 1 - \frac{\sum_{i=1}^{n} \left(E_{CO_{2}}^{i} - \hat{E}_{CO_{2}}^{i} \right)^{2}}{\sum_{i=1}^{n} \left(E_{CO_{2}}^{i} - \overline{E}_{CO_{2}} \right)^{2}}$$
(4)

where i is a general index of a validation data point (i = 1, ..., n), n is the total number of validation data points, $E_{CO_2}^i$ and $\hat{E}_{CO_2}^i$ are the actual and estimated i-th CO_2 emission values, respectively, and \overline{E}_{CO_2} is the average value of the actual CO_2 emissions across the validation dataset.

The model's configuration that achieves the best predictability of the CO_2 emissions on the 80% validation portion will be later used to evaluate its goodness and effectiveness on the fixed unseen 20% test portion. Subsequently, insights can be drawn on each model's predictability.

5 Results and Discussion

In this section, the application results of the proposed approach to the case study at hand are presented step-by-step.

The refined dataset that comprises the whole available attributes/features (X_{ref}) of 6425 data points is statistically analyzed and the correlation values between the 11 independent attributes to the CO₂ emissions are computed using the three-correlation metrics being investigated in this work (i.e., Step 1).

The Pearson correlation measures the linear association between individual numeric attributes and CO₂ emissions, while the Spearman and Kendall correlations capture monotonic relationships between the entire set of numeric and encoded categorical attributes and CO₂ emissions. For clarity and conciseness, only the Kendall correlation heatmap is presented in Fig. 14, as the correlation results were found to be largely consistent across all three correlation methods. For reference, the Pearson and Spearman correlation heatmaps are provided in Appendix A. From Fig. 14, one can cite the following insights:

- The Vehicle Manufacturer (V_{Ma}), Vehicle Model (V_{Mo}), Vehicle Class (V_C), and the Number of Transmission (V_{TR}) show very weak correlations with each other and with most other attributes, suggesting that they are largely independent and do not contribute significantly to multicollinearity.
- The Vehicle Engine Size (V_{ES}) and Number of Cylinders (V_{CY}) show moderate correlations with each other, indicating partial redundancy, i.e., mechanical related attributes, with significant contribution to multicollinearity.
- The Fuel Consumption (in City (FC_{City}), on Highway ($FC_{Highway}$), and in Combined Conditions (FC_{CCL} and F_{CCM})) show the highest correlations among each other (i.e., > 0.78), indicating high redundancy, with a significant contribution to multicollinearity.
- The fuel consumption attributes (FC_{CCL} , FC_{CCM} , FC_{City} , and $FC_{Highway}$), followed by Vehicle Engine Size (V_{ES}), Number of Cylinders (V_{CY}), Number of Transmission (V_{TR}), Vehicle Class (V_{C}), Fuel Type (FT), Vehicle Manufacturer (V_{Ma}), and Vehicle Model (V_{Mo}), show varying degrees of correlation with CO₂ emissions, with corresponding Kendall correlation coefficients of 0.9776, -0.9703, 0.9223, 0.8617, 0.6823, 0.6985, -0.2252, 0.2078, 0.1658, -0.09719, and 0.08034, respectively. In practice:
 - Higher fuel consumption is directly associated with higher CO₂ emissions.
 - Larger engines with large numbers of cylinders consume more fuel, thereby emitting more CO₂.
 - The Vehicle Class (V_C) indirectly affects CO_2 emissions by influencing engine size and fuel consumption.
 - The Number of Transmission (V_{TR}) impacts fuel consumption efficiency. For instance, specific transmission types (e.g., manual) improve fuel efficiency compared to other types (e.g., automatic), thereby contributing to lower CO_2 emissions.
 - Fuel Type (FT) reflects differences in combustion properties, which influence fuel efficiency and emissions.
 - Vehicle Manufacturer (V_{Ma}) and Vehicle Model (V_{Mo}) indicate different vehicle designs, performance, and technological variations, thereby impacting, indirectly the CO₂ emissions.

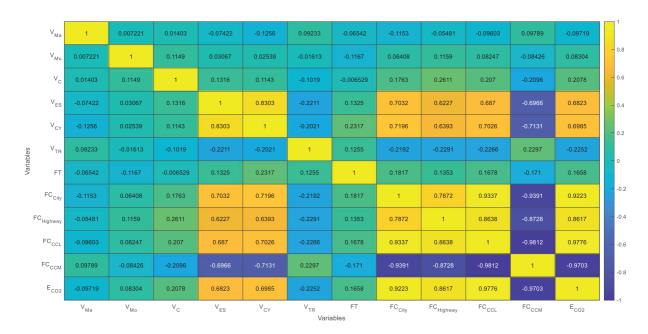


Figure 14: Kendall correlation heatmap

To gain deeper insights into the impact of each attribute and its unique values on CO_2 emissions (E_{CO_2}) , Figs. 15–25 illustrate the attributes' effects, starting with the categorical variables (Figs. 15–19) and followed by the numerical variables (Figs. 20–25). These figures highlight the average CO_2 emissions (depicted as bars) and their associated standard deviation values (depicted as error bars). From the figures, the following insights can be drawn:

