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ARTICLE

Analysis of Progressively Type-II Inverted Generalized Gamma Censored Data and Its Engineering Application

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ABSTRACT

A novel inverted generalized gamma (IGG) distribution, proposed for data modelling with an upside-down bathtub hazard rate, is considered. In many real-world practical situations, when a researcher wants to conduct a comparative study of the life testing of items based on cost and duration of testing, censoring strategies are frequently used. From this point of view, in the presence of censored data compiled from the most well-known progressively Type-II censoring technique, this study examines different parameters of the IGG distribution. From a classical point of view, the likelihood and product of spacing estimation methods are considered. Observed Fisher information and the delta method are used to obtain the approximate confidence intervals for any unknown parametric function of the suggested model. In the Bayesian paradigm, the same traditional inferential approaches are used to estimate all unknown subjects. Markov-Chain with Monte-Carlo steps are considered to approximate all Bayes' findings. Extensive numerical comparisons are presented to examine the performance of the proposed methodologies using various criteria of accuracy. Further, using several optimality criteria, the optimum progressive censoring design is suggested. To highlight how the proposed estimators can be used in practice and to verify the flexibility of the proposed model, we analyze the failure times of twenty mechanical components of a diesel engine.

KEYWORDS

Inverted generalized gamma; censoring; spacing function; likelihood; Bayesian; optimal plan

1 Introduction

Recently, we have come across several studies on inverse (or reciprocal) distributions of one or two parameters in the literature. Louzada et al. [\[1\]](#page-27-0) recently emphasized that inverse distributions provide greater flexibility for fitting data and, in many cases, have been found to be better than many other standard distributions. The three parameter inverted generalized gamma (IGG) distribution was introduced by Hoq et al. [\[2\]](#page-27-1) in the context of life testing experiments. As specific examples, the IGG distribution includes a number of lifespan distributions, including inverted gamma, inverted half-normal, inverted Weibull, inverted exponential, inverted Rayleigh, inverted Maxwell-Boltzmann,

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and inverted chi-square. The IGG distribution has been found to be a good alternative to other skewed distributions, including inverse gamma, inverse Weibull, and generalized inverse exponential distributions, and can be used to illustrate skewed data.

A random variable *x* is said to have IGG (Υ) distribution, where $\Upsilon = (\delta, \mu, \sigma)^{\top}$, if its cumulative distribution function (CDF) and probability density function (PDF) are given, respectively, by

$$
F(x; \Upsilon) = 1 - \frac{1}{\Gamma(\mu)} \gamma(\mu, \sigma^{\delta} x^{-\delta}), \ x > 0,
$$
\n(1)

and

$$
f(x; \Upsilon) = \frac{\delta}{\Gamma(\mu)} \sigma^{\delta \mu} x^{-\delta \mu - 1} e^{-\sigma^{\delta} x^{-\delta}},
$$
\n(2)

where $(\delta, \mu) > 0$ (denote the shape parameters) and $\sigma > 0$ (denotes the scale parameter). The reliability function (say, $R(t)$) and hazard rate function (say, $h(t)$) are, respectively, given by

$$
R(t; \Upsilon) = \frac{1}{\Gamma(\mu)} \gamma(\mu, \sigma^{\delta} t^{-\delta}), \ t > 0,
$$
\n(3)

and

$$
h(t; \Upsilon) = \frac{\delta \sigma^{\delta \mu}}{\gamma(\mu, \sigma^{\delta} t^{-\delta})} t^{-\delta \mu - 1} e^{-\sigma^{\delta} t^{-\delta}}, \ t > 0,
$$
\n
$$
(4)
$$

where $\gamma(a, b) = \int_0^b u^{a-1} e^{-u} du$ and $\Gamma(\xi) = \int_0^\infty t^{\xi-1} e^{-t} dt$.

The hazard rate function (4) has an unimodal shape, while the density function (2) is unimodal and right-skewed with heavy tails. These tails become thicker when the shape parameters are equal, and longer when the shape parameter δ increases.

Besides Type-I, Type-II, and progressive Type-II censoring (PT2C) plans, several censoring mechanisms are available in the literature. An important advantage of PT2C is that it allows the experimenter to withdraw some live units before the experiment stops. The PT2C can be described as follows: Suppose we have *n* identical and independent units. The effective size (say, *m*) and the progressive censoring (say, $\mathbf{R} = (R_1, R_2, \dots, R_m)$) must be determined in advance. When the first failure occurs (say, $X_{1:m:n}$), R_1 (from $n-1$) of live units are randomly selected and excluded from the test. Likewise, in case of the second failure $X_{2:m:n}$, we randomly remove R_2 from $n - R_1 - 2$ live units. Once the *m*th failure is recorded, all remaining surviving items $R_m = n - m - \sum_{i=1}^{m-1} R_i$ are eliminated. For more details; see Balakrishnan et al. [\[3\]](#page-27-2).

The maximum product spacing (MPS) was initially presented by Cheng et al. [\[4\]](#page-27-3) and was utilized by Ranneby [\[5\]](#page-27-4) as an alternative to the maximum likelihood (ML) estimation approach. In recent times, the MPS method has been employed in different contexts; see Zhu [\[6\]](#page-28-0), Jeon et al. [\[7\]](#page-28-1), Nassar et al. [\[8\]](#page-28-2), Nassar et al. [\[9\]](#page-28-3), and many others. According to Anatolyev et al. [\[10\]](#page-28-4), the MPS approach adheres to the invariance property and outperforms likelihood estimators in small-sample scenarios for heavy and skewed distributions.

The limitations and challenges of this work are particularly related to the complexity of parameter estimation, computational intensity, small sample sizes, model power, hypothesis testing, and inference difficulties. Addressing these issues often requires advanced statistical techniques and careful consideration of the specific characteristics of the data and the censoring scheme.

Researchers pay little attention to analyzing new extended gamma lifetime models because of their complex results and expensive numerical evaluations. Aside from the work of Ramos et al. [\[11\]](#page-28-5), as they studied Bayesian inferences based on non-informative priors using a complete sample, and no attempt has been made, to our knowledge, to estimate IGG parameters based on PT2C since the IGG distribution was introduced in the literature.

Given the usefulness and practicality of the IGG distribution, and with samples collected from the PT2C strategy, we state our main objectives in this paper as follows:

- Obtain the frequentist point estimators of the parameters (including *ϒ*, *R(t)*, and *h(t)*) through the ML and MPS methods of estimation.
- Obtain the approximate confidence intervals (ACIs) for all parameters using the acquired ML estimators (MLEs) and MPS estimators (MPSEs).
- As an alternative to the ML function in the Bayesian paradigm, the MPS function is also taken into consideration. Next, both ML and MPS functions are explored in a Bayesian framework for all unknown parameters under squared error loss (SEL) with independent gamma priors.
- Implement Markov chain Monte Carlo (MCMC) methodology with Metropolis–Hastings (M–H) sampler to calculate the offered Bayes point estimates as well as Bayes confidence intervals (BCIs).
- Various optimality metrics are assessed to provide the optimal PT2C plan.
- Extensive Monte Carlo simulations are performed to evaluate the performance of the proposed techniques.
- An engineering data set representing diesel engine failure times is analyzed to show the applicability of the proposed methodologies in a real-life scenario.

The rest of the article is organized as follows: In [Sections 2](#page-2-0) and [3,](#page-4-0) we discuss ML- and MPS-based estimation. In [Section 4,](#page-6-0) we discuss Bayesian inferences. Simulation investigations are highlighted in [Section 5.](#page-8-0) In [Section 6,](#page-18-0) the optimal PT2C is discussed. One real data set is analyzed in [Section 7.](#page-18-1) Finally, various observations are made in [Section 8.](#page-26-0)

2 Likelihood Estimation

This section considers the ML estimation to provide the MLEs along with their ACIs of the IGG parameters δ , μ , σ , $R(t)$, and $h(t)$ using the PT2C sample.

2.1 The MLEs

Suppose $\mathbf{x} = (x_i, R_i)$, $i = 1, 2, ..., m$, where x_i is used in place of $x_{i,m,n}$, is an observed PT2C sample obtained from the IGG *(ϒ)* distribution. From [\(2\)](#page-1-1) and [\(1\),](#page-1-2) the likelihood function (LF) becomes

$$
L(\delta, \mu, \sigma | \mathbf{x}) = A \prod_{i=1}^{m} f(x_i; \delta, \mu, \sigma) \left[1 - F(x_i; \delta, \mu, \sigma) \right]^{R_i},
$$

$$
= A \left(\frac{\delta}{\Gamma(\mu)} \right)^m \sigma^{m\delta\mu} \prod_{i=1}^{m} x_i^{-\delta\mu - 1} e^{-\sigma^{\delta} x_i^{-\delta}} \left[\frac{1}{\Gamma(\mu)} \gamma(\mu, \sigma^{\delta} x_i^{-\delta}) \right]^{R_i},
$$
 (5)

where $A = n(n - R_1 - 1) \cdots (n - (m - 1) - \sum_{i=1}^{m-1} R_i)$.

Using [\(5\),](#page-2-1) without constant terms, the log-likelihood function $\ell \propto L(\cdot)$ can be written as

 $\ell \propto m \ln(\delta) - n \ln(\Gamma(\mu)) + m \delta \mu \ln(\sigma) - (\delta \mu + 1) \sum_{\mu=1}^{m}$ $\sum_{i=1}^{m} \ln(x_i) - \sum_{i=1}^{m} (\sigma x_i^{-1})^{\delta} + \sum_{i=1}^{m} R_i \ln(\psi_i),$ (6) where $\psi_i = \gamma \left(\mu, \left(\frac{\sigma}{x_i} \right)^{\delta} \right)$.

