



ARTICLE

Enhanced Multi-Object Dwarf Mongoose Algorithm for Optimization Stochastic Data Fusion Wireless Sensor Network Deployment

Shumin Li¹, Qifang Luo^{1,2,*} and Yongquan Zhou^{1,2}

¹College of Artificial Intelligence, Guangxi University for Nationalities, Nanning, 530006, China

²Guangxi Key Laboratories of Hybrid Computation and IC Design Analysis, Nanning, 530006, China

*Corresponding Author: Qifang Luo. Email: l.qf@163.com

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ABSTRACT: Wireless sensor network deployment optimization is a classic NP-hard problem and a popular topic in academic research. However, the current research on wireless sensor network deployment problems uses overly simplistic models, and there is a significant gap between the research results and actual wireless sensor networks. Some scholars have now modeled data fusion networks to make them more suitable for practical applications. This paper will explore the deployment problem of a stochastic data fusion wireless sensor network (SDFWSN), a model that reflects the randomness of environmental monitoring and uses data fusion techniques widely used in actual sensor networks for information collection. The deployment problem of SDFWSN is modeled as a multi-objective optimization problem. The network life cycle, spatiotemporal coverage, detection rate, and false alarm rate of SDFWSN are used as optimization objectives to optimize the deployment of network nodes. This paper proposes an enhanced multi-objective mongoose optimization algorithm (EMODMOA) to solve the deployment problem of SDFWSN. First, to overcome the shortcomings of the DMOA algorithm, such as its low convergence and tendency to get stuck in a local optimum, an encircling and hunting strategy is introduced into the original algorithm to propose the EDMOA algorithm. The EDMOA algorithm is designed as the EMODMOA algorithm by selecting reference points using the K-Nearest Neighbor (KNN) algorithm. To verify the effectiveness of the proposed algorithm, the EMODMOA algorithm was tested at CEC 2020 and achieved good results. In the SDFWSN deployment problem, the algorithm was compared with the Non-dominated Sorting Genetic Algorithm II (NSGAI), Multiple Objective Particle Swarm Optimization (MOPSO), Multi-Objective Evolutionary Algorithm based on Decomposition (MOEA/D), and Multi-Objective Grey Wolf Optimizer (MOGWO). By comparing and analyzing the performance evaluation metrics and optimization results of the objective functions of the multi-objective algorithms, the algorithm outperforms the other algorithms in the SDFWSN deployment results. To better demonstrate the superiority of the algorithm, simulations of diverse test cases were also performed, and good results were obtained.

KEYWORDS: Stochastic data fusion wireless sensor networks; network deployment; spatiotemporal coverage; dwarf mongoose optimization algorithm; multi-objective optimization

1 Introduction

With the development of wireless sensors and micro-electro-mechanical systems, wireless sensor networks have developed rapidly, attracting extensive attention from both academia and industry [1]. Wireless sensor networks, which consist of sensor nodes independently distributed in the detection area, were initially widely used in the military field, and are now widely used in our daily lives such as environmental monitoring, agriculture, healthcare, smart cities, industrial automation, internet of things, transportation and vehicle



management, etc. [2]. Wireless sensor networks are low-cost, simple to deploy and scalable, and capable of real-time monitoring and data collection, but the sensor nodes have the problem of energy constraints, the deployment of network nodes greatly affects the overall energy consumption of the network and thus directly affects the performance of the wireless sensor network [3]. Literature [4] points out that deploying sensors has always been a great challenge for wireless sensor networks, and the effective deployment of nodes is a prerequisite for wireless sensor networks to cover the target area efficiently. Therefore, this study is dedicated to solving the deployment problem of wireless sensor networks to extend the network lifecycle, coverage, and other performance.

Coverage is a key indicator for determining the quality of wireless sensor network node deployment. Coverage can be divided into spatial coverage and temporal coverage, where spatial coverage measures the range of the target area monitored by the wireless sensor network, and temporal coverage measures whether the wireless sensor network is tracking the target on time [5]. Previous research on the deployment of wireless sensor network nodes has usually been based on simple target area coverage perception models, such as the 0–1 perception model and the probabilistic perception model [4,6–8]. However, the perception model used in practical applications usually adopts a data fusion model that fuses the perception results of multiple sensors. Data fusion models improve the accuracy of sensor monitoring and expand the coverage of wireless sensor networks. The 0–1 sensing model assumes that the sensing range of a sensor is a circle [5]. The probabilistic sensing model assumes that a sensor has two sensing radii, an inner sensing radius and an outer sensing radius. Targets within the inner sensing radius are detectable, while targets within the outer sensing radius are detected with a probability assigned by humans [9]. This makes the monitoring results of the model affected by the assigned probability. Therefore, there is a gap between the two models and the actual sensing of sensors. This paper studies the deployment of a stochastic data fusion wireless sensor network (SDFWSN), which is more in line with practical applications. This model assumes that the sensor's perception of the signal energy emitted by the target point is affected by environmental factors such as distance, temperature, and humidity. The signal energy is negatively correlated with the distance from the sensor to the target point, and within a certain range, it decreases with increasing temperature and decreasing humidity. The final monitoring result is a fusion of the monitoring results of sensors within a certain range. This model is in line with the perception process of sensors in practice. The model mentioned in [5] is used for spatial and temporal coverage. To the best of our knowledge, this is the first time that time delay has been considered in the process of wireless network deployment optimization, and the SDFWSN model applied in this study is more realistic, making our experimental results more accurate.

Consider a deployment area with multiple dynamic target points and static sensor node candidate locations using (α, β) spatial coverage model, i.e., a target point has a probability α of being falsely detected (no target point is present but the sensor emits a positive result) and a probability β of being correctly detected (a target point is present and the sensor correctly detects the target point), where α is referred to as the false alarm rate, β is referred to as the detection rate and $\alpha \in (0, 0.5)$ and $\beta \in (0.5, 1)$. The $\alpha - delay$ temporal coverage model is used, i.e., the average number of detection cycles from the first detection to the target provided that the network false alarm rate is not greater than α . This paper aims to reduce the false alarm rate and increase the detection rate by optimizing the deployment of the network, extending the network lifecycle, and improving the spatiotemporal coverage of the network. The problem is modeled as a multi-objective optimization problem with five objectives. Notably, this is a Non-deterministic Polynomial-time hard task [10]. When dealing with the above problem, it is best to use meta-heuristics to efficiently solve the problem [11]. DMOA is an effective swarm intelligence algorithm that can solve various optimization problems [12]. This paper designed and used an enhanced multi-objective mongoose optimization algorithm (EMODMOA) to find a feasible stochastic data fusion-based network node deployment scheme considering

network lifecycle, spatial coverage, temporal coverage, detection, and false alarms. DMOA is inspired by the social behaviors of dwarf mongoose populations such as guarding, babysitting, and attacking predators [13]. The DMOA algorithm has the advantages of being simple and easy to implement and does not require excessive parameter adjustment. However, it has a slow convergence speed and is prone to local optima due to the weak balance between exploration and exploitation [14]. In this paper, the encircling and hunting strategy is highlighted by simulating the encircling and hunting habits of the dwarf mongoose. With the encircling and hunting strategy, the algorithm can successfully escape from local optima and achieve a good balance between exploration and exploitation. In this paper, the K-Nearest Neighbor (KNN) algorithm is used to select the reference points, EMODMOA is proposed, and the performance of EMODMOA is tested using the CEC2020 multi-objective multi-modal optimization benchmark function. The algorithm is used to complete the multi-objective stochastic data fusion wireless sensor.

The main contributions of this paper are as follows:

1. By simulating the biological habits of the dwarf mongoose, a strategy for encircling and hunting is proposed, which is an enhanced dwarf mongoose optimization algorithm (EDMOA) is proposed.
2. The KNN algorithm is used to select reference points, and a multi-objective dwarf mongoose optimization algorithm is established to improve the efficiency of the multi-objective algorithm.
3. A stochastic data fusion network model is established based on the original data fusion network model by considering the influence of environmental factors on the sensing effect of sensors, and the deployment of sensor nodes of this model is studied.
4. When optimizing the deployment of network nodes, maximizing the spatial coverage of the network will maximize the temporal coverage and the accuracy of monitoring as the goal to ensure the speed and quality of network monitoring.

The rest of the paper is organized as follows: [Section 2](#) of this paper describes the literature review. [Section 3](#) gives the construction of the SDFWSN model. [Section 4](#) describes the construction of EMODMOA and the application of the algorithm, [Section 5](#) performs the CEC2020 benchmark function on the proposed algorithm and [Section 6](#) gives the experimental results and discussion. [Section 7](#) concludes the paper and proposes future work.

2 Related Works

Several works have solved the node deployment problem in WSN systems using swarm intelligence algorithms [15]. [Sections 2.1](#) and [2.2](#) provide an overview of research on WSN node deployment and DMOA, respectively.

2.1 WSN Node Deployment

Hajje et al. [16] proposed a multi-objective flower pollination algorithm (MOFPA) for stochastic WSN scheduling. It aims to deploy a set of sensors in a target area under the condition of guaranteed network connectivity while optimizing the total network coverage and energy consumption. Wang et al. [17] employ a node scheduling scheme based on a multi-objective evolutionary algorithm to schedule heterogeneous nodes in shifts, thus extending the life cycle of the network. Non-dominated Sorting Genetic Algorithm-iii (NSGA-III) is used to optimize the deployment of WSN to reduce the network energy consumption and improve network coverage while ensuring network connectivity [18]. The deployment of WSNs in environments where obstacles are present is investigated, using a multi-objective optimization algorithm to deploy sensor nodes in a way that ensures network connectivity to maximize coverage and reduce deployment costs [19]. Saad et al. [20] addressed the deployment of WSN in 3D environments using

NSGA-II. It is worth mentioning that they simulated a real space 3D model using the Bresenham line-of-sight 3D environment coverage model. Zaimen et al. [21] considered the problem of optimizing the deployment of sensor nodes in heterogeneous obstacle indoor environments, using the BIM database as well as other additional inputs (sensor node parameters) and a genetic algorithm to provide the optimal deployment. A new method based on Support Vector Regression and Genetic Algorithm is proposed for the deployment optimization problem of WSN nodes, which argues that the configuration and deployment of WSN affects almost all of their performance metrics, and the support vector regression model is utilized for the configuration of the node parameters of the Wireless Sensor Networks, and the configured node model is optimized for the deployment [22]. An enhanced multi-objective marine predator algorithm (CMOMPA) is proposed, which utilizes a Gaussian elite perturbation strategy and a learning strategy based on a competitive mechanism to generate progeny with enhanced diversity and distribution, and balances the deployment cost, connectivity, and coverage of heterogeneous WSN under specific coverage constraints [23]. The Voronoi diagram method is used to divide the monitoring area to obtain the appropriate sensing radius and communication radius, and the algorithm is used to solve the problem of deploying the wireless sensor network on 3D terrain and to improve the Quality of Service (QoS) of the wireless sensor network [24]. A resource scheduling algorithm for large-scale wireless sensor networks based on differential co-evolution and multi-objective decomposition is proposed, which is used to simultaneously optimize the position and dormant state of nodes [25]. In [26], three heuristic algorithms are used to optimize the deployment of sensor nodes, thereby maximizing the network lifetime and network coverage is divided into. The deployment of sensor nodes is optimized using an improved vampire bat optimizer, which obtains the optimal deployment location and the minimum number of sensors required by optimally splicing the sensing region with the cellular grid [27].

Looking at the current state of research at domestic and abroad, it can be found that most of the models currently studied in the literature for the deployment problem of wireless sensor networks are too simple, and there is a huge difference between them and practical applications. There are obvious differences between the currently studied sensor sensing models which mainly utilize the 0–1 sensing model, the probabilistic sensing model, the advanced sensing models, and information processing schemes adopted by the existing sensor networks; and there are few literature studies on the temporal coverage problem and the quality of network monitoring of the network. This study proposed a stochastic data fusion wireless sensor model as the wireless sensor coverage deployment model for the following reasons:

(1) The model adopts a random sensing model. Most of the traditional wireless sensor networks use a 0–1 sensing model or probabilistic sensing model, which does not consider the randomness of sensing, while sensors using a stochastic sensing model sense the signal energy of the target point will be affected by the external environment, which makes the sensor's sensing with randomness and more realistic.

(2) The current study of wireless sensor networks for monitoring using an independent transmission model which is very different from the advanced data transmission model used in practice, this project uses a data fusion model that is more in line with the practical application, a certain range of sensors to fuse their monitoring results to obtain the final monitoring results.

2.2 DMOA

In 2022, Sadoun et al. used DMOA to improve the Long Short-Term Memory (LSTM) model to predict the properties of composite materials [28]. The model improved by DMOA has a prediction accuracy of 99%. In 2022, Akinola et al. introduced a simulated annealing algorithm to a binary variant of DMOA [29] which balanced the detection and exploitation capabilities of the algorithm. In 2022, Agushaka et al. improved DMOA by incorporating other social behaviors of dwarf mongooses, i.e., predation, mound protection,

reproduction, and group splitting behaviors [30], greater enhancement of the dwarf mongoose's exploration and exploitation capabilities, and improved convergence speed of the algorithm. In 2022, Mehmood et al. proposed a meta-heuristic algorithm for parameter estimation of autoregressive exogenous models based on DMOA [31]. The algorithm has fast convergence speed, high estimation accuracy, and strong robustness. In 2023, Agushaka et al. introduced adaptive and stochastic factors to the DMOA, which improves the exploration capability and availability of the algorithm and improves the diversity of the solution [32]. In 2022, Akinola et al. solved the high-dimensional feature selection problem using a binary version of DMOA [33]. In 2022, Alissa et al. proposed a dwarf mongoose algorithm based on machine learning-driven ransomware detection by combining DMOA with machine learning-driven ransomware detection [34], which is effective in identifying and classifying malware or ransomware. In 2022, Alrayes et al. used improved DMOA to select cluster heads of unmanned aerial vehicles to find the optimal routes to reach their destinations [35]. In 2022, Balasubramaniam et al. embedded DMOA into a lightweight deep neural network architecture for heart disease prediction [36]. In 2023, Zare et al. used DMOA to integrate the battery life, operations and maintenance cost, fuel cost and environmental cost of microgrids to determine the optimal operating parameters and improve the load capacity of microgrids [37]. In 2023, Dora et al. merged Symbiotic Organism Search (SOS) into DMOA to enhance the algorithm's local search capability [38], solved the reactive power scheduling problem using the proposed enhanced DMOA and found the optimal settings to minimize the real power loss, total voltage variation and L-index. In 2023, Fu et al. proposed an improved DMOA which introduced the optimal leader mechanism and proposed a novel nonlinear control strategy based on sinusoidal function, which ensured the accuracy of the algorithm and at the same time improved the convergence speed of the algorithm [39]. In 2022, Abirami et al. combined DMOA with Gaussian Convolution Deep Confidence Networks for effective classification and extraction of retinal images to examine diabetic retinopathy [40]. In 2023, Almutairi et al. introduced quantum techniques to DMOA, which accelerated the convergence of the algorithm at a later stage [41]. In 2023, Rizk-Allah et al. used a modified DMOA to identify unknown parameters of an computational and physical elements model (single-phase transformer) and to evaluate the aging trend of the transformer at the hottest temperature [42].

Throughout the research status at domestic and abroad, the research on DMOA is mainly carried out in the following two aspects: one is to improve the performance of the basic algorithm for the deficiencies that exist, and a variety of different types of improved versions of DMOA have been proposed, the other is to broaden the scope of application of DMOA. With the deepening of the research, it can be found that although there are more literature on the improvement of DMOA performance, through a large number of numerical examples of experiments and comparative analysis found that DMOA still exists in the exploration and exploitation capacity is difficult to achieve the balance; easy to fall into the local optimum and late convergence of the slow speed and other shortcomings, and single-objective algorithms of the application of the scope of a certain degree of restriction. In this study, the shortcomings of the DMOA are as follows:

(1) EDMOA is proposed, which introduces nonlinear convergence factors and Markov Chain ideas in the original DMOA to accelerate the convergence speed of the algorithm, solve the problem of imbalance between the detection and exploitation capabilities, and improve the ability of the algorithm to jump out of the local optimal solution. In order to solve more practical application problems, EDMOA is designed to EMOA. The performance and application range of DMOA are comprehensively improved.