- It is apparent that BUGATTI vehicles contribute the most to CO₂ emissions, with around 500 g/km, compared to SMART vehicles, which emit approximately 180 g/km. Both brands exhibit minimal variability in their CO₂ emissions. This disparity can be attributed to differences in vehicle design, performance, and other contributing factors such as engine size, fuel type, and technical specifications. (Fig. 15). Similarly, individual vehicle models show varying levels of CO₂ emissions, with the CHIRON model exceeding 500 g/km, compared with the other models whose emissions are less than 500 g/km. Again, this can be attributed to variations in vehicle design, performance, and additional contributing factors such as engine size, fuel type, and other specifications (Fig. 16).
- In Fig. 17, it is evident that the vehicle class (V_C) significantly impacts CO_2 emissions. For instance, VAN-PASSENGER class exhibits the highest average emissions, reaching around 400 g/km. In contrast, the STATION WAGON-SMALL class has substantially lower emissions, averaging less than 200 g/km. This variation highlights the importance of vehicle class in determining environmental impact in terms of CO_2 emissions.
- It is apparent that vehicles with A (Automatic), AM (Automated Manual), or AS (Automatic with select Shift) transmissions generally exhibit higher CO₂ emissions compared to those with M (Manual) and AV (Continuously Variable) transmissions. However, no specific trend is observed for the number of gears, likely due to the influence of additional attributes (Fig. 18).
- It is apparent that vehicles using E85 (ethanol) and Z (premium gasoline) fuel tend, on average, to exhibit higher CO₂ emissions, followed by X (regular gasoline) and D (diesel) fuel (Fig. 19). This can be justified by the differences in combustion efficiency and energy content across the five different fuel types as well

- as the number of available events for each fuel type, i.e., 1 event for N (natural gas) fuel, as depicted in Fig. 5.
- From Fig. 20, as expected, the number of cylinders (V_{CY}) increases, ranging from 3 to 16 cylinders, and the CO₂ emissions also increase from around 180 g/km to more than 500 g/km of emissions, respectively.
- As the engine size (ES) increases, the CO_2 emissions (E_{CO_2}) also increase, as expected (Fig. 21).
- As long as fuel consumption (FC) (city (FC_{City}), highway ($FC_{Highway}$), or combined conditions in L/100 km (FC_{CCL})) increases, the CO₂ emissions (E_{CO_2}) also increase, as expected (Figs. 22–24). Conversely, as the fuel consumption in combined conditions, measured in mpg (FC_{CCM}), increases the associated CO₂ emissions (E_{CO_2}) decrease, as expected (Fig. 25). The figures illustrate the distribution of CO₂ emissions (E_{CO_2}) for each fuel consumption value, categorized into intervals.

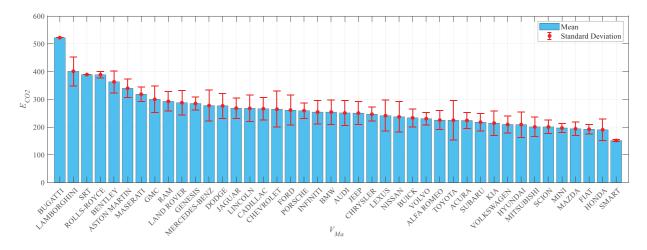


Figure 15: The distribution of CO_2 emissions (E_{CO_2}) across the available unique vehicle manufacturers (V_{Ma})

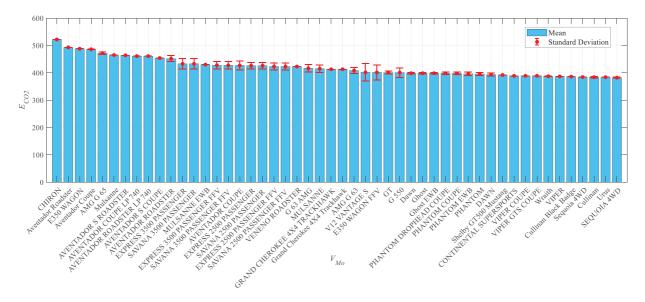


Figure 16: The distribution of CO_2 emissions (E_{CO_2}) across the available unique vehicle models (V_{Mo}). The highest 50 emissions are shown for clarity

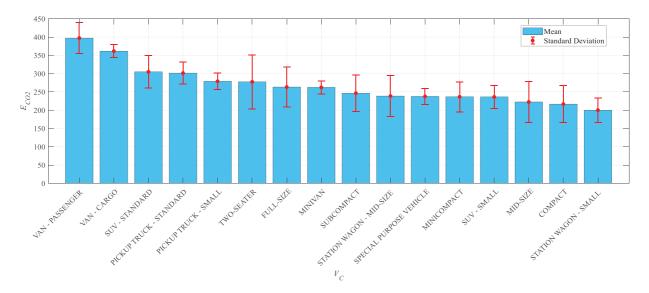


Figure 17: The distribution of CO_2 emissions (E_{CO_2}) across the available unique vehicle classes (V_C)