The MLEs $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ of δ , μ , and σ , can be offered by differentiating [\(6\)](#page-3-0) with respect to δ , μ , and σ , respectively, as

$$
\frac{\partial \ell}{\partial \delta} = \frac{m}{\delta} + \mu(m \ln(\sigma) - \sum_{i=1}^{m} \ln(x_i)) - \sum_{i=1}^{m} (\sigma x_i^{-1})^{\delta} \ln(\sigma x_i^{-1}) + \sum_{i=1}^{m} R_i \psi_i(\delta'), \tag{7}
$$

$$
\frac{\partial \ell}{\partial \mu} = -n\eta(\mu) + \delta(m\ln(\sigma) - \sum_{i=1}^{m} \ln(x_i)) + \sum_{i=1}^{m} R_i \psi_i(\mu'),\tag{8}
$$

and

 $\frac{\partial \ell}{\partial \sigma} = \frac{\delta}{\sigma}$ $\left[m\mu - \sum\nolimits_{i=1}^m {(\sigma x_i^{-1})}^{\delta} \right] + \sum\nolimits_{i=1}^m {R_i}{\psi_i}(\sigma'$ *)*, (9)

where $\eta(\mu) = d \ln(\Gamma(\mu))/d\mu$ is the digamma function and $\psi_i(\xi')$ is the first-partial derivative with respect to *ξ* as

$$
\psi_i(\delta') = \frac{\partial}{\partial \delta} \ln(\gamma(\mu, (\sigma x_i^{-1})^{\delta})) = \psi_i^{-1} (\sigma x_i^{-1})^{\delta \mu} \ln(\sigma x_i^{-1}) \exp(-(\sigma x_i^{-1})^{\delta})
$$

$$
\psi_i(\mu') = \frac{\partial}{\partial \mu} \ln(\gamma(\mu, (\sigma x_i^{-1})^{\delta})) = \psi_i^{-1} \int_0^{(\sigma x_i^{-1})^{\delta}} w^{\mu-1} \ln(w) e^{-w} dw,
$$

and

$$
\psi_i(\sigma') = \frac{\partial}{\partial \sigma} \ln(\gamma(\mu, (\sigma x_i^{-1})^{\delta})) = \psi_i^{-1} \frac{\delta}{\sigma} (\sigma x_i^{-1})^{\delta \mu} \exp(-(\sigma x_i^{-1})^{\delta}).
$$

To prove the convergence of the MLEs $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ of δ , μ , and σ , respectively, the offered form in [\(6\)](#page-3-0) makes it difficult to verify these features theoretically. To solve this problem, we simulate a PT2C sample from IGG (1,1.5,0.5) when $(n, m) = (50, 25)$ and $R_i = 1, i = 1, ..., m$. As a result, we find that $(\hat{\delta}, \hat{\mu}, \hat{\sigma}) = (1.1621, 1.4558, 0.6533)$. In [Fig. 1,](#page-4-1) the log-LF line and its normal-equation curve of $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ are depicted. To distinguish, for each sup-plot in [Fig. 1,](#page-4-1) we plot the log-LF curve (in red at the apex) and the first-partial derivative (FPD) curve (in black at the zero point) intersect at the vertical line (which represents the MLE of δ , μ , or σ). Since we obtained the estimated values of the MLEs, this indicates that the proposed likelihood equations converge well. At the same time, the MLEs $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ exist and are unique. The invariance feature of $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ makes it easy to acquire the MLEs of $R(t)$ [\(3\)](#page-1-3) and $h(t)$ [\(4\)](#page-1-0) at time $t > 0$ once the MLEs of δ , μ , and σ have been obtained.

2.2 ACIs via LF-Based

In this subsection, the $(1 - \rho)$ % ACIs of δ , μ , σ , $R(t)$, and $h(t)$ are obtained. First, from [\(6\),](#page-3-0) the second derivatives with respect to δ , μ , and σ are obtained and reported in [Appendix A.](#page-29-0) It is clear that the issue of obtaining asymptomatic expressions for the variances and covariances of $\hat{\delta}$, $\hat{\mu}$, and $\hat{\sigma}$ is tedious. We thus estimate the variance-covariance (V-C) matrix (say, $I_1^{-1}(\cdot)$), where $I_1(\cdot)$ is the observed Fisher's information, using the LF-based as

$$
I_1^{-1}(\hat{\delta}, \hat{\mu}, \hat{\sigma}) = \begin{bmatrix} -\ell_{11} & -\ell_{12} & -\ell_{13} \\ -\ell_{22} & -\ell_{23} \\ -\ell_{33} & \delta_{\hat{\mu}, \hat{\sigma}} \end{bmatrix}_{(\hat{\delta}, \hat{\mu}, \hat{\sigma})}^{-1} = \begin{bmatrix} \widehat{var}(\hat{\delta}) & \widehat{cov}(\hat{\delta}, \hat{\mu}) & \widehat{cov}(\hat{\delta}, \hat{\sigma}) \\ \widehat{var}(\hat{\mu}) & \widehat{cov}(\hat{\mu}, \hat{\sigma}) \\ \widehat{var}(\hat{\sigma}) \end{bmatrix} . \tag{10}
$$

Figure 1: The log-LF (top) and its FPD (bottom) of (a) δ , (b) μ , and (c) σ

It is established that $(\hat{\delta}, \hat{\mu}, \hat{\sigma}) \sim N((\delta, \mu, \sigma), I_1^{-1}(\hat{\delta}, \hat{\mu}, \hat{\sigma}))$. Consequently, the $(1 - \rho)\%$ ACIs of δ , μ , and σ are given, respectively, by

$$
\hat{\delta} \pm z_{\rho/2} \sqrt{\widehat{var}(\hat{\delta})}, \quad \hat{\mu} \pm z_{\rho/2} \sqrt{\widehat{var}(\hat{\mu})}, \quad \text{and} \quad \hat{\sigma} \pm z_{\rho/2} \sqrt{\widehat{var}(\hat{\sigma})},
$$

where $z_{\rho/2}$ is the upper $(\rho/2)^{th}$ standard-normal percentile point.

To find the $(1 - \rho)$ % ACIs of *R*(*t*) and *h*(*t*), we use the delta method; see Greene [\[12\]](#page-28-6). Next, the approximated variances of $\hat{R}(t)$ and $\hat{h}(t)$ (after getting $(\hat{\delta}, \hat{\mu}, \hat{\sigma})$) can be obtained as

 $\widehat{var}(\hat{R}(t)) = [\nabla R(t)]^{T} I_{1}^{-1}(\delta, \mu, \sigma)[\nabla R(t)]|_{(\hat{\delta}, \hat{\mu}, \hat{\sigma})}$ and $\widehat{var}(\hat{h}(t)) = [\nabla h(t)]^{T} I_{1}^{-1}(\delta, \mu, \sigma)[\nabla h(t)]|_{(\hat{\delta}, \hat{\mu}, \hat{\sigma})},$

where $\nabla \hat{R}(t)$ and $\nabla \hat{h}(t)$ are the estimated gradient of $R(t)$ and $h(t)$, respectively.

Hence, once we obtain the variances $\widehat{var}(\hat{R}(t))$ and $\widehat{var}(\hat{h}(t))$, then $100(1 - \rho)\%$ two-sided ACIs $R(t)$ and $h(t)$ are given by for $R(t)$ and $h(t)$ are given by

$$
\hat{R}(t) \pm z_{\rho/2} \sqrt{\widehat{var}(\hat{R}(t))}
$$
 and $\hat{h}(t) \pm z_{\rho/2} \sqrt{\widehat{var}(\hat{h}(t))}$,

respectively, where $z_{p/2}$ is the right-tail $(\rho/2)^{th}$ standard-normal point.

3 Product of Spacings Estimation

This section examines the MPS estimation approach to acquire the MPSEs and ACIs of δ , μ , σ , $R(t)$, and $h(t)$ based on the PT2C sample.

3.1 The MPSEs

Substituting [\(2\)](#page-1-1) and [\(1\)](#page-1-2) into the product of spacing (PS) function of PT2C, we get the joint PS function of *δ*, *μ*, and *σ* as follows:

$$
S(\delta, \mu, \sigma) = \prod_{i=1}^{m+1} \left[F(x_i; \delta, \mu, \sigma) - F(x_{i-1}; \delta, \mu, \sigma) \right] \prod_{i=1}^{m} \left[1 - F(x_i; \delta, \mu, \sigma) \right]^{R_i},
$$

\n
$$
= \prod_{i=1}^{m+1} \left[\frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\frac{\sigma}{x_{i-1}} \right)^{\delta} \right) - \frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\frac{\sigma}{x_i} \right)^{\delta} \right) \right] \prod_{i=1}^{m} \left[\frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\frac{\sigma}{x_i} \right)^{\delta} \right) \right]^{R_i}, \quad (11)
$$

\nwhere $F(x; \delta, \mu, \sigma) = 0$ and $F(x; \delta, \mu, \sigma) = 1$

where $F(x_0; \delta, \mu, \sigma) \equiv 0$ and $F(x_{m+1}; \delta, \mu, \sigma) \equiv 1$.

By maximizing the following logarithmic MPS function (e.g., ln *S*) with respect to *δ*, *μ*, and *σ*, one can obtain their MPSEs as follows:

$$
\ln S \propto -(n+1)\ln\Gamma(\mu) + \sum_{i=1}^{m+1} \ln\left(\psi_{i-1} - \psi_i\right) + \sum_{i=1}^{m} R_i \ln\psi_i,
$$
\n(12)

where $\psi_{i-1} = \gamma \left(\mu, \left(\sigma x_{i-1}^{-1} \right)^{\delta} \right)$ and $\psi_i = \gamma \left(\mu, \left(\sigma x_i^{-1} \right)^{\delta} \right)$.