(2) Evaluate the performance of the proposed algorithm. Theoretically analyze the time complexity of the algorithm and test the performance of the algorithm using the CEC2020 multi-objective multi-modal optimization benchmark function.

(3) The proposed algorithm is used for the optimal deployment of SDFWSN. The results obtained in this study are of great theoretical significance and application prospects for advancing the development of the discipline of modern intelligent optimization technology.

3 Network Model and Problem Formulation

In this section, based on the data fusion wireless sensor network model proposed in [5], a stochastic data fusion network model is proposed by considering the effect of the environment on sensor sensing and defining the objective function to optimize this network model.

A data fusion network consists of many distributed sensor nodes. The key objective is to integrate dispersed information from multiple nodes to obtain more comprehensive and reliable information. First, there is data collection and pre-processing. The information collected by the sensor nodes may contain noise or redundancy due to signal attenuation. Pre-processing of the data through noise filtering, anomaly detection, and data correction provides a reliable data source for subsequent data fusion, $\omega(\cdot)$ will be defined as a signal attenuation function. Second, data merging and data fusion are performed. Multiple sensor nodes may collect the same or similar data. The sensor measurements are weighted. Decision-making and reasoning are performed again. The goal of data fusion is to make decisions or reasons based on the results of data fusion. By setting a threshold, a judgment can be made based on the fusion results as to whether a target state or event has occurred. Compared with traditional wireless sensor networks, data fusion-based wireless sensor networks have stronger data transmission reliability, lower transmission latency, and wider coverage.

3.1 Description and Assumptions of the Model

3.1.1 Stochastic Perception

If the sensor detects the target area by detecting the energy of the signal emitted from the target point, the true energy of the signal received by the sensor is affected by the environment. The energy of most physical signals' decays with increasing distance from the source, and the sensing ability of the sensor decreases with increasing temperature and decreasing humidity. Assume that the sensor i is d_i meters from a target that emits a signal with energy s_0 , and the temperature in the environment is Te and the humidity is RH . The real signal energy received by the sensor i from the target point is s_i and s_i is given by the Eq. (1).

$$s_i = s_0 \cdot \omega(d_i) \cdot \xi(T_e) \cdot \zeta(RH) \quad (1)$$

where $\omega(\cdot)$ is a signal attenuation function satisfying $\omega(0) = 1$, $\omega(\infty) = 0$ and $\omega(x) = \theta(x^{-k})$. Depending on the environment (e.g., atmospheric conditions), the path loss exponent of the signal k is usually between 2.0 and 5.0 [43]. $\xi(\cdot)$, $\zeta(\cdot)$ is a nonlinear increasing and nonlinear decreasing function given by the sensor manufacturer.

3.1.2 Data Fusion

When a sensor detects a target point P , sensors within R meters of the target point P form a cluster, a cluster head is selected to fuse the sensor measurements, and the monitoring decision is made by comparing the measurements with the monitoring threshold t . Let Y be the fusion statistic, i.e., $Y = \sum_{i \in F(P)} Y_i$. When $Y \geq t$, the cluster head decides H_1 that the target is detected; otherwise, it decides H_0 that the target is not detected. $F(P)$ denotes the set of sensors within the R fusion range and $N(P)$ denotes the number of sensors in the fusion range.

3.1.3 Energy Loss

The energy loss model is used to calculate the energy loss during the communication of each sensor node [44,45]. Two-channel propagation models are used, the multipath fading channel model (d^4 power loss) for transmitting packets over multiple hops and the free-space model (d^2 power loss) for single-hop or direct transmission. Thus, the amount of energy dissipated by the transmission of l bit packet over the distance d is given by Eq. (2).

$$E_{TX}(l, d) = \begin{cases} lE_{elec} + lE_{fs}d^2, & d < d_0 \\ lE_{elec} + lE_{mp}d^4, & d \geq d_0 \end{cases} \quad (2)$$

where E_{mp} is multipath energy loss and E_{fs} is free space energy loss. E_{elec} is electronic energy. d is the distance between the source and destination nodes and d_0 is calculated by Eq. (3).

$$d_0 = \sqrt{\frac{E_{fs}}{E_{mp}}} \quad (3)$$

The equation for energy dissipation in radio reception (E_{RX}) is given by Eq. (4).

$$E_{RX}(l) = lE_{elsc} \quad (4)$$

3.1.4 Network Deployment

This article deployed the network in a two-dimensional region where sensors are uniformly and independently distributed. If any two nodes can communicate with each other, the connectivity of the network is ensured by computing the adjacency matrix of the SDFWSN. T_D is the monitoring cycle of the sensor, and the sensor performs a monitoring task every T_D seconds. In each monitoring cycle, the sensor collects the target signal energy for target monitoring within a sampling interval, which is much shorter than the detection cycle, target monitoring within a detection cycle is called unit detection, and the process of detecting a target consists of a series of unit detections.

3.2 Symbols and Definitions

3.2.1 Description of Symbols

Table 1 explains the symbol applied in this paper.

Table 1: Definition of symbol

Notation	Define
$\omega(\cdot)$	Signal attenuation function, $w(x) = \theta(x^{-k})$
$\xi(\cdot)$	Nonlinear increasing function
$\zeta(\cdot)$	Nonlinear decreasing function
$o(\cdot)$	Asymptotic upper bound symbol
$\theta(\cdot)$	Asymptotic tight bounding symbol
$Q(X)$	Standard normal distribution
s_0	Raw signal energy emitted by the target
μ, σ^2	Mean and variance of noise energy

(Continued)

Table 1 (continued)

Notation	Define
Y	Signal energy measurement, $y_i = s_i + n_i$
α/β	P_F/P_D Upper/lower limit of
H_0/H_1	Target does not exist/exists
ρ	Network density
$F(P)$	A collection of sensors within the P point fusion range
$N(P)$	Number of sensors in $F(P)$
T	Network coverage detection interval
T_D	Monitoring cycle
R	Data fusion radius
c	Spatial coverage of the network
τ	Average network detection delay
n_i	Noise energy, $n_i \sim N(\mu, \sigma^2)$

3.2.2 Definition of Terms

Definition 1. ((α, β) – covered) For a target point P to be detected, if the false alarm rate P_F and the detection probability $P_D(p)$ satisfy $P_F \leq \alpha$, $P_{D(p)} \geq \beta$, where $\alpha \in (0, 0.5)$ and $\beta \in (0.5, 1)$, then the target point P is (α, β) – covered.

Definition 2. (Spatial coverage) The percentage of target points in the target area that are covered by (α, β) – covered.

Definition 3. (α – delay) The α – delay is the average number of detection cycles from the first detection to the target provided that P_F is not greater than α .

Definition 4. (Temporal coverage) Time Override is the inverse of α – delay.

Definition 5. (False alarm rate P_F) P_F is the probability that the sensor determines the presence of a target point when no target point is present.

Definition 6. (Detection rate P_D) P_D is the probability that a target point is present, and the sensor detects it.

3.3 Derivation of the Fitness Function

3.3.1 Objective 1. Maximize Network Lifecycle

The network lifecycle is an important metric for measuring the merits of a network deployment. The network coverage should at least exceed a given threshold to ensure the proper operation of the wireless sensor network [46]. So, in this paper, the network lifecycle is defined as the time from the initialization of the network to the time when the minimum threshold value of network coverage cannot be met. The network is tested for coverage at every interval of T time, assuming that the network does not satisfy the coverage minimum threshold value when it is detected at the first n time, then the network lifecycle is judged to be over then the network life cycle can be defined as Eq. (5).

$$LT = \sum_{i=1}^n T_i \quad (5)$$

3.3.2 Objective 2. Maximize Spatial Coverage

The spatial coverage of the unified deployment network under the stochastic data fusion model, denoted by is c as Eq. (6).

$$c \cong Q \left(\frac{\gamma(R) - \rho\pi R^2}{\sqrt{\rho\pi R^2}} \right) \quad (6)$$

$$\gamma(R) = \left(\frac{Q^{-1}(\alpha)\sigma - Q^{-1}(\beta)\sqrt{\sigma_s^2 + \sigma^2}}{\mu_s} \right)^2 \quad (7)$$

where μ_s , σ_s^2 are given by Eqs. (12) and (13).

3.3.3 Objective 3. Maximize Temporal Coverage

The temporal coverage of the unified deployment network under the data fusion model, denoted by is τ as in Eq. (8).

$$\tau = 1/E[P_D] \quad (8)$$

$$E[P_D] = \sum_{N_j=0}^N P_{Dj} \cdot f_{Poi}(N_j|\rho\pi R^2) \quad (9)$$

where $E[P_D]$ is the average detection probability of any unit detection, N_j obeys the Poisson distribution, i.e., $N_j \sim \text{Poi}(\rho\pi R^2)$, where $f_{\text{Poi}}(k|\lambda)$ is the probability density function of the Poisson distribution $\text{Poi}(\lambda)$. Where $f_{\text{Poi}}(k|\lambda) = \lambda^k e^{-\lambda}/k!$, P_{Dj} are defined as Eq. (11).

3.3.4 Objective 4. False Alarm Rate P_F Minimize

The false alarm rate is the probability of false detection by the network and reducing the false alarm rate of the network means increasing the confidence of the network's detection results. Let F_j be the set of sensors in the fusion range in the j th unit detection and there are N_j sensors in F_j . When the target is not present, we have $Y|H_0 = \sum_{i \in F_j} n_i \sim N(N_j\mu, N_j\sigma^2)$ where n_i the noise energy is experienced by sensor i . This article assumes that the noise n_i at each sensor i obeys a normal distribution, i.e., $n_i \sim N(\mu, \sigma^2)$. The false alarm rate for the j th unit detection P_{Fj} can be defined as Eq. (10).

$$P_{Fj} = P(Y \geq \eta|H_0) = Q \left(\frac{T - N_j\mu}{\sqrt{N_j}\sigma} \right) \quad (10)$$

3.3.5 Objective 5. Detection Rate P_D Maximization

The false alarm rate and the detection rate are independent of each other and increasing the detection rate improves the quality of the network in detecting target points. When the target is present, the sum of energy measurements in the j th unit detection approximately obeys a normal distribution $Y|H_1 = \sum_{i \in F_j} s_i +$

$\sum_{i \in F_j} n_i \sim N(N_j\mu_s + N_j\mu, N_j\sigma_s^2 + N_j\sigma^2)$ the j th unit detection rate can be defined as Eq. (11).

$$P_{Dj} = P(Y \geq T|H_1) \approx Q \left(\frac{T - N_j\mu_s - N_j\mu}{\sqrt{N_j} \cdot \sqrt{\sigma_s^2 + \sigma^2}} \right) \quad (11)$$

where μ_s, σ_s^2 denote the mean and variance, respectively, of $s_i | i \in \mathbf{F}(p)$ for any point P . μ_s, σ_s^2 given by Eqs. (12) and (13).

$$\mu_s = \frac{2S_i}{R^2} \cdot \int_0^R x \omega(x) \xi(x) \zeta(x) dx \quad (12)$$

$$\sigma_s^2 = \frac{2S_i^2}{R^2} \cdot \int_0^R x \omega^2(x) \xi^2(x) \zeta^2(x) dx - \mu_s^2 \quad (13)$$

3.4 Problem Description

As mentioned above, under the constraints of complete coverage of the monitoring area and network connectivity, this article investigates the SDFWSN deployment problem by jointly optimizing the five objectives of the network lifecycle, spatiotemporal coverage, false alarm rate, and detection rate. In summary, the SDFWSN deployment problem can be formulated as follows (Eq. (14)):

$$\begin{aligned} & \{ \max(LT), \min(P_{Fj}), \max(P_{Dj}), \max(c), \max(\tau) \} \\ & \text{s.t. } C(G_{\text{SDFWSN}}) = 1 \end{aligned} \quad (14)$$

where $C(G_{\text{SDFWSN}}) = 1$ indicates that the network satisfies the connectivity condition.

4 Proposed EMODMOA Algorithm Design Process and Method

This section describes algorithms to solve the problem of sensor deployment in SDFWSN. Considering that Eq. (14) in which the multi-objective optimization problem is a non-convex, discontinuous, multi-modal, and NP-hard problem, this article proposes EMODMOA to solve it. In this section, firstly, the DMOA algorithm is briefly described, secondly, improvement strategies for the algorithm are presented, and finally, EMODMOA is introduced in detail, including the initialization of the algorithm, the iterative process, and the strategy of sub-generation generation. Based on this, the optimal deployment method of SDFWSN based on EMODMOA is further proposed. And the analysis of EMODMOA time complexity is given.

4.1 DMOA

DMOA is a population intelligence optimization algorithm proposed in 2022 by Agushaka et al. DMOA is inspired by the semi-nomadic and compensatory adaptive behavior of dwarf mongoose populations. The algorithm has a strong global search capability. The algorithm is divided into four main phases, searching for food, searching for mounds (exploitation phase), babysitter exchange, and choosing mounds (exploration phase) [13].

(1) Food search phase:

The algorithm divides the mongoose into an alpha group (scouting group) and a babysitter group based on their compensatory adaptive behavior, and the alpha group searches for the location of the optimal food during the food search phase. The alpha group leader is selected according to Eq. (15) and the individual position update formula is given by Eq. (16).

$$\alpha = \frac{fit_i}{\sum_{i=1}^n fit_i} \quad (15)$$

$$X_{i+1} = X_i + ph_i * peep \quad (16)$$

where ph_i is a uniformly distributed random number $[-1, 1]$ and $peep$ is the sound made by the alpha female.

(2) Mounds search phase:

The scouting group is responsible for finding the sleep mounds, and evaluation formula for individual sleep mounds as Eq. (17). Evaluation formulas for population sleep mounds are given by Eq. (18).

$$sm_i = \frac{(fit_{i+1} - fit_i)}{\max\{fit_{i+1}, fit_i\}} \quad (17)$$

$$\phi = \frac{\sum_{i=1}^n sm_i}{n} \quad (18)$$

where fit_{i+1} , fit_i denote the fitness values of the mongoose's new position and the original position respectively.

(3) Babysitter exchange phase:

Once the babysitter swap conditions are met, the babysitter group and alpha (scout) group will swap identities. Initialize the mongoose's new location as Eq. (19).

$$x_{i,j} = \text{unifrnd}(\text{VarMin}, \text{VarMax}, \text{VarSize}) \quad (19)$$

(4) Mounds choose phase:

During this phase, an individual chooses an optimal sleep mound to perch on, and the individual position equation is as follows Eq. (20). Where M is given by Eq. (21), CF is the adaptive operator and the formula is as Eq. (22).

$$X_{i+1} = \begin{cases} X_i - CF * phi * rand[X_i - M], & \text{if } \phi_{i+1} > \phi_i \\ X_i + CF * phi * rand[X_i - M], & \text{otherwise} \end{cases} \quad (20)$$

$$M = \frac{\sum_{i=1}^n X_i * sm_i}{X_i} \quad (21)$$

$$CF = \left(1 - \frac{iter}{Max_{iter}}\right)^{\left(2 \frac{iter}{Max_{iter}}\right)} \quad (22)$$

The DMOA pseudo-code is shown in Algorithm 1.

Algorithm 1: DMOA

```

01 Input:  $peep, nPop, bs, L, nAlphaGroup$ 
02 Initialize the algorithm solutions,  $Cbest$  and  $Gbest$ .
03 While ( $iter < Maxiter$ ) do
04   Set alpha use Eq. (15)
05   Create new position use Eq. (16)
06   Calculate sleeping mound use Eq. (17)
07   Calculate average sleeping mound use Eq. (18)
08   Set time counter  $C = C + 1$ .
09   if  $C > L$ 
10     Initialize the DMOA population use Eq. (19)

```

(Continued)

Algorithm 1 (continued)

```

11  Set  $C = 0$ 
12  end if
13  Update solutions position use Eq. \(20\)
14   $iter = iter + 1$ 
15  end while
16  Output: Return the most effective solution  $x$ .

```

4.2 EDMOA

This subsection describes the proposed EDMOA algorithm, and the new algorithm focuses on the improvement of the original algorithm for the shortcomings that it is easy to fall into local optimal solutions, slow convergence, and imbalance between exploration and exploitation.