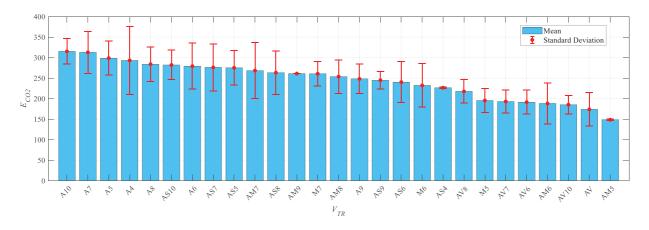


Figure 18: The distribution of CO_2 emissions (E_{CO_2}) across the available unique vehicle transmission types (V_{TR})

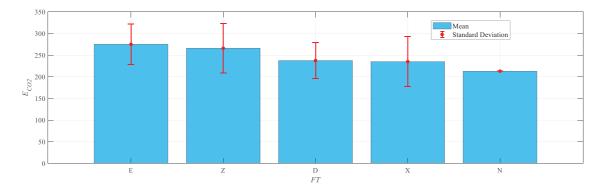


Figure 19: The distribution of CO_2 emissions (E_{CO_2}) across the available unique fuel types (FT)

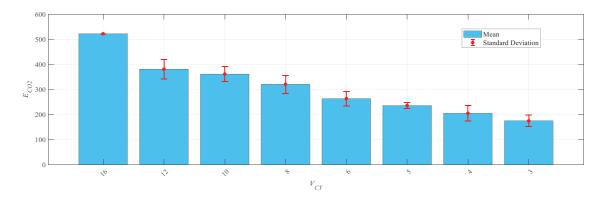


Figure 20: The distribution of CO_2 emissions (E_{CO_2}) across the available unique numbers of cylinders (V_{CY})

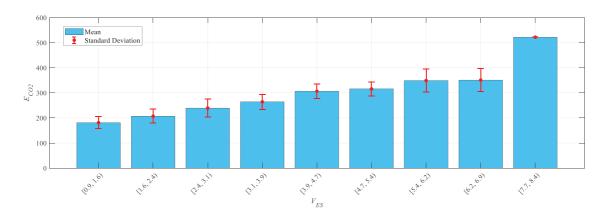
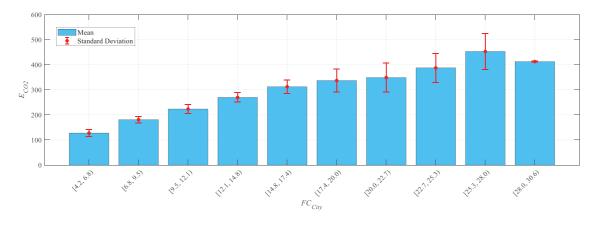


Figure 21: The distribution of CO_2 emissions (E_{CO_2}) across the available unique engine sizes (ES)



 $\textbf{Figure 22:} \ \ \text{The distribution of CO}_2 \ emissions \ (E_{CO_2}) \ across \ the \ available \ unique \ fuel \ consumption \ in \ City \ (FC_{City})$

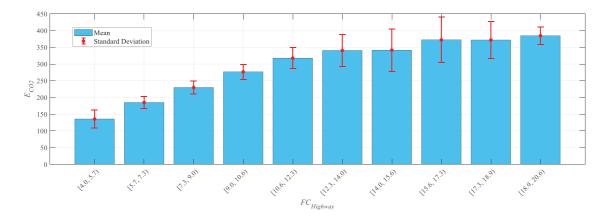


Figure 23: The distribution of CO_2 emissions (E_{CO_2}) across the available unique fuel consumption on highway ($FC_{Highway}$)

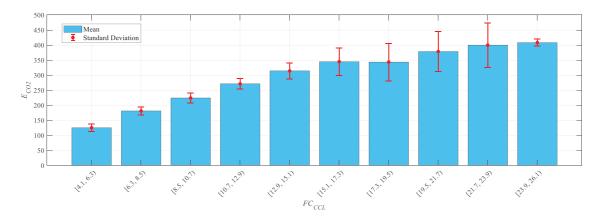


Figure 24: The distribution of CO_2 emissions (E_{CO_2}) across the available unique fuel consumption in combined conditions (L/100 km) (FC_{CCL})

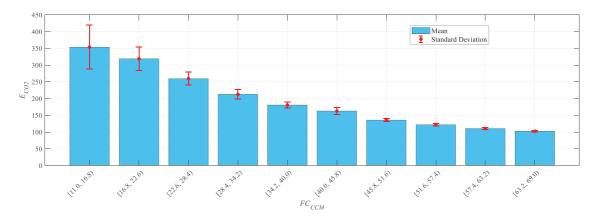


Figure 25: The distribution of CO_2 emissions (E_{CO_2}) across the available unique fuel consumption in combined conditions (mpg) (FC_{CCM})

Considering the insights drawn above, the following attributes were retained in the dataset, while the others were excluded due to their significant contributions to multicollinearity. Specifically, FC_{CCL} , V_{ES} , V_{TR} , V_C , FT, V_{Ma} , and V_{Mo} were retained, as they were considered non-redundant and independent in relation to CO_2 emissions (i.e., X_{red_1}).