Solving the following three normal equations will yield the MPSEs of δ , μ , and σ , denoted by $\tilde{\delta}$, $\tilde{\mu}$, and $\tilde{\sigma}$, respectively:

$$
\frac{\partial \ln S}{\partial \delta} = \sum_{i=1}^{m+1} \left[\frac{\psi_{i-1}(\delta') - \psi_i(\delta')}{\psi_{i-1} - \psi_i} \right] + \sum_{i=1}^{m} R_i \psi_i(\delta'), \tag{13}
$$

$$
\frac{\partial \ln S}{\partial \mu} = -(n+1)\eta(\mu) + \sum_{i=1}^{m+1} \left[\frac{\psi_{i-1}(\mu') - \psi_i(\mu')}{\psi_{i-1} - \psi_i} \right] + \sum_{i=1}^{m} R_i \psi_i(\mu'), \tag{14}
$$

and

$$
\frac{\partial \ln S}{\partial \sigma} = \sum_{i=1}^{m+1} \left[\frac{\psi_{i-1}(\sigma') - \psi_i(\sigma')}{\psi_{i-1} - \psi_i} \right] + \sum_{i=1}^{m} R_i \psi_i(\sigma'), \tag{15}
$$

where $\psi_{i-1}(\xi')$ is the first-partial derivative of ψ_{i-1} with respect to ξ .

Since the proposed MPSEs from (13) – (15) lack closed form solutions, an iterative method such as Newton-Raphson can be easily used to derive the MPSEs numerically. It is important to note that the MPSEs and MLEs of δ , μ , and σ have several flexible qualities, such as consistency, asymptotic efficiency, and invariance.

Now, to highlight the convergence of the MPSEs $\tilde{\delta}$, $\tilde{\mu}$, and $\tilde{\sigma}$ of δ , μ , and σ , respectively, the offered form in [\(12\)](#page-5-2) makes it not easy. Using the same PT2C sample generated in [Subsection 2.1,](#page-2-2) we have $(\tilde{\delta}, \tilde{\mu}, \tilde{\sigma}) = (1.2729, 1.4557, 0.5154)$. [Fig. 2](#page-6-1) supports this result. It indicates that the suggested normal equations used to create the MPSEs converge well. It also indicates that the MPSEs $\tilde{\delta}$, $\tilde{\mu}$, and *σ*˜ exist and are unique.

Figure 2: The log-PS (top) and its FPD (bottom) of (a) δ , (b) μ , and (c) σ

3.2 ACIs via PS-Based

To get the two bounds*(*1−*ρ)*% ACIs (PS-based) of the *δ*, *μ*, *σ*, *R(t)*, or *h(t)*, the second derivatives of [\(12\)](#page-5-2) with respect to δ , μ , and σ should be first obtained; see [Appendix B.](#page-30-0) Since the exact expectations of S_{ij} , $i, j = 1, 2, 3$ cannot be solved analytically, similar to the case of Fisher information using LFbased, the approximated V-C matrix of the MPSEs can be obtained as

$$
I_2^{-1}(\tilde{\delta}, \tilde{\mu}, \tilde{\sigma}) = \begin{bmatrix} -S_{11} & -S_{12} & -S_{13} \\ -S_{22} & -S_{23} \\ -S_{33} & \delta_{\tilde{\mu}, \tilde{\sigma}} \end{bmatrix}^{-1} = \begin{bmatrix} \widetilde{var}(\tilde{\delta}) & \widetilde{cov}(\tilde{\delta}, \tilde{\mu}) & \widetilde{cov}(\tilde{\delta}, \tilde{\sigma}) \\ \widetilde{var}(\tilde{\mu}) & \widetilde{cov}(\tilde{\mu}, \tilde{\sigma}) \\ \widetilde{var}(\tilde{\sigma}) \end{bmatrix}.
$$
(16)

It follows that $(\tilde{\delta}, \tilde{\mu}, \tilde{\sigma}) \sim N\left((\delta, \mu, \sigma), I_2^{-1}(\tilde{\delta}, \tilde{\mu}, \tilde{\sigma}) \right)$, where $I_2^{-1}(\tilde{\delta}, \tilde{\mu}, \tilde{\sigma})$ is given by [\(16\).](#page-6-2) Consequently, the respective $(1 - \rho)$ % ACIs (PS-based) of δ , μ , and σ are

$$
\tilde{\delta} \pm z_{\rho/2} \sqrt{\tilde{var}(\tilde{\delta})}, \ \tilde{\mu} \pm z_{\rho/2} \sqrt{\tilde{var}(\tilde{\mu})}, \text{ and } \tilde{\sigma} \pm z_{\rho/2} \sqrt{\tilde{var}(\tilde{\sigma})}.
$$

Replacing δ , μ , and σ in [\(3\)](#page-1-3) and [\(4\)](#page-1-0) by their MPSEs $\tilde{\delta}$, $\tilde{\mu}$, and $\tilde{\sigma}$, respectively, the MPSEs $\tilde{R}(t)$ and $\tilde{h}(t)$ can be easily derived. Thus, the 100(1 – ρ)% ACIs (PS-based) of $R(t)$ and $h(t)$ are given by

$$
\tilde{R}(t) \pm z_{\rho/2} \sqrt{\tilde{var}(\tilde{R}(t))}
$$
 and $\tilde{h}(t) \pm z_{\rho/2} \sqrt{\tilde{var}(\tilde{h}(t))}$,

respectively, where

$$
\widetilde{var}(\widetilde{R}(t)) = [\nabla R(t)]^{T} I_{2}^{-1}(\delta, \mu, \sigma) [\nabla R(t)]_{(\delta, \tilde{\mu}, \tilde{\sigma})} \text{ and } \widetilde{var}(\tilde{h}(t)) = [\nabla h(t)]^{T} I_{2}^{-1}(\delta, \mu, \sigma) [\nabla h(t)]_{(\delta, \tilde{\mu}, \tilde{\sigma})}.
$$

4 Bayesian Inference

In this section, under the PT2C scheme, the Bayes framework for unknown IGG parameters based on LF and PF methods is discussed. Prior information plays an influential role in obtaining Bayes' estimate. We now consider the independent gamma priors (say, ω_i , $i = 1, 2, 3$.) for δ , μ , and σ as

$$
\omega_1(\delta) \propto \delta^{a-1} e^{-b\delta}, \ \delta > 0, a, b > 0,
$$

\n
$$
\omega_2(\mu) \propto \mu^{c-1} e^{-d\mu}, \ \mu > 0, c, d > 0,
$$

\n
$$
\omega_3(\sigma) \propto \sigma^{c-1} e^{-f\sigma}, \ \sigma > 0, e, f > 0,
$$
\n(17)

where a, b, c, d, e and f are known, non-negative and reflect the prior knowledge of the IGG parameters. Thus, from [\(17\),](#page-7-0) the joint PDF of δ , μ , and σ becomes

$$
\omega(\delta, \mu, \sigma) \propto \delta^{a-1} \mu^{c-1} \sigma^{e-1} e^{-(b\delta + d\mu + f\sigma)} \delta, \mu, \sigma > 0.
$$
\n(18)

Suppose $\hat{\pi}$ denotes the unknown parameter to be evaluated. In this case, the SEL (say, $l(\cdot)$) can be defined as

$$
l(\pi,\widehat{\pi}) = (\widehat{\pi} - \pi)^2,\tag{19}
$$

where the Bayes estimator $\hat{\pi}$ is directly offered by the posterior expectation of Π .

4.1 Posterior Density via LF-Based

Using [\(5\)](#page-2-1) and [\(18\),](#page-7-1) the joint posterior PDF via the LF (say, $\Pi_1(\cdot)$) can be written as

$$
\Pi_1(\delta, \mu, \sigma | \mathbf{x}) \propto \delta^{a-1} \mu^{c-1} \sigma^{e-1} e^{-(b\delta + d\mu + f\sigma)}
$$
\n
$$
\times \left(\frac{\delta}{\Gamma(\mu)}\right)^m \sigma^{m\delta\mu} \prod_{i=1}^m x_i^{-\delta\mu-1} e^{-\sigma^{\delta} x_i^{-\delta}} \left[\frac{1}{\gamma(\mu)} \Gamma(\mu, \sigma^{\delta} x_i^{-\delta})\right]^{R_i}.
$$
\n(20)

Using an arbitrary function $\Pi(\delta,\mu,\sigma)$ of parameters δ , μ and σ , the Bayes' estimator via LFbased (say $\hat{\Pi}(\delta, \mu, \sigma)$) against the SEL can be expressed as

$$
\widehat{\Pi}(\delta,\mu,\sigma) = \frac{\int_0^\infty \int_0^\infty \int_0^\infty \Pi(\delta,\mu,\sigma)\omega(\delta,\mu,\sigma)L(\delta,\mu,\sigma|\mathbf{x})d\delta d\mu d\sigma}{\int_0^\infty \int_0^\infty \int_0^\infty \omega(\delta,\mu,\sigma)L(\delta,\mu,\sigma|\mathbf{x})d\delta d\mu d\sigma}.
$$
\n(21)

All triple integrals in [\(21\)](#page-7-2) do not have a closed form. Therefore, we will implement the M-H algorithm. From [\(20\),](#page-7-3) we note that the full conditionals of δ , μ , and σ cannot be obtained in the form of any known distribution. To generate the required samples of δ , μ , or σ , implement the MCMC algorithm as follows:

Step 1: Set initial guesses of $(\delta^0, \mu^0, \sigma^0)$ as $(\hat{\delta}, \hat{\mu}, \hat{\sigma})$. **Step 2:** Set $i = 1$. **Step 3:** Obtain $\delta^* \sim N(\delta^{i-1}, \widehat{var}(\widehat{\delta})), \mu^* \sim N(\mu^{i-1}, \widehat{var}(\widehat{\mu}))$ and $\sigma^* \sim N(\sigma^{i-1}, \widehat{var}(\widehat{\sigma})).$ **Step 4:** Compute $\Omega_1 = \frac{\prod_i (\delta^* | \mu^{i-1}, \sigma^{i-1}, \mathbf{x})}{\prod_i (\delta^i | \mu^{i-1}, \sigma^{i-1}, \mathbf{x})}$ $\frac{\prod_{1}(\delta^{*}|\mu^{i-1},\sigma^{i-1},\mathbf{X})}{\prod_{1}(\delta^{i-1}|\mu^{i-1},\sigma^{i-1},\mathbf{X})}, \Omega_{2}=\frac{\prod_{1}(\mu^{*}|\delta^{i},\sigma^{i-1},\mathbf{X})}{\prod_{1}(\mu^{i-1}|\delta^{i},\sigma^{i-1},\mathbf{X})}$ $\frac{\prod_1(\mu^*|\delta^i, \sigma^{i-1}, \mathbf{x})}{\prod_1(\mu^{i-1}|\delta^i, \sigma^{i-1}, \mathbf{x})}$ and $\Omega_3 = \frac{\prod_1(\sigma^*|\delta^i, \mu^i, \mathbf{x})}{\prod_1(\sigma^{i-1}|\delta^i, \mu^i, \mathbf{x})}$ $\frac{1}{\prod_1(\sigma^{i-1}|\delta^i, \mu^i, \mathbf{x})}$. **Step 5:** Simulate u_i , $i = 1, 2, 3$, from Uniform $U(0, 1)$ distribution.