Encircling and Hunting Strategy

Because the dwarf mongoose has the characteristic of rounding up foraging, an encircling and hunting strategy is proposed based on the biological characteristics of the dwarf mongoose to better simulate the biological behavior of the dwarf mongoose. This strategy draws inspiration from the grey wolf optimization algorithm. First, three optimal markets are selected as P_α , P_β and P_δ . Distances between individual mongoose and among them are computed as per [Eqs. \(23\)–\(25\)](#).

$$d_\alpha = |c_1 \cdot P_\alpha - x_i| \quad (23)$$

$$d_\beta = |c_2 \cdot P_\beta - x_i| \quad (24)$$

$$d_\delta = |c_3 \cdot P_\delta - x_i| \quad (25)$$

where c_1 , c_2 and c_3 is random numbers within the range of $[0, 1]$ are used to randomly select three non-optimal mongoose, P_1 , P_2 and P_3 from the remaining $n - 3$ individuals. These selected mongooses undergo computations as per [Eqs. \(26\)–\(28\)](#).

$$P_1 = \phi \cdot P_{r1} - r \cdot (d_\alpha) \quad (26)$$

$$P_2 = \phi \cdot P_{r2} - r \cdot (d_\beta) \quad (27)$$

$$P_3 = \phi \cdot P_{r3} - r \cdot (d_\delta) \quad (28)$$

where r_1 , r_2 and r_3 is random numbers within the range of $[0, 1]$, r is random numbers within the range of $[-1, 1]$, $\phi = e^{-0.05 \cdot t}$.

The mongoose individuals are updated according to [Eq. \(29\)](#).

$$x_{i+1} = \frac{P_1 + P_2 + P_3}{3} \quad (29)$$

The pseudo-code of the EDMOA algorithm is as follows (Algorithm 2):

Algorithm 2: EDMOA

```

01 Input: Set the conditions and solutions for the algorithm.
02 Initialize the algorithm parameters and solutions.
03 Set  $nAlpha = nScout = 90\% \times nPop$ ,  $nBabysitter = nPop - nAlpha$ 

```

(Continued)

Algorithm 2 (continued)

```

04 while ( $iter < Max_{iter}$ ) do
05   Set alpha use Eq. (15)
06   if  $rand > 0.7$ 
07     Update the solutions' positions using Eq. (16)
08   else
09     Update the solutions' positions using Eq. (21)
10   end if
11     Calculate sleeping mound use Eq. (17)
12     Calculate average sleeping mound use Eq. (18)
13     Set time counter  $C = C + 1$ 
14   if  $C < L$ 
15     Update the solutions' positions using Eq. (20)
16   end if
17     Update solutions position use Eq. (29)
18      $iter = iter + 1$ 
19 end while
20 Output: Return the most effective solution ( $x$ ).

```

EDMOA update flowchart is shown in Fig. 1.

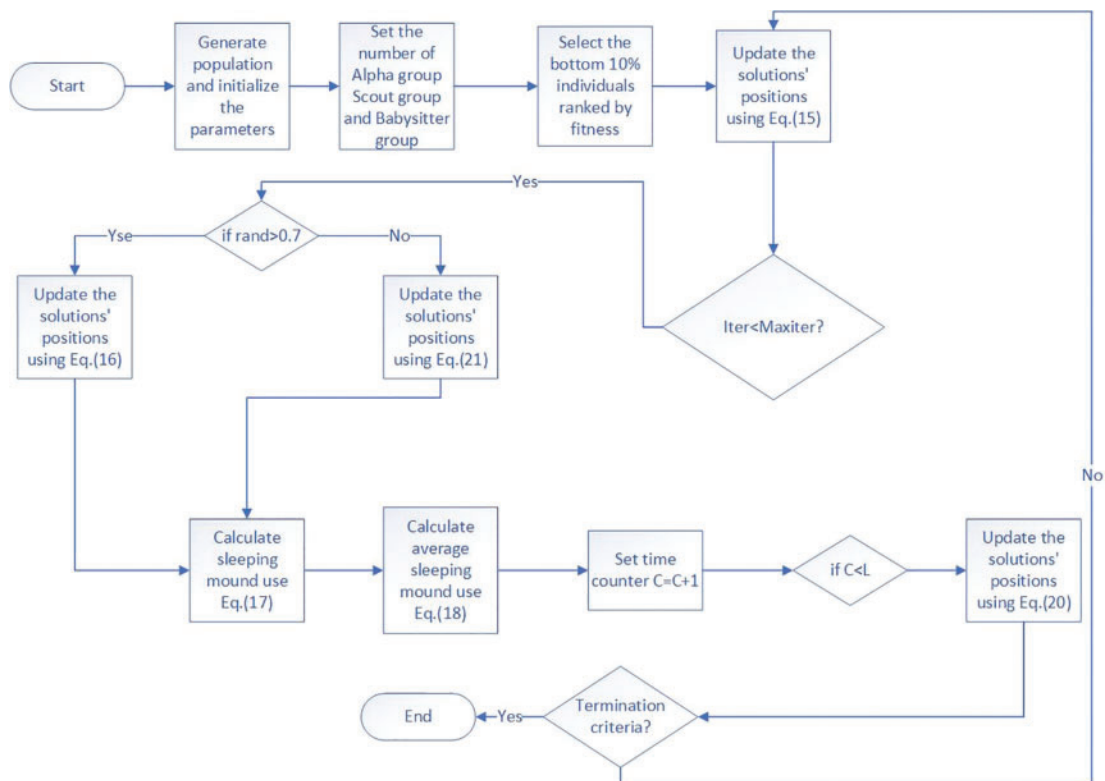


Figure 1: Flowchart of EDMOA

4.3 EMODMOA

The design of EMODMOA refers to the algorithm framework of NSGAIII, but in the selection of reference points, the classification algorithm KNN is used to classify individuals close to the reference points, select individuals in small categories, ensure the diversity of the population, and reduce the complexity of the algorithm. The pseudo-code of EMODMOA is shown in Algorithm 3, and the algorithm flowchart is as follows:

Algorithm 3: EMODMOA

```

01 Input: Population  $P_t$ ,  $H$  structured reference points  $N_c$ .
02 Initialization ( $P_t$ ,  $H$ ).
03 while ( $iter < MAXiter$ ) do
04    $Q_t = EDMOA(P_t)$ 
05    $R_t = P_t \cup Q_t$ 
06    $(F_1, F_2, \dots) = \text{Non-dominated sort}(R_t)$ .
07   repeat
08      $S_t = S_t \cup F_i$  and  $i = i + 1$ 
09   Until  $|S_t| \geq N$ .
10   Last floor to be included:  $F_l = F_i$ 
11   if  $|S_t| = N$  then
12      $P_{t+1} = S_t$ 
13   else
14      $P_{t+1} = \cup_{j=1}^{l-1} F_j$  and  $K = N - |P_{t+1}|$ 
15     Normalize-objectives  $P_t = \text{Normalize}(S_t, N_c)$ 
16     Classify based on each reference point  $[\pi(s), d(s)] = \text{KNN}(S_t, N_c)$ .
17     Compute niche count of reference point  $j \in N_c$ 
18     Choose  $K$  members from  $F_l$ 
19   end if
20    $iter++$ 
21 end while
22 Output: Next Population  $P_{t+1}$ .

```

Algorithm 3 is the pseudo-code of EMODMOA, in EMODMOA P_t is the parent of t th generation of size N and its generated child is Q_t which is also of size N . Combining the child and the parent generates R_t of size $2N$ and selects N individuals from it. To implement this selection process, R_t is first divided into multiple non-dominated layers $(F_1, F_2, \dots)$ by non-dominated ordering. The members of the populations in the non-dominated stratum rank 1 to l are put into S_t in order, and if $|S_t| = N$, the following operation is not necessary, and $P_{t+1} = S_t$ directly. If $|S_t| > N$, then a part of the next generation is solved as $P_{t+1} = \cup_{j=1}^{l-1} F_j$, and the remaining part ($K = N - |P_{t+1}|$) is chosen from F_l . The selection principle is to classify according to the KNN algorithm, selecting individuals that are far from the reference point, thereby maintaining the diversity of the solution.

The SDFWSN is deployed on a $4000 \text{ m} \times 4000 \text{ m}$ static node grid. The false alarm rate of each node is lower than 0.05 detection rate is higher than 0.95. The optimization process for the deployment of a stochastic fused wireless sensor network consisting of 220 nodes using EMODMOA is as follows:

Step 1. Initialize the parent population P_t and the reference point N_c . P_t is denoted as follows:

$$P_t = [X_1, X_2, \dots, X_N]^T \quad (30)$$

where $X_i = [x, y, R_c, n]$ is the i th individual in the population P_t representing a feasible deployment of a wireless sensor network. n is the number of sensors in the network, x and y are n dimensional column vectors, and R_c is the connectivity radius of the network.

Step 2. Generate child population Q_t by updating iteration of parent population P_t using EDMOA and merge the parent and child populations into R_t .

Step 3. Generate a Pareto frontier by the non-dominated ordering of R_t .

Step 4. Starting from the first Pareto frontier select individuals to population S_t until the number of S_t is greater than or equal to the initial population size.

Step 5. Use KNN to select individuals in the selected last Pareto frontier to join the population S_t until the number of S_t is equal to the initial population size. The population S_t is the deployment scheme of SDFWSN.

The EMODMOA flowchart is shown in Fig. 2.

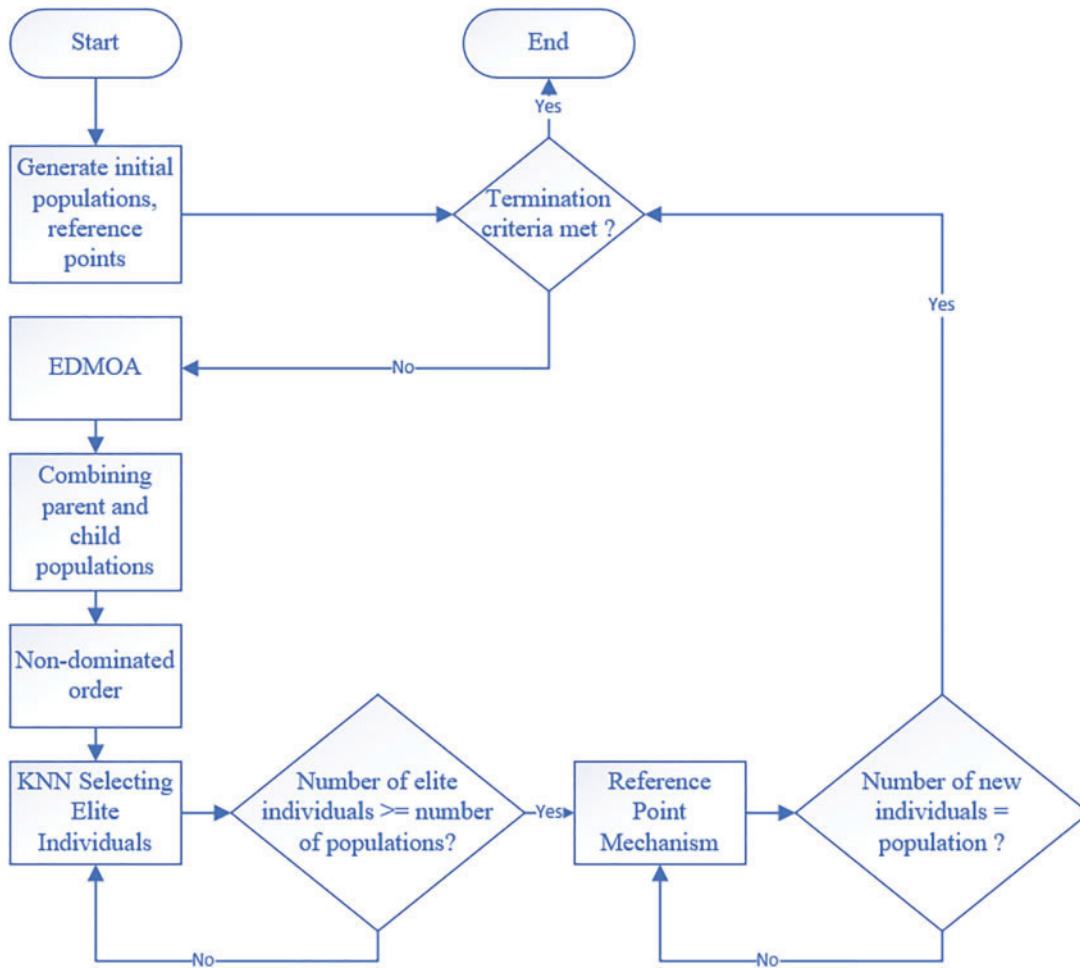


Figure 2: Flowchart of EMODMOA

5 Function Performance Testing

In this section, the performance of the proposed EMODMOA is examined using the CEC2020 multi-objective multi-modal optimization benchmark function. This benchmark function contains 24 different types of test functions for convex and concave, linear and nonlinear. Each function corresponds to objective space and decision space with optimal Pareto front (PF) and multiple local or global optimal PS sets. The performance metrics we use in the objective space are the hypervolume inverse (rHV) [47] and the Inverted Generational Distance (IGDF) [48]; in the decision space we use the inverse of the Pareto Strength Pareto (rPSP) [49] and the Inverted Generational Distance (IGDX) [48] as performance metrics. The system configuration of this experimental platform is shown in Table 2.

Table 2: System performance

Experimental environment	Setting
Software	
Operating system	Windows 10
Language	MATLAB R2022a
Hardware	
CPU	Intel Core (TM) i7-4210U
Frequency	2.4 GHz
RAM	4 GB
Hard drive	1 TB

The proposed algorithms are compared with 10 mainstream multi-objective algorithms including Multiple Objective Particle Swarm Optimization (MOPSO), Multi-objective Marine Predators Algorithm (MOMPA), Multi-Objective Evolutionary Algorithm based on Decomposition (MOEA/D), Non-dominated Sorting Genetic Algorithm II (NSGAI), Strength Pareto Evolutionary Algorithm 2 (SPEA2), Nominal Diameter Non-dominated Sorting Genetic Algorithm II (DN-NSGA-II), Multi-Strategy Salp Swarm Algorithm (MSSA), Multi-Objective Grey Wolf Optimizer (MOGWO), Multi-Objective Mayfly Algorithm (MOMA) and optimal mini niche Non-dominated Sorting Genetic Algorithm (OMNI). The parameters of each algorithm are set in Table 3. Each algorithm was run independently 21 times with 100 iterations and the mean and variance values obtained from each function test were recorded. “+”, “=” and “–” indicate that EMODMOA performs better than, equal to, and worse than the other algorithms, respectively.

Table 3: Algorithm parameter design

Algorithms	Parameter	Value
EMODMOA	Peep	2
	Population size	400
NSGAI	Crossover probability	0.9
	Mutation probability	0.1
MOMPA	Archive size	200
	Fish aggregating devices	0.3
	P	0.4

(Continued)

Table 3 (continued)

Algorithms	Parameter	Value
	Population size	400
MOMA	Population size	400
	Cognitive and social learning factors	2
MOPSO	Archive size	200
	Population size	400
	Deletion selection pressure	2
	Leader selection pressure	2
	Grid inflation rate	0.1
	Inertia weight (w)	0.5
	Number of grids per dimension	10
	Mutation rate	0.1
OMNI	Population size	400
	Neighborhood radius	2
	Preference information	0.2
MOGWO	Archive size	200
	Population size	400
	Deletion selection pressure	2
	Number of grids per dimension	10
	Leader selection pressure	4
	Grid inflation rate	0.1
MSSA	Archive size	200
	Population size	400
SPEA2	Crossover probability	0.9
	Mutation probability	0.1
	Population size	400
MOEA/D	Archive size	200
	Population size	400
	Crossover parameter	0.5
	Number of neighbors	15
DN-NSGA-II	Crossover probability	0.9
	Mutation probability	0.1
	Crowding factor	200
	Population size	400

Tables 4–7 show mean, and standard deviation results obtained by the algorithms on different performance metrics, with each row in black font indicating the optimal result for the corresponding test function. The last row of the table records the performance comparison between EMOA and the other algorithms on each test problem.