To ensure that multicollinearity is avoided, the VIF was computed for the retained attributes. As reported in Table 4, all attributes exhibit VIF values well below the typically accepted threshold of 5. This confirms that multicollinearity is not a concern in the reduced-version dataset ($\mathbf{X}_{\text{red}_1}$). Although attributes V_C and FC_{CCL} show moderate VIF values (~3.3), they remain within acceptable limits and do not suggest exclusion at this stage.

Attribute	VIF value	Interpretation
$\overline{V_{Mo}}$	0.9919	No multicollinearity
V_{Ma}	1.0326	No multicollinearity
FT	1.1540	No multicollinearity
V_C	3.3736	Moderate correlation (acceptable)
V_{TR}	1.1374	No multicollinearity
V_{ES}	0.4707	No multicollinearity
FC_{CCL}	3.3448	Moderate correlation (acceptable)

Table 4: VIF for the retained attributes

Following this, the reduced-version dataset and its variants are to be used to devise various prediction models aiming to accurately estimate the CO₂ emissions (i.e., Step 3). Specifically, the following datasets have been established. The objective is to identify the optimal dataset that comprises the optimal set of attributes that maximizes the prediction accuracy of the CO₂ emissions for any type of vehicle, compromising the vehicle specificity and fuel consumption generalizability, that is the complexity of the dataset considered while developing the predictive model:

- **Reduced-Version Dataset 1** (X_{red_1}). It comprises 8 attributes, including the CO₂ emissions after excluding the multicollinearity significantly contributing attributes. Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} , V_{ES} , V_{TR} , V_C , FT, V_{Ma} , and V_{Mo} .
- **Reduced-Version Dataset 2** (X_{red_2}). It comprises 6 attributes, including the CO₂ emissions after excluding the least two correlated attributes (V_{Ma} and V_{Mo}) whose Kendall correlation values are -0.0972 and 0.0830). Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} , V_{ES} , V_{TR} , V_C , and FT.
- **Reduced-Version Dataset 3** ($\mathbf{X}_{\text{red}_3}$). It comprises 5 attributes, including the CO₂ emissions after excluding the least three correlated attributes (FT, V_{Ma} , and V_{Mo}) whose Kendall correlation values are 0.1658, -0.0972 and 0.0830). Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} , V_{ES} , V_{TR} , and V_{C} .
- **Reduced-Version Dataset** 4 (X_{red_4}). It comprises 4 attributes, including the CO₂ emissions after excluding the least four correlated attributes (V_C , FT, V_{Ma} , and V_{Mo}) whose Kendall correlation values are 0.2078, 0.1658, -0.0972 and 0.0830). Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} , V_{ES} , and V_{TR} .
- **Reduced-Version Dataset 5** (X_{red_5}). It comprises 3 attributes, including the CO₂ emissions after excluding the least five correlated attributes (V_{TR} , V_C , FT, V_{Ma} , and V_{Mo}) whose Kendall correlation values are

- -0.2252, 0.2078, 0.1658, -0.0972 and 0.0830). Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} and V_{ES} .
- **Reduced-Version Dataset 6** (X_{red_6}). It comprises 2 attributes, including the CO₂ emissions after excluding the least six correlated attributes (V_{ES} , V_{TR} , V_C , FT, V_{Ma} , and V_{Mo}) whose Kendall correlation values are 0.6985, -0.2252, 0.2078, 0.1658, -0.0972 and 0.0830). Specifically, the following attributes are kept as input while developing the predictive model: FC_{CCL} .

Table 5 summarizes the set of attributes considered in input to the predictive model across the dataset variants, for clarity.

Dataset	Dataset notation	Dataset description	Preserved attributes
Reduced 1	$\mathbf{X}_{\mathrm{red}_1}$	8 attributes	FC_{CCL} , V_{ES} , V_{TR} , V_C , FT , V_{Ma} , and V_{Mo}
Reduced 2	\mathbf{X}_{red_2}	6 attributes	FC_{CCL} , V_{ES} , V_{TR} , V_C , and FT
Reduced 3	$\mathbf{X}_{\mathrm{red}_3}$	5 attributes	FC_{CCL} , V_{ES} , V_{TR} , and V_C
Reduced 4	\mathbf{X}_{red_4}	4 attributes	FC_{CCL} , V_{ES} , and V_{TR}
Reduced 5	$\mathbf{X}_{\mathrm{red}_5}$	3 attributes	FC_{CCL} and V_{ES}
Reduced 6	$\mathbf{X}_{\mathrm{red}_6}$	2 attributes	FC_{CCL}

Table 5: Variants of datasets used for predictive modeling of CO₂ emissions

Once the dataset variants are established, they have been used to develop various prediction models investigated in this work, i.e., LR, RTs, ETs, Kernel, SVMs, and NNs (i.e., Step 3). In this regard, each dataset variant is divided into 80% (5140 data points) and 20% (1285 data points) and the 5-fold cross validation approach is being employed. Tables 6–11 summarize the optimal models' configurations and the corresponding performance metrics on the validation portion of the 5-fold cross validation approach for X_{red_1} , X_{red_2} , X_{red_3} , X_{red_4} , X_{red_5} , and X_{red_6} , respectively. Indeed, the average computational efforts needed by the simple models, such as the LR and RTs, are much less than those required by the more advanced non-linear models, such as the SVMs and NNs, across the whole dataset variants.