Step 6: Set $(\delta^i, \mu^i, \sigma^i) = (\delta^*, \mu^*, \sigma^*)$ if $u_i \leq \min\{1, \Omega_i\}$ for $i = 1, 2, 3$; else set $(\delta^i, \mu^i, \sigma^i) =$ $(\delta^{i-1}, \mu^{i-1}, \sigma^{i-1}).$

Step 7: Obtain $R^{i}(t)$ and $h^{i}(t)$ by replacing δ , μ , and σ by their δ^{i} , μ^{i} , and σ^{i} , respectively.

Step 8: Repeat Steps 2–7 \mathscr{B} times to obtain \mathscr{B} draws of δ , μ , σ , $R(t)$, and $h(t)$ (say, φ) as $\varphi^{i} = (\delta^{i}, \mu^{i}, \sigma^{i}, R^{i}(t), h^{i}(t))$, $i = 1, 2, ..., \mathscr{B}$.

Step 9: Find the Bayes estimate of φ as

$$
\widehat{\varphi} = \frac{1}{\mathscr{B} - \mathscr{B}_0} \sum_{i = \mathscr{B}_0 + 1}^{\mathscr{B}} \varphi^i.
$$

where \mathscr{B}_0 is the burn-in size.

Step 10: Obtain the BCI via LF-based of φ as

- a. Arrange φ^i as $\varphi^{[\mathscr{B}_0+1]}, \varphi^{[\mathscr{B}_0+2]}, \ldots, \varphi^{[\mathscr{B}]}$.
- b. Determine *ρ*.
- c. Obtain the $100(1 \rho)\%$ BCI of φ as

 $\{\varphi^{[(\mathscr{B}-\mathscr{B}_0)\rho/2]},\varphi^{[(\mathscr{B}-\mathscr{B}_0)(1-\rho/2)]}\}$.

4.2 Posterior Density via PS-Based

Using (11) and (18) , the joint posterior PDF via PS-based (say, $\Pi_2(\cdot)$) becomes

$$
\Pi_{2}(\delta,\mu,\sigma|\mathbf{x}) \propto \delta^{a-1}\mu^{c-1}\sigma^{e-1}e^{-(b\delta+d\mu+f\sigma)}
$$
\n
$$
\times \prod_{i=1}^{m+1} \left[\frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\sigma x_{i-1}^{-1} \right)^{\delta} \right) - \frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\sigma x_{i}^{-1} \right)^{\delta} \right) \right] \prod_{i=1}^{m} \left[\frac{1}{\Gamma(\mu)} \gamma \left(\mu, \left(\sigma x_{i}^{-1} \right)^{\delta} \right) \right]^{R_{i}}.
$$
\n(22)

Certainly, from [\(22\),](#page-8-1) the Bayes estimator via PS-based (say $\Pi(\delta,\mu,\sigma)$) cannot be obtained in a closed expression. Thus, following the same MCMC algorithm described in [Subsection 4.1,](#page-7-4) the M-H algorithm with the start values $(\delta^0, \mu^0, \sigma^0) = (\tilde{\delta}, \tilde{\mu}, \tilde{\sigma})$ can be easily implemented to approximate Bayes estimates as well as their BCI estimates of δ , μ , σ , $R(t)$, and $h(t)$.

5 Numerical Comparisons

The performance of the proposed estimation methodologies is highlighted in this part. According to the algorithm proposed by Balakrishnan et al. [\[13\]](#page-28-7) for various levels of *n* (total test items), *m* (objective sample size), and **R** (progressive design), large 1000 PT2C samples are simulated when (δ, μ, σ) is taken as (1.5, 1.5, 0.6). At a distinct time $t = 0.2$, the estimates of $R(t)$ and $h(t)$ are evaluated when their actual values are 0.952 and 1.341, respectively. For each $n (= 50,100)$, the total number of failed subjects *m* is determined by the failure percentage, such as $\frac{m}{n} \times 100\% = 40\%$ and 80%. To assess the effects of the removals R_i , $i = 1, 2, ..., m$, for specified (n, m) , several progressive fashions are also considered, namely:

Once the simulated PT2C samples are acquired, the classical (point and 95% interval) estimations are offered. Following two independent information requirements called prior-mean and priorvariance, we can easily assign certain values to the proposed prior parameters; see Kundu [\[14\]](#page-28-8). Therefore, two different sets for the hyperparameter values of a, b, c, d, e and f of δ , μ , and σ are utilized, called Prior-I: $(a, c, e) = (3, 3, 1)$ and $b = d = f = 2$ and Prior-II: $(a, c, e) = (15, 15, 5)$ and $b = d = f = 10$.

To conduct the M-H sampling procedure, 12,000 MCMC samples are gathered from the posterior functions[\(20\)](#page-7-3) and [\(22\).](#page-8-1) For each simulated Markov chain, the first 2000 variates are removed to ignore the effect of the selection of initial guesses. In all proposed numerical simulations, we assume that all IGG model parameters are unknown. We also assume that the practitioner records the failure time of all test units $m(1 \le m \le n)$ and withdraws preassigned live units **R** ($\sum_{i=1}^{m} R_i = n - m$) during testing, and stops the test before all test units fail.

The performances of the point theoretical results of δ , μ , σ , $R(t)$, or $h(t)$ are examined in terms of their values obtained by root-mean-squared-errors (RMSE) and mean-relative-absolute-bias (MRAB). In addition, when $\rho = 5\%$, the interval comparison is made based on average interval length (AIL) and coverage-percentage (CP). Taking $\vartheta_1 = \delta$, $\vartheta_2 = \mu$, $\vartheta_3 = \sigma$, $\vartheta_4 = R(t)$, and $\vartheta_5 = h(t)$, the average point estimates (APEs) along with their RMSEs, MRABs, AILs, and CPs of ϑ , $\iota = 1, ..., 5$, are obtained using the following formulae, respectively, as

$$
APE(\vartheta_{i}) = \frac{1}{1000} \sum_{j=1}^{1000} \hat{\vartheta}_{i}^{(j)},
$$

\nRMSE $(\vartheta_{i}) = \sqrt{\frac{1}{1000} \sum_{j=1}^{1000} (\hat{\vartheta}_{i}^{(j)} - \vartheta_{i})^{2}},$
\nMRAB $(\vartheta_{i}) = \frac{1}{1000} \sum_{j=1}^{1000} \frac{1}{\vartheta_{i}} |\hat{\vartheta}_{i}^{(j)} - \vartheta_{i}|,$
\n
$$
AIL(\vartheta_{i}) = \frac{1}{1000} \sum_{j=1}^{1000} (U(\hat{\vartheta}_{i}^{(j)}) - L(\hat{\vartheta}_{i}^{(j)})),
$$

and

$$
\text{CP}(\vartheta_{\iota}) = \frac{1}{1000} \sum\nolimits_{j=1}^{1000} 1_{\left(L_{\hat{\vartheta}_{\iota}^{(j)}} : U_{\hat{\vartheta}_{\iota}^{(j)}} \right)} (\vartheta_{\iota}) \, ,
$$

where $\hat{\theta}^{(j)}_i$ denotes the offered estimate of ϑ_i , $1(\cdot)$ is the indicator operator, $L(\hat{\theta}^{(j)}_i)$ denotes the lower interval bound, and $U(\hat{\vartheta}_{i}^{\omega})$ denotes the upper interval bound.