Table 4: rHV test results

Problem	EMODMOA	EMODMOA vs. MOPSO	EMODMOA vs. NSGA-II	EMODMOA vs. MOEA/D	EMODMOA vs. SPEA2	EMODMOA vs. OMNI	EMODMOA vs. MSSA	EMODMOA vs. MOWGO	EMODMOA vs. DN-NSGA-II	EMODMOA vs. MOMPA
MMF1	Mean	1.1550	1.1438	1.1631	1.1543	1.1443	1.7110	1.1412	1.1449	1.1447
	Std	0.0036	0.0005	0.0133	0.0004	0.0007	0.0038	0.0010	0.0009	0.0004
MMF2	Mean	1.3272	1.1577	1.3007	1.1777	1.1519	1.1707	1.1662	1.1639	1.1516
	Std	0.0444	0.0923	0.0152	0.0061	0.0052	0.0060	0.0052	0.0001	0.0001
MMF4	Mean	1.8612	1.8466	1.8721	1.8509	1.8476	1.9499	1.8531	1.8491	1.8528
	Std	0.0050	0.0232	0.0030	0.0181	0.0004	0.0041	0.0002	0.0000	0.0000
MMF5	Mean	1.1540	1.1433	1.1692	1.1433	1.1438	1.1718	1.1449	1.1444	1.1447
	Std	0.0028	0.0176	0.0004	0.0065	0.0007	0.0003	0.0007	0.0000	0.0000
MMF7	Mean	1.1492	1.1431	1.1538	1.1440	1.1437	1.1680	1.1452	1.1449	1.1442
	Std	0.0023	0.0083	0.0002	0.0044	0.0005	0.0004	0.0005	0.0000	0.0000
MMF8	Mean	2.4503	2.3634	2.3990	2.3841	2.3648	2.4727	2.3751	2.3648	2.3706
	Std	0.0001	0.0003	0.0002	0.0004	0.0001	0.0001	0.0001	0.0000	0.0000
MMF10	Mean	0.0271	0.0260	0.0112	0.0523	0.0017	0.0824	0.0783	0.0777	0.0770
	Std	0.0811	0.0805	0.0893	0.0787	0.0824	0.0824	0.0783	0.0777	0.0770
MMF11	Mean	0.0039	0.0052	0.0017	0.0021	0.0001	0.0697	0.0689	0.0689	0.0689
	Std	0.0689	0.0689	0.0710	0.0689	0.0689	0.0697	0.0689	0.0689	0.0689
MMF12	Mean	0.0001	0.0008	0.0000	0.0000	0.0000	0.6485	0.6378	0.6358	0.6368
	Std	0.6346	0.6357	0.6596	0.6367	0.6528	0.0546	0.0520	0.0543	0.0543
MMF13	Mean	0.0002	0.0243	0.0496	0.0064	0.0002	0.0546	0.0520	0.0462	0.0462
	Std	0.0518	0.0543	0.0559	0.0543	0.0543	0.0546	0.0520	0.0462	0.0462
MMF14	Mean	0.0000	0.0000	0.0000	0.0000	0.0000	0.3508	0.3553	0.3415	0.3323
	Std	0.3110	0.3529	0.3508	0.4016	0.3347	0.2493	0.2460	0.2340	0.2262
MMF15	Mean	0.0073	0.0097	0.0514	0.0084	0.0129	0.2493	0.2460	0.2340	0.2262
	Std	0.2218	0.7923	0.2385	0.2675	0.2395	0.2493	0.2460	0.2340	0.2262
MMF15_e	Mean	0.0095	0.0062	0.0291	0.0084	0.0048	1.1642	1.1522	1.1469	1.1711
	Std	1.1508	1.1526	1.2658	1.1642	1.1848	1.1642	1.1522	1.1469	1.1711
MMF14_a	Mean	0.0010	0.0072	0.0095	0.0088	0.0157	0.3529	0.3553	0.3250	0.3601
	Std	0.3745	0.3484	0.3400	0.3923	0.3288	0.3529	0.3553	0.3250	0.3601
MMF15_a	Mean	0.0050	0.0188	0.0072	0.0142	0.0124	0.2388	0.2449	0.2281	0.2135
	Std	0.2493	0.2381	0.2317	0.2799	0.2364	0.2388	0.2449	0.2281	0.2135
MMF10_J	Mean	0.0124	0.0039	0.0113	0.0077	0.0034	0.0807	0.0780	0.0777	0.0777
	Std	0.0777	0.0908	0.0886	0.0781	0.0786	0.0807	0.0780	0.0777	0.0777
MMF11_J	Mean	0.0031	0.0022	0.0009	0.0008	0.0000	0.0692	0.0688	0.0688	0.0688
	Std	0.0695	0.0688	0.0703	0.0688	0.0688	0.0692	0.0688	0.0688	0.0688
MMF12_J	Mean	0.0001	0.0013	0.0004	0.0003	0.0021	0.6454	0.6362	0.6345	0.6357
	Std	0.6885	0.6352	0.6502	0.6354	0.6915	0.6454	0.6362	0.6345	0.6357
MMF13_J	Mean	0.0003	0.0028	0.0006	0.0055	0.0009	0.0545	0.0542	0.0547	0.0542
	Std	0.0544	0.0544	0.0551	0.0542	0.0547	0.0545	0.0542	0.0547	0.0542
MMF15_J	Mean	0.0001	0.0006	0.0002	0.0004	0.0008	0.0545	0.0542	0.0547	0.0542
	Std	0.0001	0.0006	0.0002	0.0004	0.0008	0.0545	0.0542	0.0547	0.0542
MMF15_a_J	Mean	0.2189	0.2374	0.2374	0.2431	0.2322	0.2452	0.2407	0.2343	0.2049
	Std	0.0093	0.0325	0.0325	0.0050	0.0074	0.2452	0.2407	0.2343	0.2049
MMF16_J1	Mean	0.0006	0.0048	0.0429	0.0044	0.0034	0.2393	0.2523	0.2673	0.2248
	Std	0.2271	0.2397	0.2352	0.2604	0.2296	0.2393	0.2523	0.2673	0.2248
MMF16_J2	Mean	0.0023	0.0047	0.0386	0.0060	0.0012	0.2338	0.2375	0.2332	0.2262
	Std	0.0057	0.0047	0.0386	0.0060	0.0012	0.2338	0.2375	0.2332	0.2262
MMF16_J3	Mean	0.2250	0.2349	0.0162	0.2514	0.2291	0.2338	0.2367	0.2321	0.2269
	Std	0.0018	0.0021	0.0162	0.2514	0.2291	0.2338	0.2367	0.2321	0.2269
MMF16_J3	Mean	0.2291	0.2350	0.2363	0.2548	0.2256	0.2323	0.2361	0.2335	0.2256
	Std	0.0088	0.0035	0.0025	0.0047	0.0048	0.2323	0.2361	0.2335	0.2256
+/ - / _{ns}		21/0/3	21/1/2	24/1/0	22/0/2	22/0/2	24/0/0	21/0/3	17/4/3	16/4/4

Table 5: IGDF test results

Problem	EMODMOA		EMODMOA vs. MOPSO		EMODMOA vs. NSGA-II		EMODMOA vs. MOEA/D		EMODMOA vs. SPEA2		EMODMOA vs. OMNI		EMODMOA vs. MSSA		EMODMOA vs. MCGWO		EMODMOA vs. MOMA		EMODMOA vs. DN-NSGA-II		EMODMOA vs. MOMPA	
MMF1	Mean	0.0011	0.0074	0.0016	0.0113	0.0002	0.0017	0.0018	0.0005	0.0000	0.0017	0.0002	0.0023	0.0181	0.0026	0.0017	=	0.0021	+	=	0.0000	
	Std	0.0000	0.0017	0.0002	0.0000	0.0002	0.0005	0.0018	0.0005	0.0000	0.0005	0.0002	0.0023	0.0026	0.0017	=	0.0021	+	=	0.0000		
	Mean	0.0040	0.0823	0.0062	0.0815	0.0002	0.0151	0.0028	0.0151	0.0025	0.0063	0.0063	0.0145	0.0123	0.0172	+	0.0126	+	=	0.0063		
MMF2	Mean	0.0030	0.0221	0.0171	0.0469	0.0088	0.0020	0.0028	0.0020	0.0025	0.0111	0.0009	0.0200	0.0023	0.0000	=	0.0016	+	+	0.0020		
	Std	0.0000	0.0037	0.0000	0.0042	0.0001	0.0017	0.0029	0.0004	0.0001	0.0014	0.0002	0.0200	0.0023	0.0000	=	0.0016	+	+	0.0020		
	Std	0.0008	0.0007	0.0000	0.0001	0.0001	0.0004	0.0029	0.0004	0.0001	0.0002	0.0002	0.0146	0.0021	0.0015	+	0.0018	+	+	0.0021		
MMF3	Mean	0.0016	0.0070	0.0003	0.0114	0.0001	0.0017	0.0021	0.0001	0.0001	0.0015	0.0002	0.0146	0.0021	0.0015	+	0.0018	+	+	0.0021		
	Std	0.0000	0.0014	0.0001	0.0009	0.0001	0.0005	0.0021	0.0001	0.0001	0.0002	0.0002	0.0146	0.0021	0.0015	+	0.0018	+	+	0.0021		
	Mean	0.0017	0.0045	0.0011	0.0074	0.0001	0.0017	0.0027	0.0017	0.0000	0.0015	0.0002	0.0159	0.0025	0.0011	-	0.0020	+	+	0.0019		
MMF4	Mean	0.0000	0.0036	0.0011	0.0043	0.0001	0.0017	0.0027	0.0006	0.0000	0.0002	0.0002	0.0119	0.0031	0.0016	+	0.0019	+	+	0.0025		
	Std	0.0001	0.0044	0.0001	0.0016	0.0003	0.0007	0.0020	0.0007	0.0002	0.0003	0.0002	0.0119	0.0031	0.0016	+	0.0019	+	+	0.0025		
	Mean	0.0019	0.1288	0.1193	0.3166	0.0001	0.0574	0.0876	0.0574	0.0221	0.1731	0.0010	0.1904	0.0473	0.0106	+	0.1710	+	+	0.0099		
MMF5	Mean	0.0009	0.1349	0.1163	0.0668	0.0091	0.0221	0.0876	0.0221	0.0224	0.0915	0.0010	0.0535	0.0140	0.0099	+	0.0138	+	+	0.0142		
	Std	0.0089	0.154	0.0210	0.1470	0.0002	0.0140	0.0085	0.0140	0.0007	0.0160	0.0025	0.1001	0.0675	0.0637	+	0.0953	+	+	0.0715		
	Mean	0.0001	0.0014	0.0899	0.0413	0.0010	0.0015	0.0085	0.0015	0.0006	0.0013	0.0021	0.0201	0.0047	0.0045	+	0.0029	+	+	0.0032		
MMF6	Mean	0.0001	0.0014	0.0122	0.0276	0.0002	0.0029	0.0037	0.0029	0.0014	0.0070	0.0003	0.0201	0.0047	0.0045	+	0.0029	+	+	0.0032		
	Std	0.0002	0.0118	0.0410	0.0003	0.0019	0.0007	0.0037	0.0007	0.0014	0.0003	0.0003	0.0650	0.0178	0.0135	+	0.0211	+	+	0.0184		
	Mean	0.0005	0.0233	0.0136	0.2294	0.0002	0.0171	0.0118	0.0171	0.0007	0.0160	0.0025	0.1001	0.0675	0.0637	+	0.0953	+	+	0.0715		
MMF7	Mean	0.0040	0.0301	0.8349	0.0664	0.0664	0.0113	0.0038	0.0113	0.0000	0.0064	0.0003	0.124	0.0049	0.0049	+	0.1633	+	+	0.1035		
	Std	0.0000	0.0272	0.0349	0.0664	0.0664	0.0113	0.0038	0.0113	0.0000	0.0064	0.0003	0.124	0.0049	0.0049	+	0.1633	+	+	0.1035		
	Mean	0.0518	0.0745	0.1177	0.0928	0.0928	0.2041	0.070	0.2041	0.030	0.0904	0.0120	0.1919	0.0694	0.0714	+	0.1047	+	+	0.1059		
MMF8	Mean	0.0009	0.0050	0.0083	0.0055	0.0256	0.0021	0.0070	0.0021	0.0030	0.0059	0.0093	0.1159	0.0694	0.0714	+	0.1047	+	+	0.1059		
	Std	0.00878	0.1157	0.1078	0.1354	0.0038	0.2813	0.070	0.2813	0.030	0.0059	0.0093	0.1159	0.0694	0.0714	+	0.1047	+	+	0.1059		
	Std	0.0004	0.0039	0.0120	0.0085	0.0409	0.0133	0.0182	0.0078	0.0030	0.0147	0.0157	0.1839	0.1115	0.0988	+	0.1664	+	+	0.1325		
MMF9	Mean	0.1837	0.1908	0.1878	0.1971	0.1971	0.2031	0.0182	0.2031	0.0030	0.0202	0.0157	0.2506	0.2035	0.1931	=	0.1986	+	+	0.1927		
	Std	0.0222	0.0094	0.0254	0.0380	0.0218	0.0023	0.0291	0.0023	0.0000	0.0406	0.0027	0.2506	0.2035	0.1931	=	0.1986	+	+	0.1927		
	Mean	0.1018	0.1605	0.2508	0.2078	0.2078	0.0928	0.0596	0.0928	0.0009	0.0908	0.0077	0.1272	0.0908	0.1449	+	0.0923	+	+	0.0926		
MMF10	Mean	0.0000	0.0009	0.0003	0.0886	0.0021	0.0004	0.0096	0.0004	0.0009	0.0005	0.0007	0.0941	0.0842	0.0870	+	0.0824	+	+	0.0830		
	Std	0.0469	0.0885	0.0014	0.2469	0.0021	0.00810	0.0096	0.00810	0.0009	0.0812	0.0004	0.0941	0.0842	0.0870	+	0.0824	+	+	0.0830		
	Std	0.0000	0.0014	0.0003	0.0088	0.0054	0.0000	0.0055	0.0000	0.0009	0.0008	0.0004	0.0941	0.0842	0.0870	+	0.0824	+	+	0.0830		
MMF11	Mean	0.1260	0.1443	0.2914	0.3125	0.3125	0.1479	0.0055	0.1479	0.0009	0.1453	0.0066	0.1830	0.1455	0.1446	+	0.1478	+	+	0.1467		
	Std	0.0000	0.0002	0.0092	0.1082	0.1082	0.0012	0.182	0.0012	0.0009	0.0028	0.0066	0.1830	0.1455	0.1446	+	0.1478	+	+	0.1467		
	Mean	0.1684	0.2374	0.2563	0.2123	0.2123	0.2653	0.0291	0.2653	0.0009	0.1898	0.0066	0.2506	0.1788	0.1802	+	0.2032	+	+	0.1881		
MMF12	Mean	0.0045	0.0125	0.0203	0.0053	0.0226	0.0061	0.0291	0.0061	0.0033	0.0077	0.0030	0.2506	0.1788	0.1802	+	0.2032	+	+	0.1881		
	Std	0.0045	0.0125	0.0203	0.0053	0.0226	0.0061	0.0291	0.0061	0.0033	0.0077	0.0030	0.2506	0.1788	0.1802	+	0.2032	+	+	0.1881		
	Mean	0.0054	0.0076	0.0076	0.0048	0.0429	0.0070	0.0096	0.0044	0.0021	0.1977	0.0077	0.1942	0.1687	0.1802	+	0.2134	+	+	0.1951		
MMF13	Mean	0.1337	0.1397	0.1775	0.1673	0.1673	0.2876	0.0096	0.2876	0.0041	0.1496	0.0045	0.2941	0.1380	0.1821	=	0.1593	+	+	0.1444		
	Std	0.0023	0.0057	0.0068	0.0034	0.0283	0.0059	0.0070	0.0060	0.0021	0.0073	0.0045	0.2941	0.1380	0.1821	=	0.1593	+	+	0.1444		
	Mean	0.2229	0.2349	0.3268	0.2574	0.2574	0.2872	0.0096	0.2872	0.0044	0.0081	0.0077	0.2830	0.2267	0.2300	+	0.2339	+	+	0.2380		
MMF14	Mean	0.0011	0.0021	0.0168	0.0032	0.0217	0.0071	0.0135	0.0048	0.0031	0.0081	0.0077	0.2830	0.2267	0.2300	+	0.2339	+	+	0.2380		
	Std	0.0011	0.0021	0.0168	0.0032	0.0217	0.0071	0.0135	0.0048	0.0031	0.0081	0.0077	0.2830	0.2267	0.2300	+	0.2339	+	+	0.2380		
	Mean	0.1621	0.2311	0.2311	0.2350	0.2350	0.2590	0.0077	0.2590	0.0047	0.1847	0.0047	0.2115	0.1780	0.1812	+	0.1902	+	+	0.1888		
Std	0.0010	0.0076	0.0088	0.0035	0.0035	0.0047	0.0077	0.0035	0.0047	0.0026	0.0047	0.0055	0.1780	0.1812	0.1812	+	0.1902	+	+	0.1888		
		23/0/1		19/2/1		24/0/0		23/0/1		23/0/1		24/0/0		23/0/1		19/1/4		24/0/0		20/0/4		
		+/+/-																				