Table 6: Performance of predictive models using Reduced Dataset 1 (X_{red1}) on the Validation portion

Model	Optimal configuration	Performance metrics (Validation)					
Model	Optimur configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)	
LR	Interactions	2.55	2.07	0.85	0.997	9.69	
RTs	Minimum Leaf Size is 8	2.72	2.06	0.84	0.997	68.01	
	Ensemble Method is Bag						
	Minimum Leaf Size is 1						
ETs	Number of Learners is 10	2.52	1.88	0.77	0.998	252.8	
	Learning Rate is 0.998						
	Number of Predictors to						
	Sample is 6						
	Learner is Least Squares						
	Kernel						
Kernel	Number of Expansion	5.678	3.89	1.65	0.987	198.4	
	Dimensions is 106						

Table 6	(con	tinue	(be
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Model	Optimal configuration	Performance metrics (Validation)					
	Optimur configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)	
	Lambda is 0.18036						
	Kernel Scale is 0.010286						
	Standardize Data is Yes						
	Kernel Function is Linear						
	Kernel Scale is Auto						
SVM	Box Constraint is 54.1142	2.76	2.15	0.90	0.997	5.81	
	Epsilon is 5.4114						
	Standardize Data is Yes						
	Number of Layers is 2						
	Activation is None						
ANN	Layers Size is 1×3	2.56	2.08	0.85	0.997	717.3	
	Lambda is 3.56×10^{-9}						
	Standardize Data is Yes						

Table 7: Performance of predictive models using Reduced Dataset 2 (X_{red_2}) on the Validation portion

		Perform	nance m	netrics	(Valida	ation)
Model	Optimal configuration	RMSE	MAE	MAP	$\mathbf{E} \mathbf{R}^2$	Time
		(g/km)	(g/km)	(%)	(%)	(sec)
LR	Linear	2.56	2.09	0.85	0.997	4.96
RTs	Minimum Leaf Size is 13	2.69	2.06	0.85	0.997	10.41
	Ensemble Method is LSBoost					
	Minimum Leaf Size is 130					
ETs	Number of Learners is 10	4.17	2.77	1.15	0.993	78.99
	Learning Rate is 0.9345					
	Number of Predictors to Sample is 5					
	Learner is Least Squares Kernel					
	Number of Expansion Dimensions is 361					
Kernel	Lambda is 1.1145×10^{-5}	6.55	4.09	1.73	0.983	46.99
	Kernel Scale is 0.23953					
	Standardize Data is Yes					
	Kernel Function is Linear					
SVM	Box Constraint is 0.031355	2.67	2.03	0.84	0 997	3287
3 V IVI	Epsilon is 0.21702	2.07	2.03	0.01	0.777	3207
	Standardize Data is No					
	Number of Layers is 3					
	Activation is ReLU					
ANN	Layer Size is $6 \times 2 \times 6$	2.56	2.09	0.85	0.997	898
	Lambda is 1.1337×10^{-7}					
	Standardize Data is Yes				E R ² (%) 0.997 0.997 0.993	

Table 8: Performance of predictive models using Reduced Dataset 3 (X_{red_3}) on the Validation portion

		Performance metrics (Validation)				
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
LR	Linear	2.56	2.09	0.85	0.997	14.26
RTs	Minimum Leaf Size is 11	2.67	2.05	0.84	0.997	39.79
	Ensemble Method is LSBoost					
	Minimum Leaf Size is 1					
ETs	Number of Learners is 10	9.76	7.09	2.95	0.96	242
	Learning Rate is 0.4851					
	Number of Predictors to Sample is 1					
	Learner is Least Squares Kernel					
	Number of Expansion Dimensions					
Kernel	is 449	10.52	5.47	2.31	0.956	118
	Lambda is 0.0072764				0.956	
	Kernel Scale is 35.2316					
	Standardize Data is No					
	Kernel Function is Linear					
SVM	Box Constraint is 2.13	2.64	2.14	0.88	0.007	2502
3 V IVI	Epsilon is 3.9653	2.04	2.14	0.00	0.337	2302
	Standardize Data is Yes					
	Number of Layers is 3					
	Activation is None					
ANN	Layers Size is $3 \times 1 \times 9$	2.56	2.09	0.85	0.997 0.997 0.96	1367
	Lambda is 5.9279×10^{-9}					
	Standardize Data is Yes					

Table 9: Performance of predictive models using Reduced Dataset 4 $(X_{\mathrm{red_4}})$ on the Validation portion