All calculations are performed in R with the 'coda' (proposed by Plummer et al. [\[15\]](#page-28-9)) and 'maxLik' (by Henningsen et al. [\[16\]](#page-28-10)) packages. [Tables 1](#page-10-0)[–5](#page-14-0) list the APEs, RMSEs, and MRABs of each unknown subject in the first, second, and third columns, respectively. Meanwhile, in [Tables 6](#page-14-1)[–10,](#page-18-2) the AILs and CPs of each unknown subject are reported in the first and second columns, respectively. For distinction, using LF (as an example), we abbreviate the Bayes estimates MCMC using LF-based, ACI using LFbased, and BCI using LF-based as MCMC-LF, ACI-LF, and BCI-LF, respectively. From [Tables 1](#page-10-0)[–10,](#page-18-2) regarding the lowest values of RMSE, MRAB, and AIL, as well as the highest values of CP, we can make the following observations:

- In general, the proposed point (or interval) estimates of δ , σ , $R(t)$, or $h(t)$ showed good behavior.
- As *n* (or *m*) increases or $\sum_{i=1}^{m} R_i$ decreases, the accuracy of all acquired estimates becomes better.
- Comparing the proposed point approaches, it is clear that:
	- The MLE (or MCMC-LF) of *δ*, *σ*, *R(t)*, and *h(t)* performed better compared to those obtained from the PS (or MCMC-PS) approach.
	- The performance of μ behaved better via the PS (or MCMC-PS) approach compared to others.
- Comparing the proposed interval approaches, it is clear that:
	- The ACI-LF estimates of *δ*, *σ*, and *R(t)* have overall lower AILs and higher CPs compared to those obtained using the ACI-PS approach.
	- The AILs of ACI-PS estimates of μ and $h(t)$ have worked effectively compared to those developed from the ACI-LF approach.
- The CPs of the BCI estimates are (in most cases) greater than the specified nominal level, while the ACI estimates are lower (or closer) to the specified nominal level.
- Due to the availability of gamma priors, Bayes' MCMC-LF (or MCMC-PS) estimates of all unknown parameters outperform ML (or MPS) estimates. The same comment is also drawn in the context of comparing the BCI-LF (or BCI-PS) with the ACI-LF (or ACI-PS).
- Obviously, the variance of Prior-II is less than that of Prior-I. Therefore, all Bayes estimates of all unknown parameters developed from Prior-II using LF (or PS) data outperform those obtained based on other methods.
- Comparison of the proposed Scheme-1 (first stage) and Scheme-3 (last stage), it is clear that the point estimates of δ , μ , and σ via the LF (using Scheme-1) and via the PS (using Scheme-3) behaved better than others.
- Regarding the interval estimates of δ , μ , and σ , the associated asymptotic/credible interval estimates become better under Scheme-3, in most situations, compared to others.
- As a tip, to obtain accurate estimates of any unknown life parameter when the proposed censored data are present, the experimenter should record an appropriate effective sample size, taking into account the total cost of the test.
- To sum up, the Bayes M-H procedure is recommended to study the unknown parameters of life of the IGG model in the presence of PT2C data.

$\mathfrak n$	\boldsymbol{m}	Scheme		MLE					MCMC-LF		
							Prior-I			Prior-II	
	50 20		1.6077	0.2837	0.1427	1.5747	0.1610	0.0704	1.4570	0.1285	0.0339
			1.6280	0.3273	0.1600	1.4847	0.1512	0.0622	1.4661	0.1284	0.0298
		3	1.6384	0.3423	0.1617	1.5343	0.1579	0.0488	1.4517	0.1422	0.0328
	40 1		1.5771	0.2029	0.1040	1.4101	0.1490	0.0599	1.5022	0.1318	0.0335
			1.5853	0.2148	0.1110	1.5027	0.1444	0.0614	1.4742	0.1335	0.0280
			1.5688	0.2135	0.1100	1.4591	0.1425	0.0370	1.5176	0.1349	0.0355
											(0.41)

Table 1: The point comparisons of *δ*

	Table 1 (continued)											
\mathfrak{m} n	Scheme		MLE		MCMC-LF							
					Prior-I			Prior-II				
10040	$\mathbf{1}$	1.5510	0.1745	0.0909	1.5711	0.1595	0.0690	1.4927	0.1146	0.0204		
	\overline{c}	1.5721	0.2072	0.1053	1.4067	0.1230	0.0329	1.5039	0.1220	0.0250		
	3	1.5803	0.2133	0.1093	1.4659	0.1351	0.0250	1.4562	0.1282	0.0317		
80	$\mathbf{1}$	1.5535	0.1351	0.0700	1.5115	0.1446	0.0450	1.4749	0.1249	0.0236		
	\overline{c}	1.5426	0.1387	0.0722	1.4079	0.1352	0.0277	1.4672	0.1196	0.0230		
	3	1.5435	0.1439	0.0746	1.5199	0.1342	0.0305	1.4605	0.1327	0.0340		
			MPSE					MCMC-PS				
20 50	$\mathbf{1}$	1.8248	0.4642	0.2391	1.5988	0.1967	0.0903	1.5474	0.1447	0.0542		
	\overline{c}	1.8222	0.4737	0.2421	1.5455	0.1634	0.0750	1.4462	0.1418	0.0491		
	3	1.7224	0.4100	0.1951	1.3956	0.1603	0.0696	1.4570	0.1452	0.0350		
40		1.6866	0.2821	0.1469	1.3910	0.1620	0.0726	1.5382	0.1520	0.0543		
	\overline{c}	1.6907	0.2855	0.1493	1.5518	0.1533	0.0565	1.4289	0.1446	0.0474		
	3	1.6263	0.2358	0.1203	1.5284	0.1501	0.0492	1.5420	0.1713	0.0798		
10040	1	1.6697	0.2537	0.1321	1.6022	0.1886	0.0892	1.4876	0.1336	0.0346		
	$\overline{2}$	1.6811	0.2776	0.1441	1.3875	0.1509	0.0542	1.4324	0.1245	0.0388		
	3	1.6307	0.2450	0.1252	1.5126	0.1379	0.0321	1.4868	0.1297	0.0283		
80	$\mathbf{1}$	1.6164	0.1806	0.0952	1.5349	0.1423	0.0457	1.5021	0.1400	0.0288		
	\overline{c}	1.6026	0.1700	0.0890	1.4268	0.1475	0.0539	1.5097	0.1396	0.0336		
	3	1.5806	0.1543	0.0806	1.5011	0.1373	0.0382	1.5856	0.1486	0.0510		

Table 2: The point comparisons of *μ*

	Table 2 (continued)										
\boldsymbol{n} \mathfrak{m}	Scheme		MLE					MCMC-LF			
						Prior-I			Prior-II		
	$\overline{2}$	1.4626	0.0982	0.1149	1.4541	0.0876	0.0553	1.4856	0.0695	0.0410	
	3	1.4598	0.0992	0.1268	1.4576	0.0962	0.0572	1.4883	0.0481	0.0226	
40		1.4620	0.0899	0.0953	1.5179	0.0644	0.0368	1.5257	0.0331	0.0169	
	$\overline{2}$	1.4626	0.0893	0.0949	1.4576	0.0703	0.0433	1.5232	0.0391	0.0229	
	3	1.4576	0.0835	0.0983	1.4143	0.0613	0.0337	1.5011	0.0254	0.0141	
10040		1.4619	0.0786	0.0854	1.4639	0.0579	0.0303	1.4859	0.0362	0.0179	
	2	1.4623	0.0783	0.0852	1.5610	0.0587	0.0313	1.5495	0.0347	0.0192	
	3	1.4602	0.0798	0.0865	1.5103	0.0461	0.0245	1.4905	0.0305	0.0169	
80		1.4622	0.0689	0.0752	1.5775	0.0428	0.0231	1.5477	0.0314	0.0136	
	2	1.4626	0.0684	0.0750	1.4183	0.0575	0.0312	1.4769	0.0312	0.0168	
	3	1.4595	0.0611	0.0770	1.4952	0.0277	0.0138	1.5291	0.0255	0.0139	

Table 3: The point comparisons of *σ*

Table 3 (continued)										
$n \, m$	Scheme		MLE			MCMC-LF				
						Prior-I			Prior-II	
									0.4906 0.1684 0.1511 0.5092 0.1288 0.0719 0.5479 0.1267	0.0835
	3	0.4914			0.1653 0.1461 0.5288 0.1451 0.0701			0.4943	0.1181	0.0636

Table 4: The point comparisons of *R(t)*

MLE Scheme \boldsymbol{m} n							MCMC-LF				
							Prior-I			Prior-II	
50	20	$\mathbf{1}$	1.3716	0.5793	0.3386	1.2032	0.6067	0.3919	1.0642	0.3620	0.2332
		\overline{c}	1.2886	0.4699	0.2789	0.9517	0.5271	0.3233	1.0673	0.4549	0.2916
		3	1.2868	0.4588	0.2685	1.7641	0.5161	0.3238	1.5692	0.3744	0.2196
	40	$\mathbf{1}$	1.3137	0.4568	0.2721	1.2421	0.2799	0.1621	1.2784	0.2559	0.1487
		\overline{c}	1.3159	0.4611	0.2733	1.4074	0.3285	0.2001	1.2961	0.2263	0.1362
		$\overline{3}$	1.3041	0.4349	0.2576	1.0996	0.3389	0.2178	1.4356	0.2330	0.1453
	10040	$\mathbf{1}$	1.3235	0.4072	0.2426	0.8355	0.3777	0.2019	1.0985	0.3077	0.1923
		\overline{c}	1.3387	0.3288	0.1949	1.2816	0.2375	0.1460	1.2823	0.2222	0.1299
		3	1.3264	0.3173	0.1872	1.3361	0.2831	0.1795	1.3762	0.1804	0.0961
	80	$\mathbf{1}$	1.2926	0.3307	0.1983	1.4479	0.2550	0.1528	1.4729	0.2507	0.1538
		\overline{c}	1.3161	0.3148	0.1885	1.4201	0.2786	0.1560	1.4175	0.1796	0.1125
		$\overline{3}$	1.3023	0.3065	0.1813	1.4748	0.3443	0.2017	1.3804	0.2143	0.1230
				MPSE		MCMC-PS					
50	20	$\mathbf{1}$	1.0883	0.6785	0.4153	0.9217	0.7178	0.4826	1.1026	0.5693	0.3443
		$\overline{2}$	1.1457	0.5463	0.3328	0.8055	0.6076	0.4060	0.9480	0.4859	0.2961
		$\overline{3}$	1.1341	0.5071	0.3034	1.8203	0.6112	0.3738	1.8989	0.7003	0.4338
	40	$\mathbf{1}$	1.1403	0.5119	0.3112	1.1520	0.4279	0.2615	1.2045	0.3924	0.2311
		\overline{c}	1.1683	0.5041	0.3052	1.0759	0.3776	0.2351	1.3341	0.3065	0.2014
		$\overline{3}$	1.1773	0.4683	0.2815	1.5356	0.4985	0.3184	1.2698	0.2809	0.1694
	10040	$\mathbf{1}$	1.1500	0.4764	0.2900	0.7572	0.5269	0.3173	1.0337	0.3730	0.2360
		\overline{c}	1.2641	0.3603	0.2155	1.2937	0.2237	0.1357	1.2602	0.2025	0.1232
		$\overline{3}$	1.2402	0.3394	0.2025	1.6176	0.4133	0.2580	1.5947	0.3654	0.2149
	80	$\mathbf{1}$	1.1908	0.3684	0.2242	1.6057	0.3870	0.2480	1.5557	0.2684	0.1698
		\overline{c}	1.2320	0.3410	0.2051	1.2087	0.3207	0.1963	1.1545	0.2306	0.1286
		$\overline{3}$	1.2254	0.3283	0.1964	1.3158	0.3383	0.2164	1.2997	0.2211	0.1376