Table 6: rPSP test results

Problem	EMODMOA	EMODMOA vs. MOPSO	EMODMOA vs. NSGA-II	EMODMOA vs. MOEA/D	EMODMOA vs. SPEA2	EMODMOA vs. OMNI	EMODMOA vs. MSSA	EMODMOA vs. MOGWO	EMODMOA vs. MOMA	EMODMOA vs. DN- NSGA-II	EMODMOA vs. MOMP
MMF1	Mean Std	0.0112 0.0165	0.0203 0.0677	0.0227 0.0086	0.0038 0.0088	0.0512 0.0073	0.0076 0.0851	0.0412 0.0341	0.0308 0.0391	0.0555 0.0643	0.0435 0.0344
MMF2	Mean Std	0.0310 0.0700	0.0551 0.4871	0.0028 0.0218	0.0417 0.0386	0.0010 0.0672	0.0851 0.2645	0.0341 0.0548	0.0391 0.0161	0.0643 0.0488	0.0344 0.0249
MMF4	Mean Std	0.0058 0.0095	0.0419 0.0915	0.0218 0.0039	0.0362 0.0277	0.0121 0.0011	0.0466 0.0234	0.0341 0.0548	0.0391 0.0161	0.0643 0.0488	0.0344 0.0249
MMF5	Mean Std	0.1504 0.0187	0.1365 0.0915	0.0086 0.0086	0.0564 0.0564	0.1123 0.1123	0.3668 0.0324	0.1017 0.0179	0.0540 0.0148	0.1173 0.0286	0.0809 0.0228
MMF7	Mean Std	0.0045 0.0093	0.0432 0.0057	0.0086 0.0071	0.0086 0.0071	0.0126 0.0035	0.2276 1.1381	0.0179 0.1801	0.0148 0.1336	0.0286 0.1340	0.0228 0.0651
MMF8	Mean Std	0.0539 0.1016	0.3092 0.7253	0.0046 0.5134	0.0945 0.5235	0.0009 0.1087	0.9045 0.1065	0.1308 0.0164	0.1336 0.0023	0.1340 0.1470	0.0651 0.0026
MMF10	Mean Std	0.0030 0.0015	0.1322 0.1662	0.0036 0.0332	0.0274 0.0223	0.0004 0.0004	0.1065 0.1031	0.0164 0.0049	0.0023 0.0034	0.1470 0.0046	0.0026 0.0039
MMF11	Mean Std	0.0030 0.0008	0.0053 0.0004	0.0036 0.0007	0.0033 0.0002	0.0003 0.0003	0.1031 0.0087	0.0049 0.0031	0.0034 0.0018	0.0046 0.0023	0.0039 0.0021
MMF12	Mean Std	0.0016 0.0002	0.0065 0.0039	0.0019 0.0313	0.0016 0.0136	0.0074 0.0003	0.0074 0.0087	0.0031 0.0031	0.0018 0.0462	0.0023 0.0743	0.0021 0.0348
MMF13	Mean Std	0.0518 0.0077	0.0873 0.0673	0.0280 0.0932	0.0280 0.0736	0.0797 0.0068	0.1107 0.0844	0.0709 0.1524	0.0462 0.0487	0.0743 0.0855	0.0348 0.0492
MMF14	Mean Std	0.0439 0.0017	0.0543 0.0073	0.0439 0.0415	0.0439 0.0415	0.0792 0.0064	0.0844 0.0896	0.1524 0.0557	0.0487 0.0467	0.0855 0.0811	0.0492 0.0490
MMF15	Mean Std	0.0018 0.0018	0.0071 0.0056	0.0059 0.0059	0.0059 0.0059	0.0046 0.0046	0.0896 0.6316	0.0557 8.2020	0.0467 2.4577	0.0811 1.2721	0.0490 1.6994
MMF1_e	Mean Std	1.4716 2.0148	2.7892 9.7638	3.2150 3.2150	13.6998 0.4693	1.848 0.8909	6.316 0.0055	8.2020 0.0094	2.4577 0.0767	1.2721 0.1055	1.6994 0.1232
MMF14_a	Mean Std	0.0000 0.0000	0.1149 0.0318	0.1698 0.1698	0.0038 0.0038	1.0001 0.0077	0.0055 0.1071	0.0094 0.0754	0.0767 0.0584	0.1055 0.1012	0.1232 0.0896
MMF15_a	Mean Std	0.0046 0.0039	0.0657 0.0116	0.0889 0.0341	0.0889 0.0341	0.0895 0.0895	0.1071 1.7836	0.0754 4.1183	0.0584 6.0297	0.1012 2.6129	0.0896 6.9792
MMF10_J	Mean Std	2.1267 3.0736	8.4507 0.4498	3.0627 3.0627	1.7055 0.3908	5.9067 3.1041	1.7836 2.0109	4.1183 1.7158	6.0297 2.0360	2.6129 2.0134	6.9792 2.1926
MMF11_J	Mean Std	0.910 1.6395	6.1345 3.2935	3.0627 3.0627	3.7084 3.7084	2.1233 2.1233	2.3451 2.0109	1.6316 1.7158	1.7849 2.0360	2.6304 2.6304	2.5664 2.5664
MMF12_J	Mean Std	0.5012 1.2885	6.1345 3.2935	1.5465 1.5465	0.0810 0.0810	0.1658 0.1658	0.6382 0.6382	0.6194 0.6194	0.5461 0.5461	0.5998 0.5998	0.5284 0.5284
MMF13_J	Mean Std	0.3201 0.3002	0.6699 0.9982	0.2460 0.2460	0.485 0.485	0.0338 0.0338	0.6244 0.6244	0.5230 0.5230	0.4680 0.4680	0.2884 0.2884	0.6478 0.6478
MMF15_J	Mean Std	0.1001 0.1974	0.2220 0.1974	0.0386 0.0386	0.0043 0.0043	0.0080 0.0080	0.2918 0.2918	0.2523 0.2523	0.2608 0.2608	0.2272 0.2272	0.2818 0.2818
MMF15_a_J	Mean Std	0.0225 0.1899	0.3225 0.2795	0.0429 0.0429	0.0081 0.0081	0.0150 0.0150	0.2034 0.2034	0.2260 0.2260	0.1951 0.1951	0.1962 0.1962	0.1979 0.1979
MMF16_J1	Mean Std	0.1114 0.1997	0.0114 0.1997	0.0048 0.0048	0.0048 0.0048	0.0075 0.0075	0.8076 0.8076	0.6860 0.6860	0.6670 0.6670	0.5043 0.5043	0.8651 0.8651
MMF16_J2	Mean Std	0.1610 0.7949	0.0057 0.7949	0.0352 0.0352	0.0043 0.0043	0.0126 0.0126	0.8076 0.8076	0.6860 0.6860	0.6670 0.6670	0.5043 0.5043	0.8651 0.8651
MMF16_J3	Mean Std	0.0328 0.1254	0.0611 0.2811	0.1893 0.1893	0.1324 0.1324	0.1884 0.1884	0.8076 0.8076	0.6860 0.6860	0.6670 0.6670	0.5043 0.5043	0.8651 0.8651
MMF16_J3	Mean Std	0.0000 0.0000	0.0001 0.0001	0.0387 0.0387	0.0387 0.0387	0.0029 0.0029	0.3042 0.3042	0.3646 0.3646	0.2839 0.2839	0.2706 0.2706	0.2877 0.2877
+/-/±		24/0/0	24/0/0	21/1/2	24/0/0	20/1/3	24/0/0	21/1/2	23/1/0	23/1/0	23/1/0

Table 7: IGDx test results

Problem		EMODMOA	EMODMOA vs. MOPSO	EMODMOA vs. NSGA-II	EMODMOA vs. MOEA/D	EMODMOA vs. SPEA2	EMODMOA vs. OMNI	EMODMOA vs. MSSA	EMODMOA vs. MOGWO	EMODMOA vs. MOMA	EMODMOA vs. DN- NSGA-II	EMODMOA vs. MOMPA
MMF1	Mean	0.0311	0.0896	0.0694	0.1977	0.0336	0.0503	0.2003	0.0411	0.0308	0.0549	0.0431
	Std	0.0001	0.0152	0.0512	0.0084	0.0087	0.0015	0.0070	0.0086	+	+	+
MMF2	Mean	0.0340	0.1591	0.0581	0.2856	0.0382	0.0605	0.0778	0.0341	0.0391	0.0591	0.0343
	Std	0.0340	0.0236	0.0581	0.0036	0.0099	0.0121	0.0144	0.0267	+	+	+
MMF4	Mean	0.0178	0.0418	0.0741	0.2382	0.0233	0.0432	0.2429	0.0541	0.0161	0.0487	0.0248
	Std	0.0008	0.0094	0.0552	0.0039	0.0386	0.0011	0.0051	0.0541	=	+	+
MMF5	Mean	0.0424	0.1447	0.0180	0.3564	0.0654	0.1111	0.3390	0.1013	0.0539	0.1162	0.0806
	Std	0.0000	0.0182	0.0117	0.0091	0.0321	0.0030	0.0123	0.1013	+	+	+
MMF7	Mean	0.0149	0.0410	0.0466	0.1311	0.0211	0.0251	0.1503	0.0266	0.0148	0.0280	0.0224
	Std	0.0000	0.0072	0.0056	0.0068	0.0077	0.0009	0.0034	0.0266	=	+	+
MMF8	Mean	0.0339	0.2874	0.6028	1.1175	0.7116	0.1285	0.7976	0.1681	0.1282	0.1316	0.0641
	Std	0.0001	0.1417	0.2147	0.0321	0.0995	0.0992	0.0165	0.1681	+	+	+
MMF10	Mean	0.0023	0.1299	0.1103	0.3201	0.0244	0.1684	0.1020	0.0143	0.0023	0.1402	0.0026
	Std	0.0009	0.1645	0.1215	0.1211	0.0174	0.0004	0.0005	0.0143	-	+	=
MMF11	Mean	0.0034	0.0053	0.0036	0.0089	0.0032	0.0044	0.0129	0.0049	0.0034	0.0046	0.0039
	Std	0.0002	0.0008	0.0017	0.0002	0.0024	0.0003	0.0006	0.0049	=	+	+
MMF12	Mean	0.0066	0.0065	0.0019	0.0136	0.0016	0.0074	0.0085	0.0031	0.0018	0.0023	0.0021
	Std	0.0002	0.0039	0.0044	0.0036	0.0027	0.0003	0.0002	0.0031	+	+	+
MMF13	Mean	0.0318	0.0748	0.0862	0.0599	0.0999	0.0744	0.1048	0.0561	0.0462	0.0735	0.0347
	Std	0.0000	0.0376	0.0163	0.0059	0.0271	0.0068	0.0042	0.0561	+	+	=
MMF14	Mean	0.0439	0.1543	0.0943	0.1406	0.2231	0.0805	0.0829	0.1535	0.0488	0.0843	0.0527
	Std	0.0035	0.0073	0.0263	0.0065	0.0054	0.0021	0.0058	0.1535	+	+	+
MMF15	Mean	0.0435	0.0470	0.0780	0.0635	0.1111	0.0725	0.0872	0.0565	0.0461	0.0803	0.0510
	Std	0.0018	0.0111	0.0030	0.0056	0.0101	0.0018	0.0087	0.0565	+	+	+
MMF1_e	Mean	2.0450	1.2301	0.4297	3.3005	2.1093	1.0105	2.3708	2.4466	1.3091	0.9863	1.1350
	Std	0.2921	0.0072	0.5774	0.7999	0.3671	0.4654	0.4837	2.4466	+	+	-
MMF14_a	Mean	0.0500	0.1115	0.1177	0.1523	0.2300	0.1004	0.1337	0.1283	0.0764	0.1045	0.1221
	Std	0.0030	0.0083	0.0273	0.0093	0.0062	0.0054	0.0120	0.1283	+	+	+
MMF15_a	Mean	0.0504	0.1157	0.1052	0.0870	0.1602	0.0919	0.1118	0.0692	0.0588	0.1006	0.0894
	Std	0.0004	0.0039	0.0086	0.0104	0.0092	0.0109	0.0158	0.0692	+	+	+
MMF10_I	Mean	0.1855	0.1908	0.1878	0.1406	0.1970	0.2048	0.1507	0.2033	0.2004	0.1675	0.2006
	Std	0.0164	0.0094	0.0388	0.0009	0.0009	0.0033	0.0007	0.2033	-	0.1675	0.2006
MMF11_I	Mean	0.2193	0.2695	0.2508	0.2417	0.2506	0.2499	0.2538	0.2484	0.2494	0.2503	0.2495
	Std	0.0003	0.0019	0.0003	0.0003	0.0004	0.0003	0.0007	0.2484	+	+	+
MMF12_I	Mean	0.1620	0.6885	0.2469	0.2481	0.2466	0.2463	0.2488	0.2436	0.2440	0.2463	0.2454
	Std	0.0004	0.0014	0.0006	0.0006	0.0004	0.0009	0.0004	0.2436	+	+	+
MMF13_I	Mean	0.2840	0.2643	0.2914	0.3312	0.3136	0.2759	0.2954	0.2683	0.2594	0.2801	0.2532
	Std	0.0009	0.0002	0.0092	0.0053	0.0167	0.0027	0.0060	0.2683	+	+	-
MMF15_J	Mean	0.1608	0.2374	0.2563	0.2747	0.2733	0.2438	0.2729	0.2582	0.2525	0.2305	0.2620
	Std	0.0010	0.0325	0.0203	0.0172	0.0027	0.0123	0.0226	0.2582	+	+	+
MMF15_a_I	Mean	0.1770	0.2593	0.2260	0.2334	0.2326	0.0242	0.2375	0.2110	0.2143	0.2128	0.2303
	Std	0.0001	0.0054	0.0076	0.0153	0.0044	0.0185	0.0081	0.2110	+	+	+
MMF16_I1	Mean	0.1446	0.2097	0.1775	0.1966	0.2091	0.1682	0.1692	0.1973	0.1500	0.1717	0.1503
	Std	0.0015	0.0057	0.0049	0.0067	0.0457	0.0093	0.0020	0.1973	=	+	+
MMF16_I2	Mean	0.1504	0.3349	0.3268	0.2455	0.3308	0.3214	0.3388	0.3280	0.3252	0.3099	0.3337
	Std	0.0007	0.0021	0.0021	0.0154	0.0048	0.0124	0.0045	0.3280	+	+	+
MMF16_I3	Mean	0.1080	0.2411	0.2231	0.0154	0.2364	0.2132	0.2162	0.2361	0.2021	0.2138	0.2256
	Std	0.0050	0.0088	0.0072	0.0076	0.0123	0.0005	0.0005	0.2361	=	+	=

1/10:

[Table 4](#) provides statistics on the rHV obtained by different algorithms. The smaller the rHV, the wider the coverage of the multidimensional objective space of the resulting Pareto front. As can be seen from the table, EMOA obtained the minimum value among the 15 functions, which is much better than the other algorithms. Although EMOA failed to obtain the minimum value in 9 functions, the mean and standard deviation of the rHV index of these functions are still ranked first. This is because EMOA very well simulates the biological characteristics of the dwarf mongoose, making the algorithm have strong global search capabilities, not disturbed by local optima, and can maximize the number of non-dominated solutions, thus greatly improving the convergence and diversity of the algorithm.