		Performance m)
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
LR	Linear	2.57	2.09	0.85	0.997	8
RTs	Minimum Leaf Size is 7	2.68	2.05	0.84	0.997	31.9
	Ensemble Method is LSBoost Minimum Leaf Size is 1					
ETs	Number of Learners is 30 Learning Rate is 0.1648 Number of Predictors to Sample is 3	2.81	2.37	0.96	0.997	289

Table 9 (continued)

			Performan	ce metrics ((Validation))
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
	Learner is Least Squares Kernel					
	Number of Expansion Dimensions is					
Kernel	126	6.68	3.23	1.36	0.982	91
	Lambda is 0.14639					
	Kernel Scale is 0.0018324					
	Standardize Data is Yes					
	Kernel Function is Gaussian					
CVIN	Box Constraint is 947.4246	2.58	2.02	0.04	0.007	1707
SVM	Epsilon is 1.2928	2.58	2.03	0.84	0.997	1797
	Standardize Data is No					
	Number of Layers is 2					
	Activation is None					
ANN	Layer Size is 4×2	2.68	2.21	0.90	0.997	1060
	Lambda is 10.5122					
	Standardize Data is No					

 $\textbf{Table 10:} \ \ Performance \ of \ predictive \ models \ using \ Reduced \ Dataset \ 5 \ (X_{red_5}) \ on \ the \ Validation \ portion$

		Performance metrics (Validation)				
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
LR	Linear	2.56	2.09	0.85	0.997	4.6
RTs	Minimum Leaf Size is 2	2.60	2.06	0.84	0.997	9.7
	Ensemble Method is Bag					
	Minimum Leaf Size is 25					
ETs	Number of Learners is 499	2.69	2.10	0.86	0.997	68
	Learning Rate is 0.553					
	Number of Predictors to Sample is 2					
	Learner is Least Squares Kernel					
	Number of Expansion Dimensions is 118					
Kernel	Lambda is 4.3848×10^{-6}	3.47	2.28	0.95	0.995	27
	Kernel Scale is 0.001001					
	Standardize Data is No					
	Kernel Function is Linear					
SVM	Box Constraint is 0.05048	2.66	1.00	0.02	0.007	1260
3 V IVI	Epsilon is 0.133	2.00	1.99	0.82	0.997	1260
	Standardize Data is No					

Table 10 (continued)

		Performance metrics (Validation)				
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
43737	Number of Layers is 2	2.54	2.00	0.05	2.22	267
ANN	Activation is ReLU Layer Size is 11 × 144	2.56	2.08	0.85	0.997	367
	Lambda is 4.6675×10^{-9}					
	Standardize Data is Yes					

 $\textbf{Table 11:} \ \ \text{Performance of predictive models using Reduced Dataset 6} \ (X_{red_6}) \ \text{on the Validation portion}$

		Performance metrics (Validation)				
Model	Optimal configuration	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)	Time (sec)
LR	Linear	2.57	2.09	0.85	0.997	4.88
RTs	Minimum Leaf Size is 2	2.57	2.05	0.84	0.997	8.60
	Ensemble Method is LSBoost					
	Minimum Leaf Size is 2					
ETs	Number of Learners is 484	2.57	2.06	0.84	0.997	97
	Learning Rate is 0.088196					
	Number of Predictors to Sample is 2					
	Learner is Least Squares Kernel					
	Number of Expansion Dimensions is					
Kernel	1004	3.01	2.20	0.91	0.996	17.26
	Lambda is 0.19211					
	Kernel Scale is 0.0012527					
	Standardize Data is Yes					
	Kernel Function is Quadratic					
SVM	Box Constraint is 39.5719	2.67	1.99	0.82	0.997	628
3 V IVI	Epsilon is 0.064001	2.07	1.77	0.02	0.777	020
	Standardize Data is Yes					
	Number of Layers is 3					
	Activation is Sigmoid					
ANN	Layers Size is $5 \times 3 \times 231$	2.56	2.07	0.85	0.997	693
	Lambda is 3.0917×10^{-5}					
Kernel SVM ANN	Standardize Data is No					

Looking at the tables, one can clearly observe that, across all performance metrics, reducing the number of attributes/features used to develop the prediction models (i.e., moving from \mathbf{X}_{red_6}) does not significantly impact prediction accuracy, except in the case of the Kernel model, where performance appears to deteriorate as the number of attributes decreases. This suggests that the removed attributes may not provide

unique predictive information and are likely non-essential or redundant, with their effects already captured by the most influential attribute, i.e., Fuel Consumption. In fact, the use of a simple LR model may be sufficient, offering a favorable compromise between predictive accuracy and computational efficiency.

Once the optimal models are identified, they will be used to evaluate the predictability of the CO₂ emissions on the 20% test portion. It is crucial to benchmark and compare the developed models under identical conditions, i.e., using the same test dataset with the same operating settings, to ensure a fair and meaningful assessment of their performance. In this regard, Tables 12–17 summarize the models' performance across the dataset variants, reporting the achieved RMSE, MAE, MAPE, and R² metrics' values. Looking at the tables, one can observe that the models' performance remains nearly consistent across all performance metrics, except for the Kernel model, whose performance varies between different dataset variants. Furthermore, the performance metrics align closely with those obtained on the validation set across all models, indicating that overfitting did not occur on the unseen test set.