Table 5: The point comparisons of $h(t)$

Table 6: The interval comparisons of *δ*

n	\boldsymbol{m}	Scheme	ACI-LF		BCI-LF					
					Prior-I		Prior-II			
50	20		1.2813	0.952	0.4308	0.973	0.3417	0.980		
		2	0.9403	0.944	0.3479	0.965	0.3334	0.971		
		3	0.9309	0.927	0.3604	0.947	0.3481	0.954		
	40		0.6332	0.965	0.3567	0.986	0.3022	0.994		
		$\overline{2}$	0.6127	0.952	0.3382	0.973	0.3086	0.981		
		3	0.6110	0.939	0.3380	0.960	0.3309	0.967		
100	40		0.7657	0.968	0.4003	0.989	0.3371	0.997		
		2	0.5512	0.957	0.3439	0.978	0.3137	0.986		

Table 7: The interval comparisons of μ

\boldsymbol{n}	\boldsymbol{m}	Scheme 20 1	ACI-LF			BCI-LF		
					Prior-I		Prior-II	
50			2.3852	0.841	0.1904	0.914	0.1559	0.931
		$\overline{2}$	2.2584	0.857	0.1571	0.928	0.1405	0.947
		3	2.2177	0.885	0.1505	0.957	0.1209	0.968
	40	1	2.0073	0.867	0.1563	0.942	0.1379	0.960
		$\overline{2}$	1.1767	0.894	0.1375	0.976	0.1259	0.978
		3	1.0459	0.902	0.1289	0.976	0.1206	0.987
100	40	1	2.0738	0.868	0.1613	0.941	0.1320	0.960
		\overline{c}	1.8204	0.876	0.1473	0.955	0.1305	0.972
		3	1.4948	0.893	0.1424	0.970	0.1056	0.983
	80	1	1.0867	0.889	0.1459	0.960	0.1295	0.981
		$\overline{2}$	0.7623	0.907	0.1086	0.980	0.1058	0.985
		3	0.7513	0.917	0.1171	0.982	0.0941	0.987
				ACI-PS			BCI-PS	
50	20	1	1.2145	0.904	0.1790	0.946	0.1309	0.955
		$\overline{2}$	1.2109	0.909	0.1623	0.952	0.1346	0.951
								(Continued)

	Table 7 (continued)								
\boldsymbol{n}	\mathfrak{m}	Scheme	ACI-LF		BCI-LF				
					Prior-I		Prior-II		
		3	0.7144	0.920	0.1557	0.963	0.1071	0.972	
	40		0.9033	0.913	0.1366	0.956	0.1286	0.973	
		$\overline{2}$	0.9382	0.910	0.1121	0.953	0.0986	0.982	
		3	0.6524	0.932	0.1238	0.976	0.0934	0.984	
100	40		0.8761	0.921	0.1486	0.964	0.1192	0.979	
		$\overline{2}$	0.8723	0.922	0.1455	0.965	0.1066	0.984	
		3	0.5141	0.937	0.1154	0.981	0.0902	0.988	
	80		0.6317	0.933	0.1127	0.977	0.1102	0.983	
		$\overline{2}$	0.6827	0.942	0.1104	0.986	0.0959	0.987	
		3	0.4758	0.951	0.1005	0.989	0.0825	0.991	

Table 8: The interval comparisons of *σ*

n m Scheme ACI-LF BCI-LF Prior-I Prior-II 50 20 1 0.1278 0.911 0.0684 0.937 0.0572 0.953 2 0.1176 0.918 0.0688 0.935 0.0466 0.957 3 0.1109 0.921 0.0813 0.928 0.0808 0.947 40 1 0.1147 0.917 0.0659 0.939 0.0550 0.952 2 0.0522 0.933 0.0518 0.943 0.0391 0.965 3 0.0803 0.928 0.0633 0.940 0.0457 0.958 100 40 1 0.0885 0.938 0.0663 0.950 0.0563 0.968 2 0.0828 0.943 0.0646 0.952 0.0441 0.974 3 0.0776 0.945 0.0769 0.944 0.0537 0.970 80 1 0.0796 0.944 0.0528 0.957 0.0469 0.971 2 0.0477 0.955 0.0403 0.960 0.0329 0.975 3 0.0690 0.949 0.0569 0.954 0.0414 0.973 ACI-PS BCI-PS 50 20 1 0.1774 0.895 0.0810 0.920 0.0760 0.931 2 0.1154 0.904 0.0810 0.918 0.0628 0.935 3 0.1659 0.900 0.1063 0.912 0.1038 0.923 40 1 0.1403 0.908 0.0790 0.933 0.0662 0.936 2 0.0720 0.926 0.0644 0.929 0.0498 0.943 3 0.1078 0.919 0.0747 0.924 0.0692 0.930 100 40 1 0.1197 0.926 0.0794 0.936 0.0743 0.951 2 0.1112 0.924 0.0796 0.935 0.0615 0.962 3 0.1112 0.925 0.0745 0.940 0.0657 0.958 80 1 0.1016 0.929 0.0633 0.946 0.0514 0.966 2 0.0532 0.936 0.0468 0.948 0.0434 0.967 3 0.0841 0.932 0.0678 0.943 0.0472 0.970

Table 9: The interval comparisons of *R(t)*

\boldsymbol{n}	m	Scheme	ACI-LF			BCI-LF				
					Prior-I		Prior-II			
50	20	$\mathbf{1}$	4.8207	0.891	1.2557	0.932	1.0404	0.953		
			2.1276	0.909	1.3205	0.928	1.0873	0.946		
		$\frac{2}{3}$	3.7047	0.901	1.3993	0.924	1.3739	0.947		
	40	$\mathbf{1}$	2.1424	0.900	1.0163	0.943	0.8362	0.964		
		\overline{c}	2.0774	0.912	1.1200	0.940	0.9500	0.961		
		$\overline{\mathbf{3}}$	1.7131	0.918	1.0309	0.938	1.0186	0.956		
100	40	$\mathbf{1}$	2.2815	0.922	1.3822	0.957	1.1552	0.966		
		\overline{c}	1.9498	0.919	0.9902	0.960	0.8055	0.975		
		$\overline{3}$	2.3791	0.910	1.0045	0.948	0.8220	0.972		
	80	$\mathbf{1}$	1.4611	0.928	1.2239	0.967	0.7061	0.988		
		\overline{c}	1.4282	0.942	0.8934	0.981	0.7699	0.984		
		$\overline{3}$	1.1908	0.953	0.9950	0.976	0.7475	0.985		
				ACI-PS			BCI-PS			
50	20	$\mathbf{1}$	2.5623	0.917	1.0601	0.947	0.8967	0.967		
		\overline{c}	2.4664	0.915	1.0098	0.951	0.9260	0.962		
		$\overline{\mathbf{3}}$	2.4522	0.914	1.1464	0.942	1.0669	0.958		
	40	$\mathbf{1}$	2.0923	0.920	0.8919	0.957	0.8736	0.970		
		\overline{c}	1.9119	0.923	0.9281	0.954	0.8477	0.974		
		$\overline{\mathbf{3}}$	1.4353	0.926	0.8808	0.960	0.8167	0.978		
100	40	$\mathbf{1}$	2.0164	0.930	1.4839	0.969	1.1885	0.978		
		$\frac{2}{3}$	1.9060	0.938	0.8074	0.977	0.7495	0.985		
			1.7277	0.934	1.1011	0.973	1.0631	0.981		
	80	$\mathbf{1}$	1.3577	0.939	1.0535	0.980	0.9022	0.982		
		$\frac{2}{3}$	1.4091	0.944	0.9979	0.983	0.6250	0.999		
			1.1316	0.957	1.0574	0.979	0.8011	0.987		

Table 10: The interval comparisons of *h(t)*

6 Optimum PT2C

The previous sections dealt with the derivation of point and interval estimations, using both frequentist and Bayesian MCMC estimations, for the parameters of life of the IGG distribution when samples are gathered from the PT2C strategy. Following Ng et al. [\[17\]](#page-28-11), when the design of removal items **R** is fixed in advance as well as *n* (total test items) and *m* (effective sample) are pre-specified, one can choose the optimal $\mathbf{R} = (R_1, R_2, \dots, R_m)$ censoring scheme.

Thus, to select the optimal progressive censoring (OPC) plan, [Table 11](#page-19-0) reports common criteria for this purpose. Regarding the A-and D-optimality criteria, our objective is to reduce the trace and determinant values of estimated variances and covariances developed from the LF and PS methods. Further, the goal of F-optimality is to maximize the observed values of the Fisher matrices in relation to the MLE (or MPSE) (say, *ξ*ˆ) of the unknown parameter(s) (say *ξ*) being considered. The OPC plan that offers more information should correspond to the lowest A and D values and the largest F value; see, for example, Elshahhat et al. [\[18\]](#page-28-12), Elshahhat et al. [\[19\]](#page-28-13), among others.