[Table 5](#) shows the IGDF results obtained by each algorithm. On IGDF, EMOA achieves the minimum in 20 functions and its performance is far beyond the other algorithms. The results obtained in Multi-objective Multimodal test function1 (MMF1), MMF5, MMF7, and MMF11_1 are also very competitive although no minimum is achieved. This proves once again that EMOA has strong search capability and convergence performance, which matches the rHV results shown in [Table 4](#).

The rPSP is used to measure the uniformity and compactness of the solutions obtained by the measurement algorithm in the Pareto front. The rPSP values obtained by different algorithms are recorded in [Table 6](#). As can be seen from the table, among the 19 test functions, EMOA has the smallest value and ranks first among all algorithms. In functions MMF5, MMF10, MMF13, and MMF1_e, EMOA did not obtain the smallest value, but the optimization results were also very competitive among all algorithms, and the number of minimum values obtained by other algorithms was far less than that of EMOA. The comparison of rPSP values shows that EMOA can obtain a Pareto front with a uniform distribution and compact arrangement, which proves that EMOA has a strong global search capability. This is due to the improvement of the original MOA algorithm, which combines the obtained solution with the best solution of the previous generation and uses KNN to select reference points to retain the best solution. Therefore, EMOA can find multiple optimal solutions for multimodal problems, demonstrating excellent search capabilities.

[Table 7](#) gives the statistics of the performance metric IGDx. In [Table 7](#), EMOA's results for IGDx are better than the other algorithms. Minimum values were obtained for 16 functions and good results were obtained although no minimum values were obtained for the remaining functions. It shows that EMOA is very good at searching the decision space and IGDx measures the convergence between the PS obtained by the algorithm and the true PS. Combined with the results of rPSP in [Table 6](#), it proves that EMOA is better than other algorithms in its global search ability.

Overall, the overall performance of EMOA in CEC2020 is excellent. EMOA can get closer to the global optimal solution and more diverse Pareto frontiers. This fully reflects its superior search performance and convergence and proves that we can lead the EMOA algorithm to solve real multi-objective problems.

6 Experimental Results and Discussion

In this study, the EMOA algorithm is used to solve the SDFWSN deployment, which is deployed on a static node grid of 4000 m × 4000 m. The false alarm rate of each node is lower than 0.05, detection rate is higher than 0.95. The SDFWSN consists of 220 sensor nodes. The proposed EMOA algorithm is compared parametrically with the existing multi-objective algorithms NSGAI, MOPSO, MOEA_D, and MOGWO in terms of the network lifecycle, spatial coverage, temporal coverage, false alarm rate, and detection rate. And to better evaluate the performance of the proposed algorithms, this article adopts the widely used evaluation metrics in multi-objective optimization algorithms [50], hyper volume (HV), Delta and non-dominant solution (NDS) metrics are evaluated for the multi-objective algorithm. [Table 8](#) lists the

experimental settings and their values. Table 9 shows the parameter settings of the various multi-objective algorithms compared.

Table 8: Experimental parameter settings

Simulation parameters	Values
Area covered	4000 m × 4000 m
Deployment mode	Uniform and Independent deployment
Location of sink	Centre of network field
Number of nodes	220 nodes
Packet length (l)	2000 bits
$E_{initial}$	1 J
E_{elec}	50 nJ/bit
E_{mp}	100 pJ/bit/m ⁴
E_{fs}	10 pJ/bit/m ²
E_{DA}	5 pJ/bit/signal
α	0.05
β	0.95
T	1
T_D	1

Table 9: Function parameter settings

Algorithms	Parameter	Value
EMODMOA	Peep	2
	Population size	40
	Archive size	20
	Population size	40
	Deletion selection pressure	2
MOPSO	Leader selection pressure	2
	Grid inflation rate	0.1
	Inertia weight (w)	0.5
	Number of grids per dimension	10
	Mutation rate	0.1
MOGWO	Archive size	20
	Population size	40
	Deletion selection pressure	2
	Number of grids per dimension	10
	Leader selection pressure	4
MOEA/D	Grid inflation rate	0.1
	Archive size	20
	Population size	40
	Crossover parameter	0.5

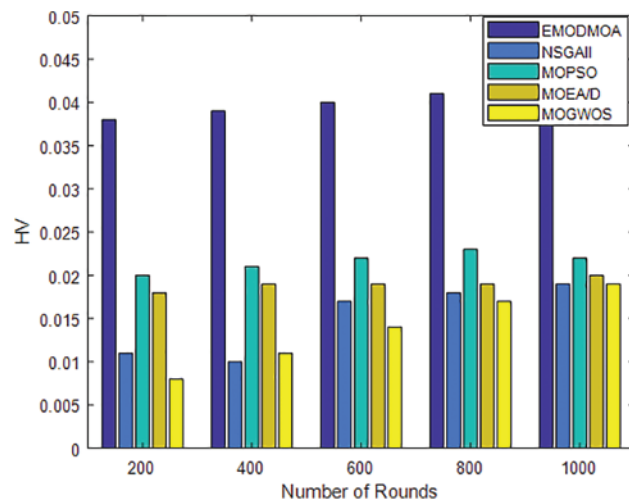
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Table 9 (continued)

Algorithms	Parameter	Value
NSGAI	Number of neighbors	15
	Population size	40
	Crossover probability	0.9
	Mutation probability	0.1

6.1 Basic Experiment

The HV index evaluates the convergence and diversity of the solution set by comparing the hypercube between the solution set and the reference point. The HV index is positive. In multi-objective optimization, the larger the hypercube occupied by the solution set, the better the performance of the solution set, indicating that the algorithm has found a better solution in the objective space. The Delta index is a commonly used evaluation index that can help determine the diversity and homogeneity of the solution set generated by the optimization algorithm. It measures the degree of dispersion of the solutions within the solution set and provides information about the structure of the solution set. The closer the Delta metric is to 1, the better the diversity and homogeneity of the solution set; the closer it is to 0, the worse the diversity and homogeneity of the solution set. NDS is the number of optimal solution sets obtained by the algorithm, which intuitively reflects the algorithm's ability to find the best solution. In this paper, the HV, Delta, and NDS values of NSGAI, MOPSO, MOEA/D, and MOGWOS are compared with those of the EMO/MOA algorithm. The results are shown in Figs. 3–5. The results show that the super-volume values obtained by the EMO/MOA algorithm are higher than those of the other algorithms under different parameter settings, which indicates that the EMO/MOA algorithm has strong convergence. Moreover, the Delta and NDS values of EMO/MOA are higher than those of the other algorithms, which indicates that EMO/MOA can find a Pareto frontier with more diversity and richness, and thus provide decision-makers with more choices.

**Figure 3:** HV vs. Number of iterations

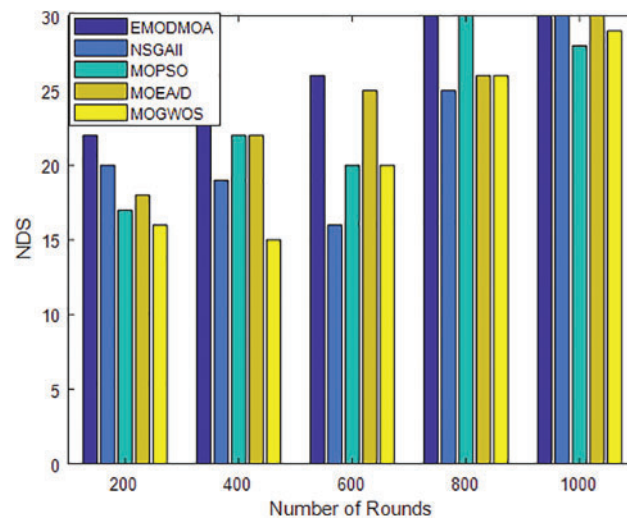


Figure 4: NDS vs. Number of iterations

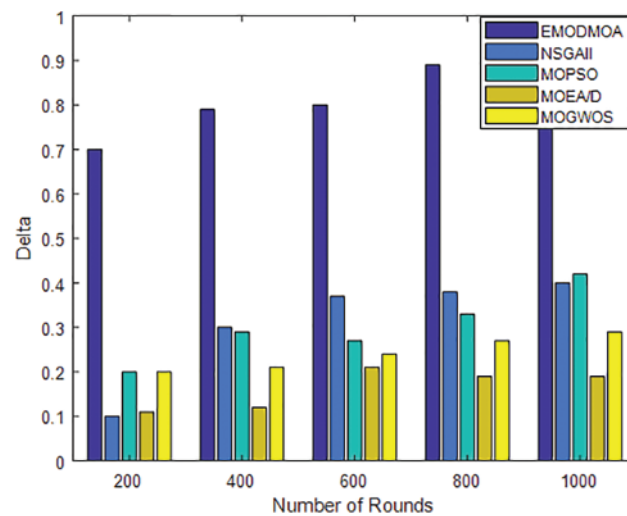


Figure 5: Delta vs. Number of iterations

Fig. 6 shows the network life cycle as the number of iterations increases. It can be seen from the figure that the network life cycle is extended with optimization. Comparing the EMO DMA algorithm with algorithms such as NSGAII, MOPSO, MOEA/D, and MOGWO, our proposed algorithm obtains the maximum network life cycle after 500 iterations. As can be seen from the direction of the broken line in the figure, EMO DMA can steadily improve the network life cycle, and it has the highest stability among all algorithms.

The analysis of the spatial coverage of the network is given in Fig. 7, which improves with the number of iterations. A comparison of the EMO DMA algorithm with NSGAII, MOPSO, MOEA/D, and MOGWO reveals that our proposed algorithm gives the optimal spatial coverage of the network at the later stage of iteration. This is due to the scientific improvement of our algorithm and shows that our proposed algorithm is highly competitive among many multi-objective optimization algorithms.

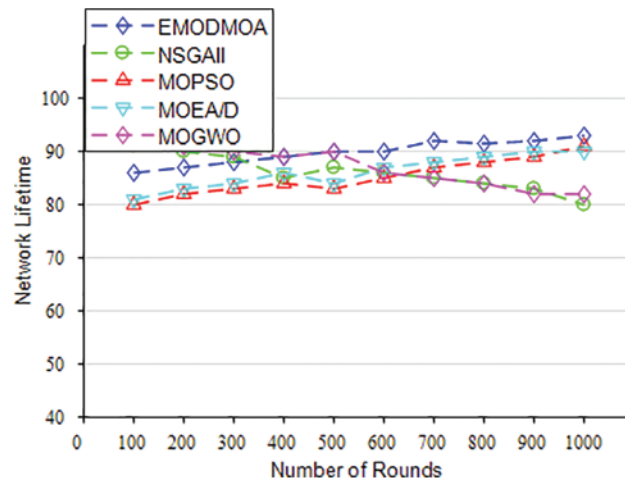


Figure 6: Network lifecycle vs. Number of iterations

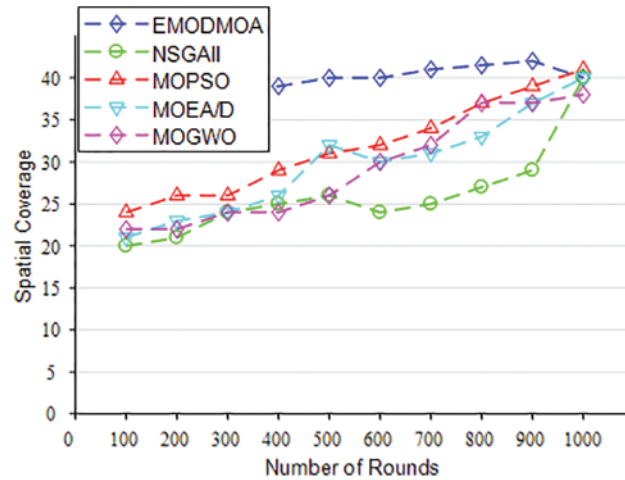


Figure 7: Spatial coverage vs. Number of iterations

Fig. 8 gives an analysis of the network time coverage, which is optimized with the increase of the number of iterations. Comparing EMOA with NSGAII, MOPSO, MOEA/D, and MOGWO, it is found that the final iteration result of our proposed algorithm has the best time coverage. Compared with the broken lines obtained by other algorithms, the optimized broken lines obtained by our algorithm tend to grow steadily, which indicates that our proposed algorithm has strong stability.

Figs. 9 and 10 show the detection rate and false alarm rate of the network, respectively. The detection rate indicates the probability that the network correctly detects the target, while the false alarm rate indicates the probability that the network transmits information about the existence of a target when there is no target. Therefore, as the number of iterations increases, the algorithm should improve the detection rate of the network while reducing the false alarm rate. Observing Fig. 9, it can be found that all algorithms have optimized the detection rate, and the MOGWO algorithm has achieved the optimal detection rate. Although the algorithm proposed in this paper has not achieved the optimal detection rate, the detection rate obtained is not much different from the optimal detection rate. In addition, compared with Fig. 10, it can be found that although the MOGWO algorithm achieves the optimal detection rate, the optimization effect on the false

alarm rate is not ideal. In contrast, EMODMA, MOPSO, and MOEA/D improve the detection rate while reducing the false alarm rate. EMODMA achieves a good detection rate and an optimal false alarm rate, thereby improving network performance.

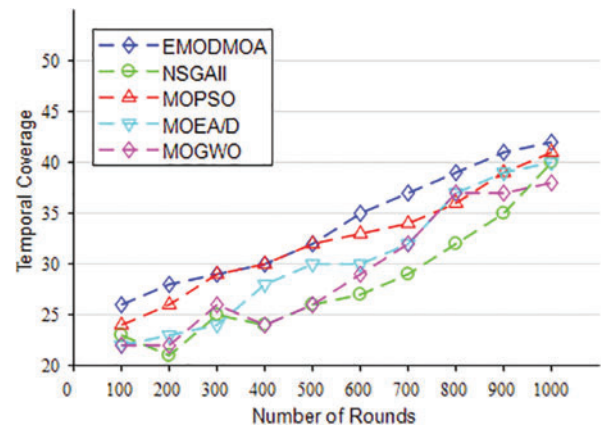


Figure 8: Temporal coverage vs. Number of iterations

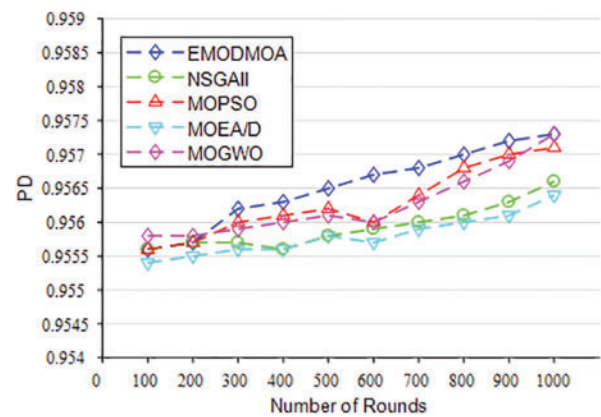


Figure 9: Detection rate vs. Number of iterations

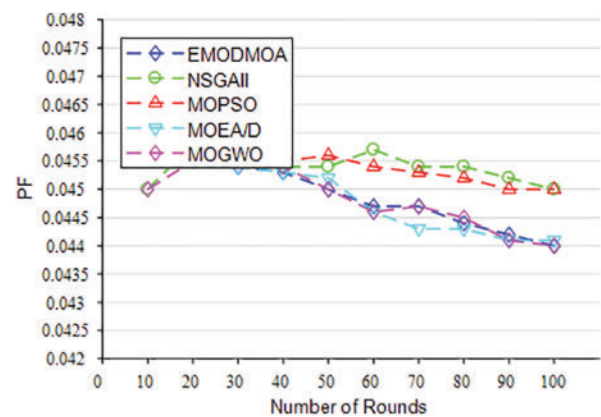


Figure 10: False alarm rate vs. Number of iterations

Fig. 11 shows the deployment of the sensors optimized by the EMODMOA algorithm, and after the optimized deployment, the sensor nodes can cover almost all the target areas. Our algorithm can optimize the deployment of wireless sensors very well. Improve the spatial coverage of the network.