Table 12: Performance of predictive models using the reference dataset on the test portion

Model	Performance metrics (Test)							
	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)				
LR	3.45	2.15	0.87	0.995				
RTs	3.55	2.11	0.86	0.995				
ETs	3.37	1.90	0.78	0.996				
Kernel	5.79	3.87	1.63	0.99				
SVM	3.57	2.18	0.90	0.995				
ANN	3.46	2.17	0.88	0.995				

Table 13: Performance of predictive models using Reduced Dataset 2 (X_{red_2}) on the Test portion

Model	Performance metrics (Test)						
	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)			
LR	3.46	2.18	0.88	0.995			
RTs	3.47	2.12	0.87	0.995			
ERTs	4.54	2.78	1.14	0.992			
Kernel	6.39	3.81	1.57	0.984			
SVM	3.54	2.10	0.86	0.995			
ANN	3.46	2.18	0.88	0.995			

Table 14: Performance of predictive models using Reduced Dataset 3 (X_{red₃}) on the Test portion

Model	Performance metrics (Test)					
Wiodei	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)		
LR	3.46	2.18	0.88	0.995		
RTs	3.54	2.13	0.87	0.995		

Table 14 (continued)

Model		Performance 1	metrics (Test)	
Wiodei	RMSE (g/km)	MAE (g/km)	MAPE (%)	R^{2} (%)
ERTs	9.50	7.13	3.05	0.965
Kernel	20.53	11.69	4.86	0.834
SVM	3.49	2.22	0.90	0.995
ANN	3.46	2.18	0.88	0.995

Table 15: Performance of predictive models using Reduced Dataset 4 (X_{red_4}) on the Test portion

Model	Performance metrics (Test)						
	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)			
LR	3.46	2.18	0.89	0.995			
RTs	3.53	2.12	0.86	0.995			
ERTs	3.56	2.45	0.99	0.995			
Kernel	4.04	2.54	1.05	0.994			
SVM	3.46	2.10	0.86	0.995			
ANN	3.48	2.27	0.92	0.995			

 $\textbf{Table 16:} \ \ \text{Performance of predictive models using Reduced Dataset 5} \ (X_{red_5}) \ on \ the \ \text{Test portion}$

Model	Performance metrics (Test)							
	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)				
LR	3.46	2.18	0.89	0.995				
RTs	3.45	2.12	0.87	0.995				
ERTs	3.53	2.19	0.89	0.995				
Kernel	3.08	2.31	0.94	0.996				
SVM	3.58	2.09	0.85	0.995				
ANN	6.47	2.28	0.93	0.984				

Table 17: Performance of predictive models using Reduced Dataset 6 (X_{red_6}) on the Test portion

Model		Performance 1	metrics (Test)	
Model	RMSE (g/km)	MAE (g/km)	MAPE (%)	R^{2} (%)
LR	3.45	2.18	0.88	0.995
RTs	3.45	2.14	0.87	0.995

Model	Performance metrics (Test)			
	RMSE (g/km)	MAE (g/km)	MAPE (%)	R ² (%)
ERTs	3.45	2.14	0.87	0.995
Kernel	3.63	2.27	0.93	0.995
SVM	3.57	2.09	0.85	0.995
ANN	3.44	2.15	0.88	0.995

Table 17 (continued)

For further clarity, Fig. 26 shows the actual (solid line) and predicted (solid lines with different markers) CO₂ emissions obtained by the LR on the test portion across the dataset variants. An exact match can be observed among the estimates obtained while using the different dataset variants.

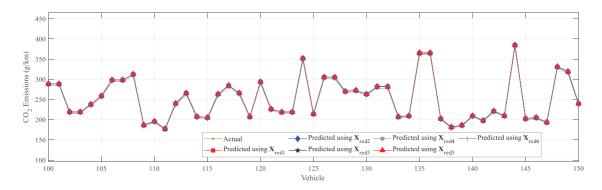


Figure 26: Examples of actual vs. predicted CO₂ emissions obtained by the LR for 50 test vehicles across the dataset variants

To justify the performance of our models, a careful comparative study to two studies that used the same dataset was carried out. Based on the Bi-LSTM deep neural network, the performance metrics in terms of R² on the testing 20% of the whole dataset was reported to be 93.78% [25]. Therefore, our models yield substantially better results than those of [25] since they yielded an R² between 98% and 99% in the out-of-sample testing datasets. Similarly, the accuracy of the models investigated in [26] was found to be comparable to our study performance metrics with a superiority to our models since they are simpler and straightforward against the deep neural networks tested in [26] known to be time-consuming during their training phase.

The findings of our study have shown the proposed models to accurately predict the level of CO_2 being emitted by the investigated LDVs. For instance, using machine learning techniques exhibited significant implications for both policy and industry applications. Policymakers can benefit from these predictive models to improve the effectiveness of the regulations and emission standards, ensuring compliance with environmental goals such as those stated in the Paris Agreement. In addition, the LDVs manufacturers can use the findings of this study (mainly the features that are the most likely to affect the CO_2 emission levels) to lower the current levels. At the regional level, each country in which the investigated LDVs are used can inspire those insights to check the expected CO_2 levels even before importing any type of the studied vehicles.