Criterion	Goal
A	Minimize trace $(I^{-1}(\hat{\xi}))$
D	Minimize det $(I^{-1}(\hat{\xi}))$
H,	Maximize trace $(I(\hat{\xi}))$

Table 11: Three criteria of OPC plans

7 Diesel Engine Data Analysis

This section analyzes a useful real data set consisting of the failure times (in weeks) of 20 mechanical components of a diesel engine to demonstrate the performance of the proposed methodologies; see Murthy et al. [\[20\]](#page-28-14). For computational convenience, we multiply each original data unit by one hundred, and the new transformed data set is: 6.70, 6.80, 7.60, 8.10, 8.40, 8.50, 8.50, 8.60, 8.90, 9.80, 9.80, 11.4, 11.4, 11.5, 12.1, 12.5, 13.1, 14.9, 16.0, and 48.5.

First, the IGG distribution is fitted to the complete diesel engine data with eleven inverted lifetime distributions (for $x > 0$ and $\delta, \mu, \sigma > 0$) as competitors, namely:

- (1) Generalized inverted Gompertz (GIG(δ, μ, σ)) by Elshahhat et al. [\[21\]](#page-28-15).
- (2) Alpha-power inverse-Weibull (APIW(δ, μ, σ)) by Basheer [\[22\]](#page-28-16).
- (3) Generalized inverse-Weibull (GIW(δ , μ , σ)) by De Gusmão et al. [\[23\]](#page-28-17).
- (4) Exponentiated inverted-Weibull (EIW(μ , σ)) by Flaih et al. [\[24\]](#page-28-18).
- (5) Generalized inverted-exponential (GIE(μ , σ)) by Abouammoh et al. [\[25\]](#page-28-19).
- (6) Generalized inverted half-logistic (GIHL(μ , σ)) by Potdar et al. [\[26\]](#page-28-20).
- (7) Inverted exponentiated Rayleigh (IER(μ , σ)) by Ghitany et al. [\[27\]](#page-28-21).
- (8) Inverted Nadarajah–Haghighi (INH(μ , σ)) by Tahir et al. [\[28\]](#page-29-1).
- (9) Inverted Gompertz ($IGo(\mu, \sigma)$) by Eliwa et al. [\[29\]](#page-29-2).
- (10) Inverse-Weibull (IW(μ , σ)) by Keller et al. [\[30\]](#page-29-3).
- (11) Inverse gamma (IG(μ , σ)) by Glen [\[31\]](#page-29-4).

To evaluate the feasibility of the IGG model in comparison with other popular models, several information measures are implemented, namely: (i) Kolmogorov-Smirnov (KS) statistic (with its *p*-value); (ii) Anderson-Darling (AD); (iii) Cramer von Mises (CvM); (iv) estimated negative loglikelihood (ENL); (v) Akaike information (AI); (vi) consistent Akaike information (CAIC); and (vii) Hannan-Quinn information (HQI).

The MLEs (with their standard-errors (SEs)) of δ , μ , and σ as well as the evaluated information criteria are provided in [Table 12.](#page-20-0) It shows that the IGG distribution has the greatest *p*-value and the lowest values for other statistics, thus the IGG model fits the diesel engine data set quite satisfactorily and is the best choice among others. Moreover, the quantile–quantile (Q–Q) plots for the competitive distributions are displayed in [Fig. 3.](#page-20-1) It also confirms the same findings as displayed in [Table 12.](#page-20-0)

Model	MLE (SE)							Statistics			
	δ	μ	σ	ENL	AIC	CAIC	BIC	HQIC	AD	CvM	$KS(p-value)$
IGG		7.7656 (5.8386) 0.3521 (0.3504) 7.3541 (0.9362) 52.907			111.81	113.31	114.80	112.39	0.3229	0.0445	0.1144(0.956)
${\rm GIG}$	2.4085 (1.3514)		4.2427 (3.6299) 19.924 (7.7511) 53.092		112.19	113.69	115.17	112.77	0.3061	0.0420	0.1145(0.956)
APIW	485.95 (1161.7)		3.7807 (0.5672) 750.25 (968.83) 54.029		114.06	115.56	117.05	114.64	0.4185	0.0545	0.1146(0.955)
GIW	3.7843 (0.6867)		8.0911 (668.49) 1.5647 (489.20) 53.474		112.95	114.45	115.93	113.53	0.3517	0.0464	0.1141(0.956)
EIW			84.818 (45.153) 2.0182 (0.2506) 58.146		120.29	120.99	122.28	120.68	0.5438	0.0696	0.2260(0.259)
GIE			8.5938 (3.5241) 27.176 (4.8461) 57.703		119.41	120.11	121.39	119.80	1.0166	0.1385	0.1655(0.644)
GIHL			5.5828 (2.1396) 0.0342 (0.0054) 56.923		117.84	118.55	119.83	118.23	0.8622	0.1152	0.1495(0.763)
IER			1.9731 (0.6436) 128.51 (31.149) 55.262		114.52	115.22	116.51	114.91	0.5704	0.0735	0.1326(0.873)
INH			0.5158 (0.1374) 6.4190 (0.2920) 54.866		113.73	114.43	115.72	114.12	0.6969	0.1038	0.2113(0.334)
IGo			2.3979 (1.6447) 21.837 (7.4234) 55.255		114.51	115.22	116.50	114.90	0.2850	0.0403	0.2261(0.258)
IW			2.0202 (0.2310) 81.148 (38.906) 58.270		120.53	121.24	122.53	120.92	0.5480	0.0704	0.2117(0.332)
IG			7.4987 (2.3205) 75.333 (24.110) 56.120		116.24	116.94	118.23	116.62	0.7674	0.1007	0.1339(0.866)
$\frac{0}{1}$ $0.\overline{8}$ 0.6 ECDF 0.4 0.2 0.0	0.2 0.4 0.6 0.0 IGG	$\frac{0}{1}$ 0.8 0.6 ECDF 0.4 0.2 0.0 0.8 1.0	$0.0 \quad 0.2$ 0.4 0.6 0.8 GIG	1.0	$\frac{0}{1}$ ∞ \circ 0.6 ECDF 0.4 0.2 0.0	0.0	$0.2 \quad 0.4$ 0.6 APIW	0.8 1.0	$\frac{1}{1}$ $0.\overline{8}$ 0.6 ECDF 0.4 0.2 0.0	0.0	0.2 0.4 0.6 0.8 1.0 GIW
1.0 $0.\overline{8}$ 0.6 ECDF 0.4 0.2 0.0	0.2 0.4 0.6 0.8 1.0 0.0	$\frac{0}{1}$ 0.8 0.6 ECDF 0.4 0.2 0.0	0.0 0.2 0.4 0.6 0.8	1.0	1.0 ∞ ö 0.6 ECDF 0.4 0.2 0.0	0.0	0.2 0.4 0.6 0.8 1.0		$\frac{0}{1}$ $0.\overline{8}$ 0.6 ECDF 0.4 0.2 0.0		0.0 0.2 0.4 0.6 0.8 1.0
	EIW		GIE				GIHL				IER
$\frac{0}{1}$ $0.\overline{8}$ $0.\overline{6}$ ECDF 0.4 0.2 0.0	0.0 0.2 0.4 0.6	$\frac{0}{1}$ 0.8 0.6 ECDF 0.4 0.2 0.0 0.8 1.0	0.0 0.2 0.4 0.6 0.8	1.0	$\overline{1}$. O $0.\overline{8}$ $0.\overline{6}$ ECDF 0.4 $0.\overline{2}$ 0.0		0.0 0.2 0.4 0.6 0.8 1.0		$\frac{1}{1}$ 0.8 0.6 ECDF 0.4 $0.\overline{2}$ 0.0		0.0 0.2 0.4 0.6 0.8 1.0
	$\ensuremath{\mathsf{INH}}$		IGo				IW				$\sf IG$

Table 12: Fitting results of IGG and its competitors from diesel engine data

Figure 3: The Q–Q diagrams of IGG and its competitors from diesel engine data

To capture the behavior of the estimated PDFs and CDFs of the IGG and its competitive distributions using the diesel engine data, we have provided two plots: (a) representing the histogram and the fitted densities and (b) representing the fitted/empirical reliability lines; see [Fig. 4.](#page-21-0) It demonstrates that the IGG distribution reflects the overall structure of the histograms and confirms the numerical results presented here.

Figure 4: Fitted densities and reliability lines of IGG and its competitors from diesel engine data

Using the complete diesel engine data, for different choices of **R**, three PT2C samples (with $m =$ 10) are obtained; see [Table 13.](#page-21-1) The scheme $\mathbf{R} = (1, 0, 0, 0, 1)$ (as an example) is referred to as $R =$ *(*1, 0[∗] 3, 1*)* for simplicity. For each PT2C data, the point and interval estimators of *δ*, *μ*, *σ*, *R(t)*, and *h(t)* (at $t = 10$) are obtained; see [Tables 14](#page-21-2) and [15,](#page-22-0) respectively. Since we have no prior information about IGG *(ϒ)*, the Bayesian results are approximated using the M-H algorithm based on gamma improper priors, i.e., $a_i = b_i = 0$, $i = 1, 2, 3$. Here, to perform our calculations, we set all hyperparameters values to 0.001. To run the MCMC sampler, the initial guess of *δ*, *μ*, or *σ* is taken as MLE (or MPSE), and then the first 5000 (of 30,000) iterations are taken as burn-in.