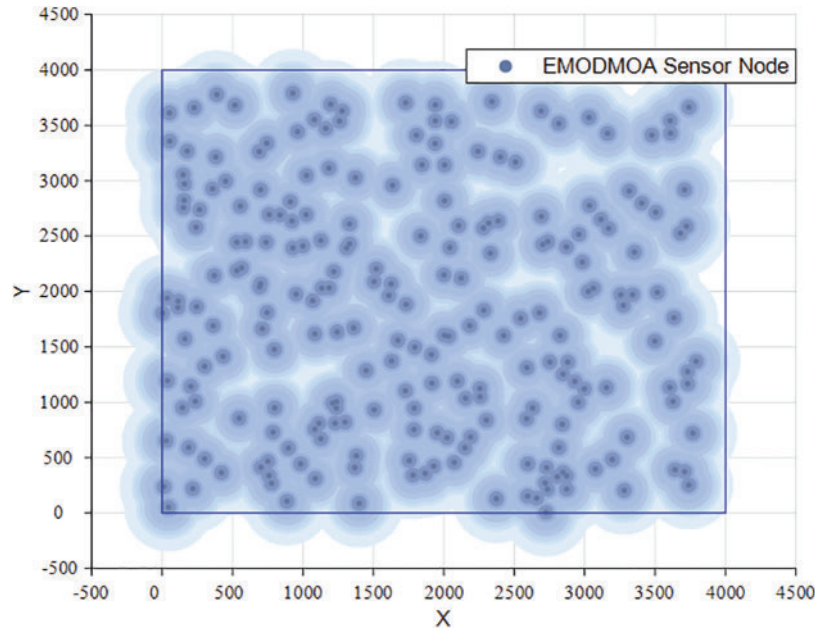


Figure 11: Optimization by EMODMOA

Fig. 12 shows the data fusion graph of SDFWSN, the red circle indicates the sensors that perform data fusion, and the optimized nodes are evenly distributed, and a certain number of sensors are distributed in each data fusion range, which ensures the quality of network transmission. Since the sensors use stochastic sensing, the quality of sensing decreases as the distance between the target node and the sensor increases, the shades of blue in the graph represent the quality of the target area covered by the sensors, i.e., the *PD* value of the target area, which represents the accuracy degree of the network in detecting the target, and it can be seen that most of the target areas are covered by a higher quality to ensure the accuracy of the network monitoring. This provides a good guarantee for network QoS.

Figs. 13–16 represent the data fusion maps after optimization with the MOEA/D, MOGWO, MOPSO, and NSGAI algorithms, comparing Figs. 13–16 with Fig. 12, the superiority of network nodes deployed using EMODMOA can be found. First, the nodes of the network optimized using other algorithms are unevenly distributed, and all of them have different degrees of coverage gaps, which will affect the quality of the network. Second, the uneven distribution of the number of sensors within the fusion range leads to poor detection accuracy, i.e., the network cannot provide accurate detection results, which directly affects the QoS of the network. In summary, it can be found that the deployment of the network optimized by EMODMOA is much better than the deployment of network nodes optimized using the other four algorithms, which can be seen in the algorithms of the superiority of the deployment of the network nodes.

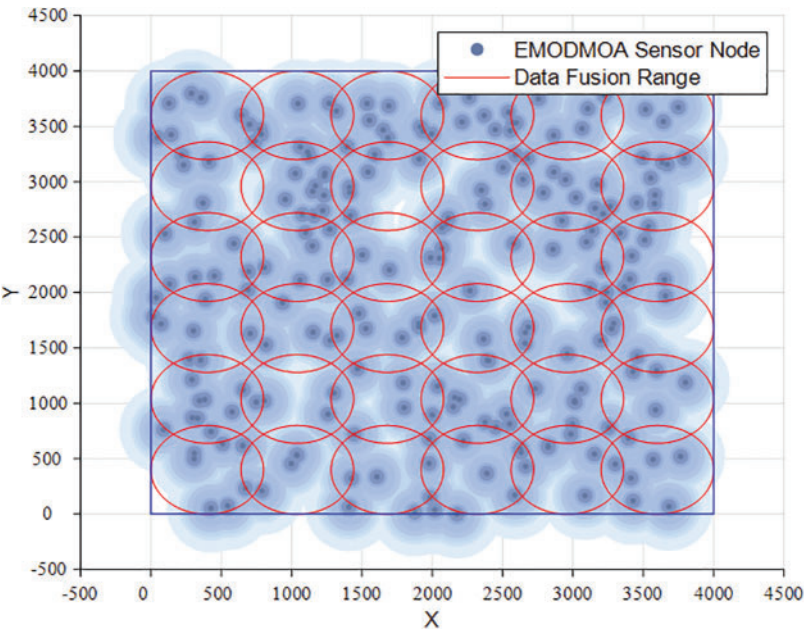


Figure 12: Sensor data fusion of EMODMOA

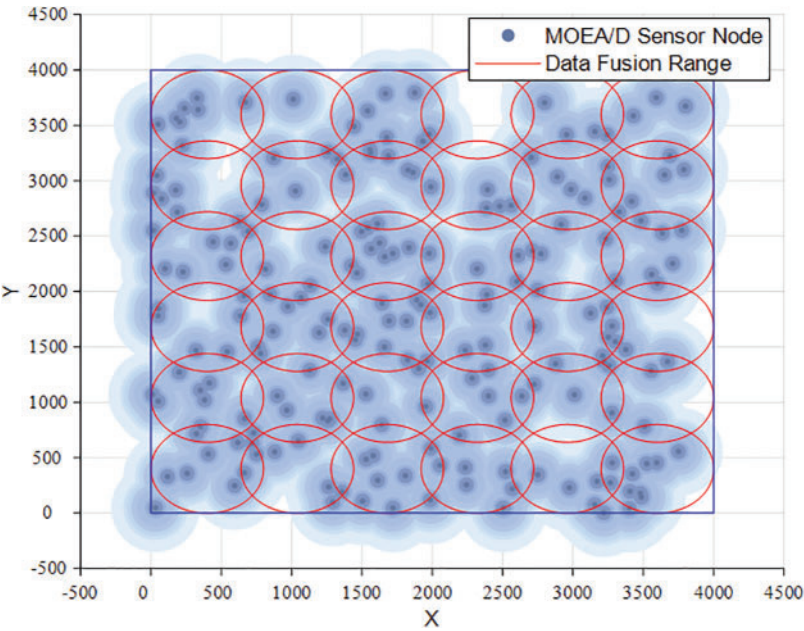


Figure 13: Sensor data fusion of MOEA/D

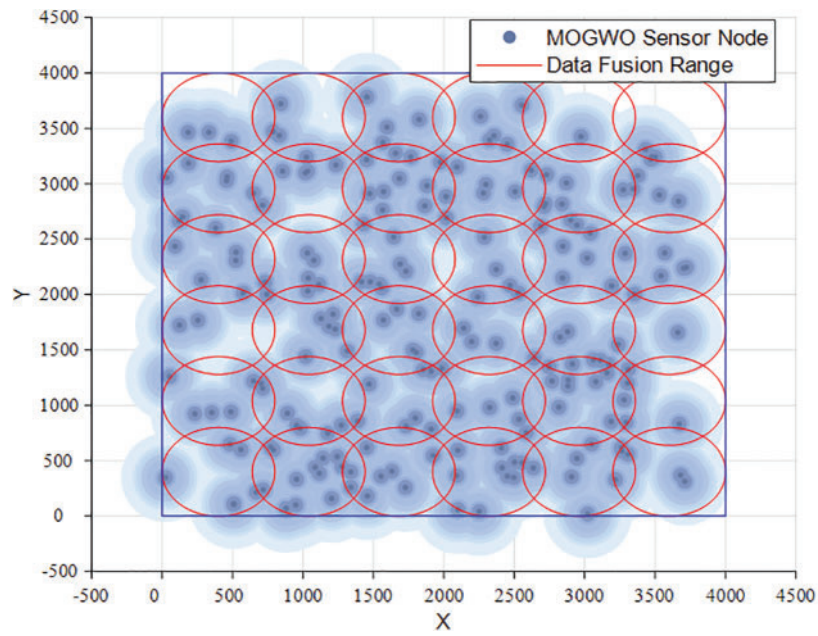


Figure 14: Sensor data fusion diagram of MOGWO

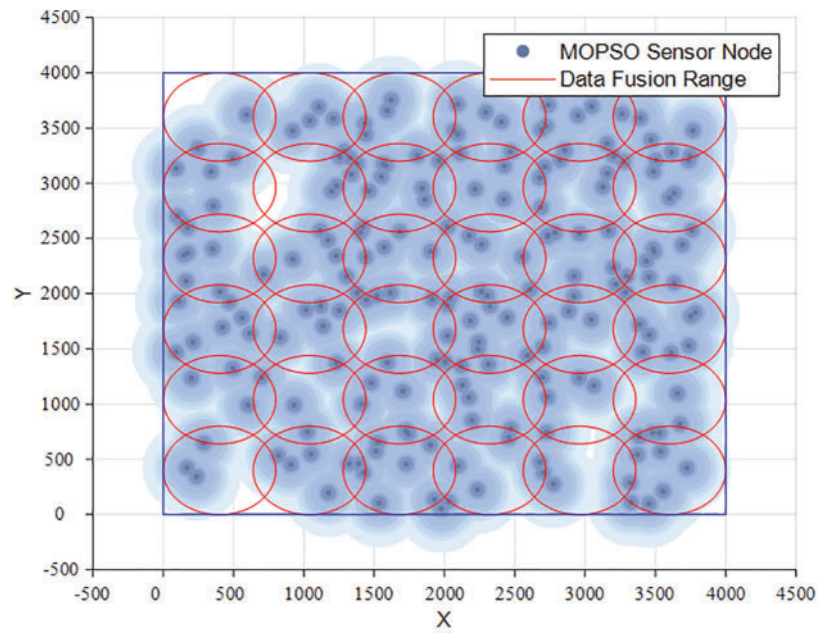


Figure 15: Sensor data fusion diagram of MOPSO

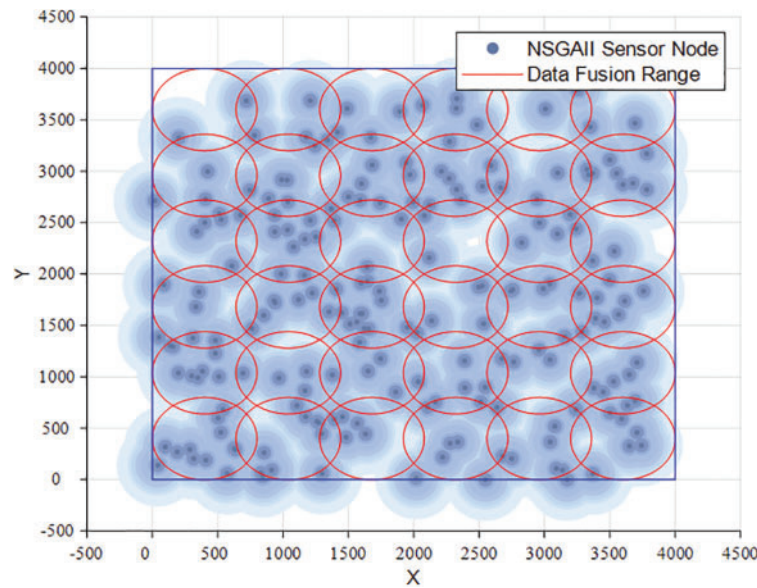


Figure 16: Sensor data fusion diagram of NSGAI

In the simulation experiment, 220 wireless sensors are required to cover an area of $16 \times 10^6 \text{ m}^2$. After the experimental deployment, it is calculated that the coverage areas of EMOA, MOPSO, MOGWO, MOEA/D, and NSGAI are $15.1 \times 10^6 \text{ m}^2$, $13.1 \times 10^6 \text{ m}^2$, $12.2 \times 10^6 \text{ m}^2$, $12.9 \times 10^6 \text{ m}^2$, and NSGAI covers an area of $12.4 \times 10^6 \text{ m}^2$. The calculation time for each algorithm is shown in Fig. 17 below. Within the allowable time frame, EMOA achieved the optimal coverage.

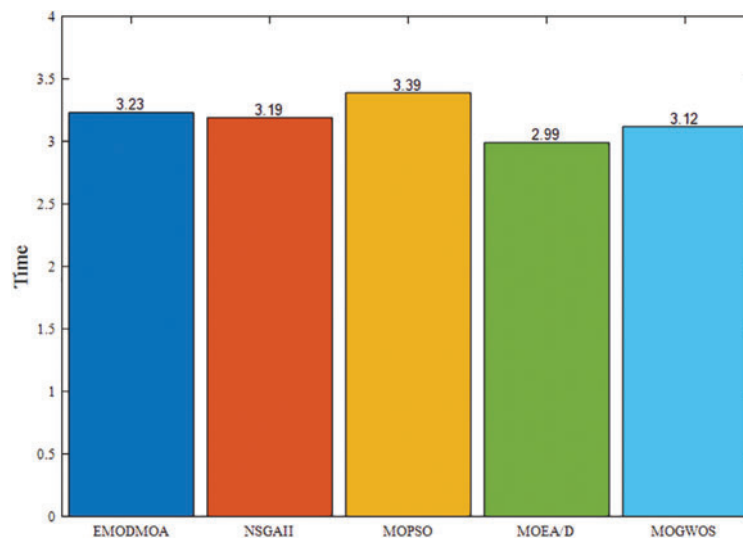


Figure 17: Algorithm running time

6.2 Use Case

To enhance the credibility of the algorithm, four different use cases are designed for verification. The deployment of many nodes and a small number of nodes in a small area, i.e., $1000 \text{ m} \times 1000 \text{ m}$, is discussed, as is the deployment of many nodes and a small number of nodes in a large area, i.e., 5000×5000 .

Case 1: 300 nodes are deployed within a $1000\text{ m} \times 1000\text{ m}$ range, and the network coverage is as Fig. 18.

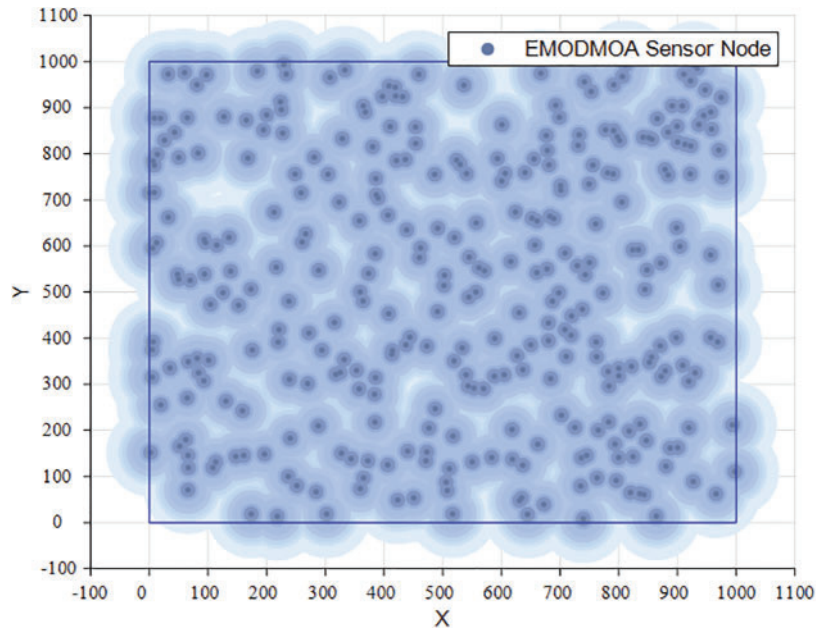


Figure 18: $1000\text{ m} \times 1000\text{ m}$ range and 300 nodes

Case 2: 100 nodes are deployed within a $1000\text{ m} \times 1000\text{ m}$ range, and the network coverage is as Fig. 19.