6 Conclusions, Limitations, and Future Directions

In this paper, the predictability of CO₂ emissions from Light-Duty Vehicles (LDVs) was investigated using a comprehensive dataset encompassing LDVs from various manufacturers, their CO₂ emissions, and other critical influencing attributes. Six Machine Learning (ML) models, ranging from simple linear regression models to highly non-linear regression models, were developed and optimized to estimate CO₂ emissions accurately. To facilitate the models' development stage, a detailed statistical analysis was conducted to identify the most influential attributes of CO₂ emissions. Three correlation metrics, namely Pearson, Spearman, and Kendall, were employed to compute attribute correlations. Based on the computed correlation values, different reduced dataset variants were established to optimally identify the set of attributes that maximize the predictability of CO₂ emissions. The effectiveness of the developed ML models was examined across these dataset variants using well-established performance metrics from the literature. The obtained results reveal that Fuel Consumption attributes were the most influential on CO₂ emissions, as evidenced by their high correlation values across all three metrics. The investigated models demonstrated consistent performance across all metrics and dataset variants, with the LR model emerging as the optimal choice due to its balance between predictive accuracy and computational efficiency. Specifically, the LR model achieved superior performance, with the Mean Absolute Percentage Error falling below 0.90% and the Coefficient of Determination exceeding 99.7%. These results were obtained using the 80-20 rule for validation and test datasets, respectively, and a 5-fold cross validation approach on the validation dataset. While this work underscores the effectiveness of various ML models, particularly NNs, in accurately estimating CO₂ emissions from LDVs, several limitations can be identified, along with recommendations to enhance the robustness and applicability of the findings:

- The study relies solely on standalone ML models, which may limit predictive performance compared to
 hybrid approaches that leverage complementary strengths. Thus, future work can be devoted to exploring
 hybrid modeling approaches to further enhance prediction accuracy.
- The dataset used in this study may not fully capture the variability of real-world driving conditions, as it lacks attributes such as speed variability, driving behavior, fuel quality, and road conditions. Thus, future work can be devoted to expanding the dataset by the inclusion of such additional attributes to provide a deeper understanding of the attributes influencing CO₂ emissions and improve the models' predictability.
- The developed ML models were trained on a static dataset, making the models less adaptable to evolving conditions experienced by the vehicles over time. Thus, future work can be devoted to integrating incremental learning methods to allow models to effectively adapt to evolving conditions, ensuring their long-term applicability.
- Inspired by the work presented in [23] which explored the ability of several statistical and ML models to forecast annual CO₂ emissions of the building sector, the findings can be extended to the transportation sector to predict the quantity of CO₂ expected to be emitted by the LDVs at a country level. To carry out such research, statistics of the vehicles being used over the past years as well as the distribution of their brands, manufacturers, average time of annual use, etc. are key information.

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Availability of Data and Materials: The authors confirm that the data supporting the findings of this study are available online.

Ethics Approval: Not applicable.

Conflicts of Interest: The authors declare no conflicts of interest to report regarding the present study.

Appendix A

Figs. A1 and A2 show the Pearson and Spearman correlation heatmaps computed on the refined dataset, using the numeric and numeric and encoded categorical attributes, respectively.

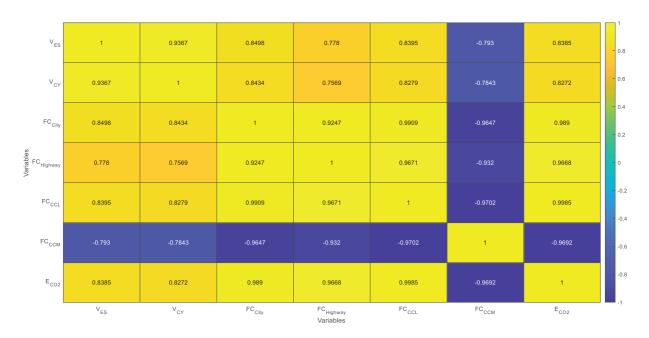


Figure A1: Pearson correlation heatmap

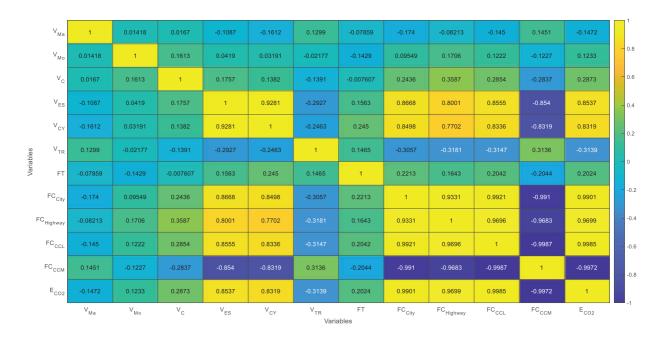


Figure A2: Spearman correlation heatmap

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