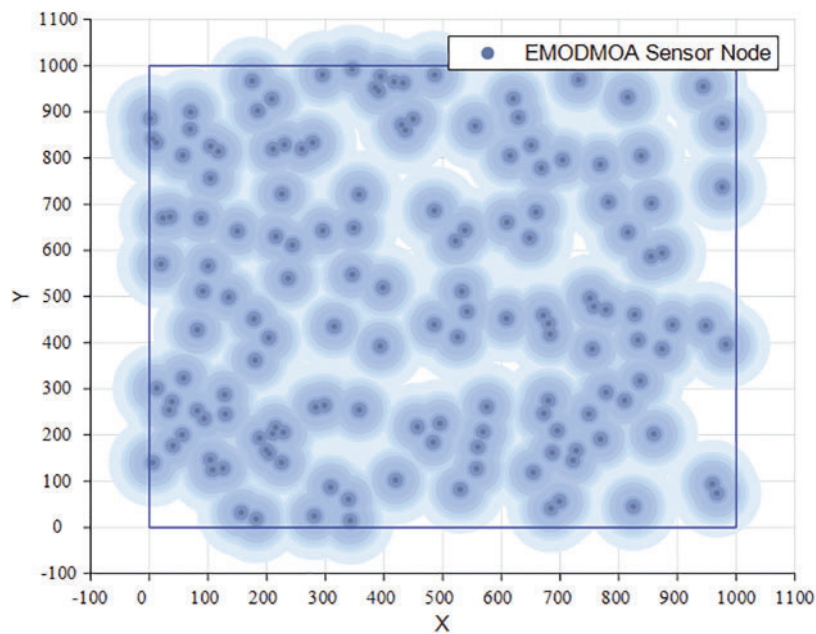


Figure 19: $1000\text{ m} \times 1000\text{ m}$ range and 100 nodes

Case 3: 300 nodes are deployed within an area of $5000\text{ m} \times 5000\text{ m}$, and the network coverage is as Fig. 20.

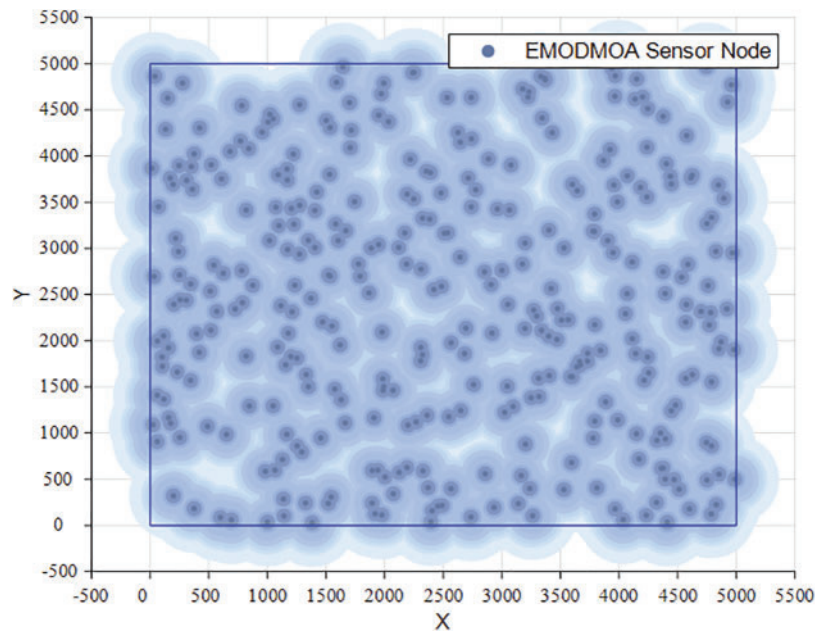


Figure 20: 5000 m $\times$ 5000 m range and 300 nodes

Case 4: 100 nodes are deployed within a 5000 m $\times$ 5000 m range, and the network coverage is as [Fig. 21](#).

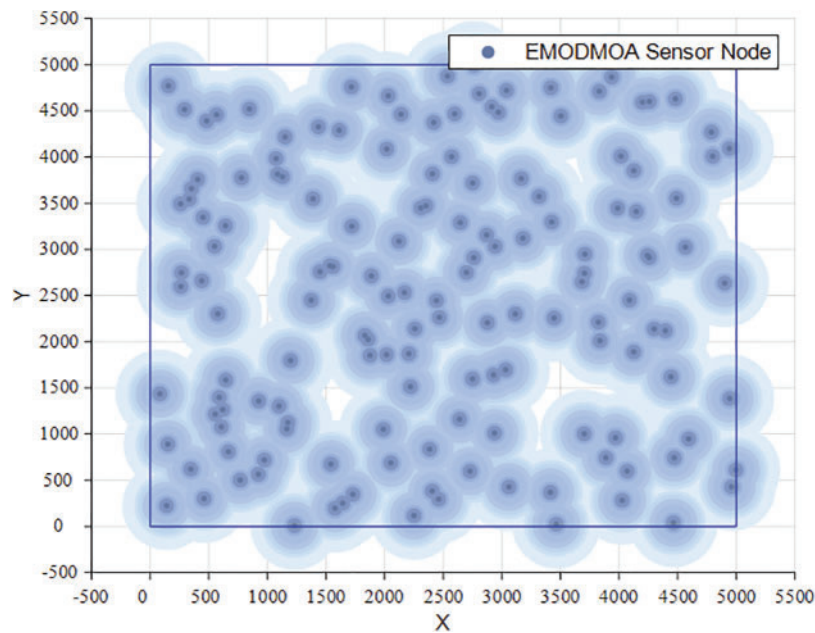


Figure 21: 5000 m $\times$ 5000 m range and 100 nodes

As can be seen from the coverage map of the wireless sensor network, the EMODMOA algorithm can optimize multi-node networks well and can ensure the uniform distribution of wireless sensor nodes, thus covering the target area well. For networks with a small number of wireless sensors, it is better than the limited number of sensors themselves, so full coverage of the target area cannot be guaranteed, but the sensors

optimized by EMOA can also be distributed more evenly in the target area. As can be seen from the figure, both the large target area and the small target area can be well covered after optimization by the wireless sensor network.

Table 10 shows the false alarm rate and detection rate after EMOA optimization in different cases. For the same target range, the more sensors there are, the lower the false alarm rate and the higher the detection rate. This shows that EMOA is suitable for optimizing multi-node networks. When the number of nodes is the same, the false alarm rate is low, and the detection rate is high for a small target area. In summary, EMOA is suitable for optimizing multi-wireless sensor node networks, and there is no limit on the range of the target area.

Table 10: Dynamic performance table

Case	Area covered	Deployment mode	PD	PF
Case1	1000 m × 1000 m	300	0.996	0.049
Case2	1000 m × 1000 m	100	0.977	0.044
Case3	5000 m × 5000 m	300	0.958	0.047
Case4	5000 m × 5000 m	100	0.944	0.051

6.3 Large-Scale Deployment

To verify the performance of the algorithm in large-scale wireless sensor networks, we will add an experiment to deploy a large-scale wireless sensor network for verification.

The experimental parameters are set as shown in Table 11, with 400 wireless sensor network nodes deployed within a 5000 m × 5000 m area.

Table 11: Experimental parameter settings

Simulation parameters	Values
Area covered	5000 m × 5000 m
Deployment mode	Uniform and Independent deployment
Location of sink	Centre of network field
Number of nodes	400 nodes
Packet length (l)	2000 bits
$E_{initial}$	1 J
E_{elec}	50 nJ/bit
E_{mp}	100 pJ/bit/m ⁴
E_{fs}	10 pJ/bit/m ²
E_{DA}	5 pJ/bit/signal
α	0.05
β	0.95
T	1
T_D	1

Figs. 22–26 show the optimization of the network life cycle, spatial coverage, temporal coverage, false alarm rate, and detection rate of large-scale networks. Fig. 22 shows that EMODMOA has extended the network cycle from 70 to 87. Fig. 23 shows that EMODMOA has improved spatial coverage by 17%. Fig. 24 shows that EMODMOA has improved spatial coverage by 3%. Figs. 25–26 show that after EMODMOA optimization, the network false alarm rate has been greatly reduced and the network detection rate has been greatly improved. The EMODMOA algorithm has greatly extended the network life cycle, improved the spatial coverage and temporal coverage, greatly reduced the false alarm rate, and improved the detection rate of the network. Fig. 27 shows that EMODMOA can be used for large-scale deployment.

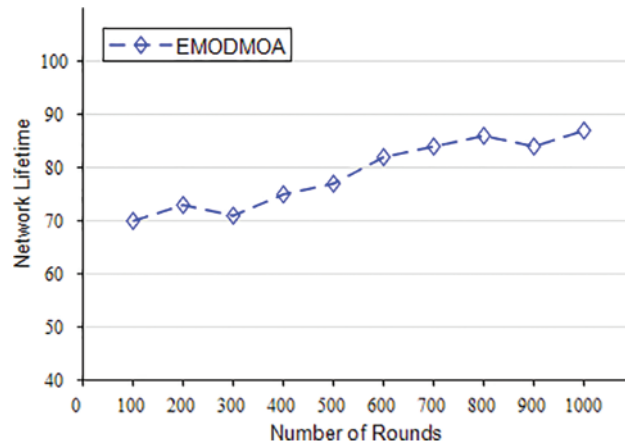


Figure 22: The network lifetime of large-scale deployment

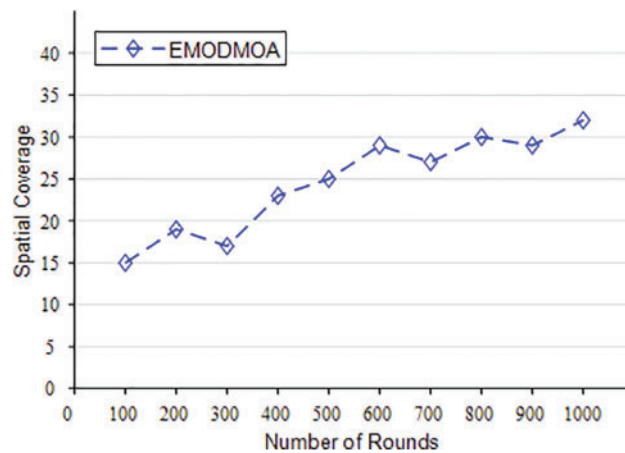


Figure 23: The spatial coverage of large-scale deployment

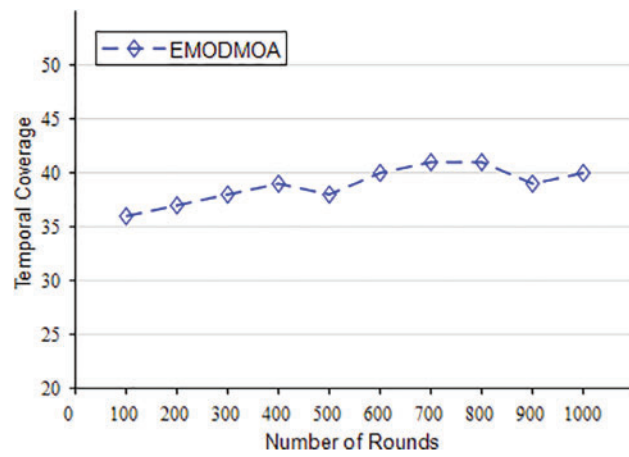


Figure 24: The temporal coverage of large-scale deployment

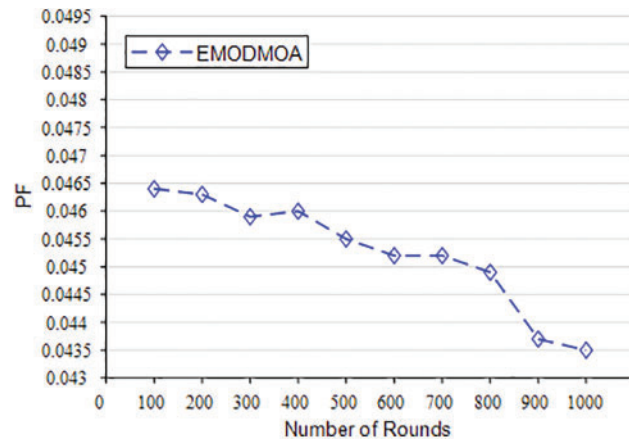


Figure 25: The PF of large-scale deployment

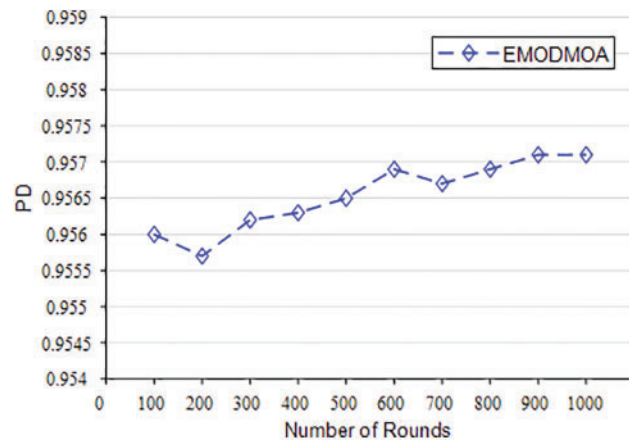


Figure 26: The PD of large-scale deployment

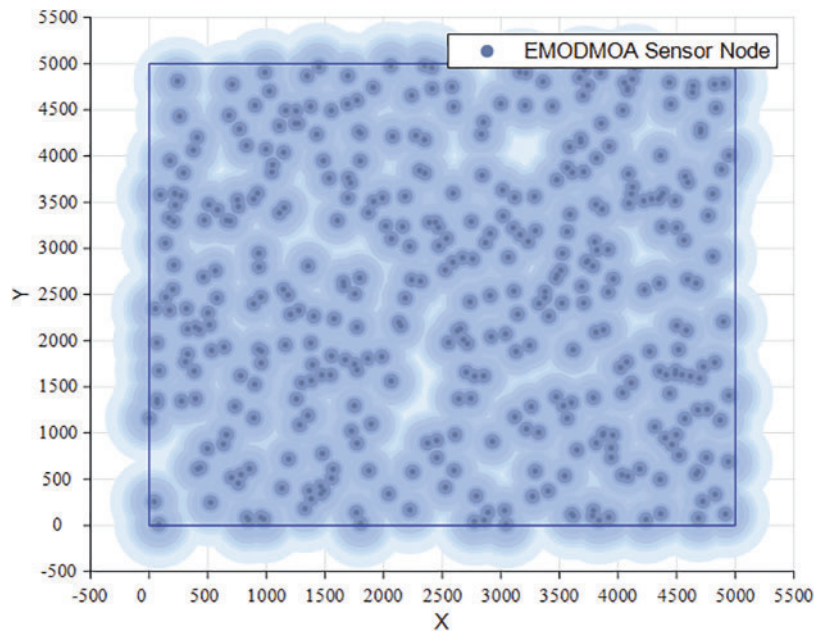


Figure 27: Large-scale deployment

7 Conclusion and Future Work

In this paper, an EMODMA algorithm is proposed, which solves the problem of deploying a five-target SDFWSN. The algorithm improves the original DMOA algorithm by balancing the exploration and exploitation phases of the algorithm, thereby improving the convergence speed of the algorithm and preventing the algorithm from getting stuck in a local optimum. Using the KNN algorithm to select reference points can obtain various feasible solutions. The CEC2020 multi-objective multimodal optimization benchmark function was tested on the proposed algorithm, and the results showed that the algorithm was superior to other multi-objective algorithms used for comparison. Experiments on the deployment of SDFWSN were conducted in this paper. When the algorithm is applied to SDFWSN, it outperforms NSGAI, MOPSO, MOEA/D, and MOGWO in terms of HV, Delta, and NDS metrics. To verify the feasibility of the algorithm, cross-case deployment, and large-scale deployment are carried out. In the experiment, the algorithm can improve the spatial coverage and network survival rate, while improving the detection rate and reducing the false alarm rate. The algorithm proposed in this paper effectively solves the deployment problem of two-dimensional planar SDFWSN.

However, the algorithm proposed in this study cannot well optimize the deployment of a network with few sensors in a large target area, and the model applied in the experiment can also be further optimized to make it more in line with practical applications. Therefore, in future work, we will focus on optimizing the model of a network with few sensors in a large target area, solve practical problems that affect the deployment of wireless sensors, and consider more realistic factors in the construction of the model, to achieve a model that is more in line with practical applications. We will deploy this network and verify the randomness of wireless sensor perception based on data fusion.

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Availability of Data and Materials: The original contributions presented in the study are included in the article, further inquiries can be directed to the corresponding authors.

Ethics Approval: Not applicable.

Conflicts of Interest: The authors declare no conflicts of interest to report regarding the present study.

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