Sample	(R_1, R_2, \ldots, R_m)	Generated data
$\mathbf{1}$	$(10, 0^*9)$	6.70, 11.4, 11.4, 11.5, 12.1, 12.5, 13.1, 14.9, 16.0, 48.5
2	(0, 4, 5, 5, 0, 4)	6.70, 6.80, 7.60, 8.10, 8.40, 9.80, 13.1, 14.9, 16.0, 48.5
3	(0, 9, 10)	6.70, 6.80, 7.60, 8.10, 8.40, 8.50, 8.50, 8.60, 8.90, 9.80

Table 13: Three PT2C samples from diesel engine data

Table 14: The point (SE) estimates of δ , μ , σ , $R(t)$, and $h(t)$ from diesel engine data

Sample	Parameter	MLE	MPSE	MCMC-LF	MCMC-PS
		375.09 (16.950)	6.3776(2.3115)	$375.08 (3.16 \times 10^{-4})$	$6.3785(9.52\times10^{-4})$
	μ	0.0036(0.0012)	1.4547 (0.2280)	$0.0042(2.83\times10^{-6})$	$1.4413(7.50\times10^{-4})$
	σ	6.6528(0.0657)	13.077 (0.8674)	$6.6528(3.15\times10^{-6})$	$13.053(9.25\times10^{-4})$

Table 14 (continued)						
Sample	Parameter	MLE	MPSE	MCMC-LF	MCMC-PS	
	R(10)	0.5712(0.2858)	0.9895(0.0448)	$0.5309(2.29\times10^{-4})$	$0.9883(3.43\times10^{-5})$	
	h(10)	37.431 (10.556)	0.0307(0.0024)	$37.419(6.85\times10^{-5})$	$0.0331(7.78\times10^{-5})$	
\mathfrak{D}	δ	375.03 (9.7201)	2.4541 (0.6851)	$375.02 (3.14 \times 10^{-4})$	$2.4524(1.88\times10^{-3})$	
	μ	0.0031(0.0010)	1.4615 (0.2297)	$0.0037(2.83\times10^{-6})$	$1.4395(9.75\times10^{-4})$	
	σ	6.6510 (0.0706)	12.243 (1.9397)	$6.6510(3.09\times10^{-6})$	$12.156(1.83\times10^{-3})$	
	R(10)	0.6167(0.2912)	0.6630(0.2888)	$0.5658(2.44\times10^{-4})$	$0.6616(3.76\times10^{-4})$	
	h(10)	37.436 (8.6046)	0.1479(0.0072)	$37.422 (6.88 \times 10^{-5})$	$0.1480(1.62\times10^{-4})$	
\mathcal{E}	δ	1772.3 (8.3902)	3.4394 (0.9908)	$1772.3(6.33\times10^{-4})$	$2.4558(1.87\times10^{-3})$	
	μ	0.0010(0.0003)	1.4557 (0.2262)	$0.0011 (6.01 \times 10^{-7})$	$1.5206(1.02\times10^{-3})$	
	σ	6.6851(0.0270)	10.398 (1.0967)	$6.6850 (6.33 \times 10^{-7})$	$12.109(1.81\times10^{-3})$	
	R(10)	0.4989(0.0038)	0.5017(0.1514)	$0.4599(1.98\times10^{-4})$	$0.6312(3.95\times10^{-4})$	
	h(10)	177.13 (0.0029)	0.2656(0.0116)	$177.11(8.81\times10^{-5})$	$0.1621(1.89\times10^{-4})$	

Table 15: The interval [length] estimates of δ , μ , σ , $R(t)$, and $h(t)$ from diesel engine data

[Tables 14](#page-21-2) and [15](#page-22-0) indicate that the computed estimates of δ , μ , σ , $R(t)$, or $h(t)$ based on both MCMC approaches performed satisfactorily than those obtained based on classical approaches with respect to minimum standard-error and interval length values. Trace diagrams of *δ*, *μ*, *σ*, *R(t)*, and $h(t)$ are plotted; see [Fig. 5.](#page-23-0) For each sup-plot in [Fig. 5,](#page-23-0) the sample average and 95% BCI bounds are displayed with solid and dashed horizontal lines, respectively. Using the Gaussian kernel when the sample average is plotted as a vertical dash-dotted line, [Fig. 6](#page-25-0) displays the estimates with their histograms of δ , μ , σ , $R(t)$, and $h(t)$. It indicates that the simulated estimates (from MCMC-LF or MCMC-PS) of δ , μ , and σ are fairly symmetrical. It also shows the simulated estimates of $R(t)$ and *h(t)* are fairly symmetrical (using MCMC-LF) and are also close to being negatively and positively skewed, respectively (using MCMC-PS).

Figure 5: (Continued)

Figure 5: Trace plots of δ , μ , σ , $R(t)$, and $h(t)$ from diesel engine data

Figure 6: Posterior histograms of δ , μ , σ , $R(t)$, and $h(t)$ from diesel engine data

Now, using [Table 13,](#page-21-1) the selection of the OPC plan is explored. So, from [\(10\)](#page-3-1) and [\(16\),](#page-6-2) the criteria A, D, and F are evaluated; see [Table 16.](#page-26-1) It shows that the scheme $\mathbf{R} = (0^*9, 10)$ used in Sample 3 is the best PT2C compared to others. Clearly, the OPC plan proposed here supports our findings reported in [Section 5.](#page-8-0)

Sample	LF				
Criterion \rightarrow	A	D	F		
	1.679×10^{-6}	287.429	739578.9		
2	4.745×10^{-7}	94.4785	993350.9		
3	4.900×10^{-9}	70.3856	10499746		
	PS				
	1.048×10^{-1}	6.14721	29.29390		
2	2.324×10^{-2}	4.28454	35.86464		
	1.687×10^{-2}	2.23559	36.66400		

Table 16: The OPC design from diesel engine data

8 Concluding Remarks

In this paper, various estimates of the inverted generalized gamma parameters *δ*, *μ*, *σ*, *R(t)*, and *h(t)* have been investigated through the maximum likelihood and maximum product of spacings, and Bayes methods based on data sets collected from progressively Type-II censoring. In addition, the asymptotic confidence intervals of the same unknown quantites have been obtained based on the maximum likelihood and maximum product of spacing methods, as well as the Bayes' credible intervals have been obtained based on Bayesian approaches as well. The Monte Carlo results show that, as expected, the Bayesian-based estimates behave satisfactorily when compared with frequentist alternatives. An ideal progressive strategy has been suggested using several metrics. To confirm the practical applicability of our calculations, a real-world data set containing mechanical components of diesel engines has been examined. We recently recommended a Bayes MCMC setup using MPS-based. As future work, it would be better to extend the proposed inferential techniques to other real-life domains such as medicine, physics, chemistry, etc.

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Appendix A: Fisher-LF Elements

Differentiating [\(6\)](#page-3-0) with respect to the unknown parameters δ , μ and σ , the elements of the observed Fisher information matrix via LF can be expressed as

$$
\ell_{11} = \frac{\partial^2 \ell}{\partial \delta^2} = -\frac{m}{\delta^2} - \sum_{i=1}^m (\sigma x_i^{-1})^{\delta} \left(\ln(\sigma x_i^{-1}) \right)^2 + \sum_{i=1}^m R_i \psi_i(\delta' \delta'),
$$
\n
$$
\ell_{22} = \frac{\partial^2 \ell}{\partial \mu^2} = -n\eta'(\mu) + \sum_{i=1}^m R_i \psi_i(\mu' \mu'),
$$
\n
$$
\ell_{33} = \frac{\partial^2 \ell}{\partial \sigma^2} = -\frac{\delta}{\sigma^2} \left[m\mu + (\delta - 1) \sum_{i=1}^m (\sigma x_i^{-1})^{\delta} \right] + \sum_{i=1}^m R_i \psi_i(\sigma' \sigma'),
$$
\n
$$
\ell_{12} = \frac{\partial^2 \ell}{\partial \delta \partial \mu} = m \ln \sigma - \sum_{i=1}^m \ln x_i + \sum_{i=1}^m R_i \psi_i(\delta' \mu'),
$$
\n
$$
\ell_{13} = \frac{\partial^2 \ell}{\partial \delta \partial \sigma} = \frac{1}{\sigma} \left[m\mu - \sum_{i=1}^m (\sigma x_i^{-1})^{\delta} \left[1 + \delta \ln(\sigma x_i^{-1}) \right] \right] + \sum_{i=1}^m R_i \psi_i(\delta' \sigma'),
$$
\nand

and

$$
\ell_{23}=\frac{\partial^2\ell}{\partial\mu\partial\sigma}=\frac{m\delta}{\sigma}+\sum\nolimits_{i=1}^m R_i\psi_i(\mu'\sigma'),
$$

where $\eta'(\mu) = d\eta(\mu)/d\mu$ is the trigamma function,

$$
\psi_i(\delta'\delta') = \frac{\partial^2}{\partial \delta^2} \ln \gamma \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} (\sigma x_i^{-1})^{\delta \mu} \left(\ln \left(\sigma x_i^{-1} \right) \right)^2 \exp \left(-(\sigma x_i^{-1})^{\delta} \right),
$$

\n
$$
\psi_i(\mu'\mu') = \frac{\partial^2}{\partial \mu^2} \ln \gamma \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} \int_0^{(\sigma x_i^{-1})^{\delta}} \psi^{\mu-1} (\ln(w))^2 e^{-w} dw,
$$

\n
$$
\psi_i(\sigma'\sigma') = \frac{\partial^2}{\partial \sigma^2} \ln \gamma \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} \left(\frac{\delta}{\sigma} \right)^2 (\sigma x_i^{-1})^{\delta \mu} \exp \left(-(\sigma x_i^{-1})^{\delta} \right) \left[\mu - \delta^{-1} - (\sigma x_i^{-1})^{\delta} \right],
$$

\n
$$
\psi_i(\delta'\mu') = \frac{\partial^2}{\partial \delta \partial \mu} \ln \gamma \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} \delta (\sigma x_i^{-1})^{\delta \mu} \left(\ln \left(\sigma x_i^{-1} \right) \right)^2 \exp \left(-(\sigma x_i^{-1})^{\delta} \right)
$$

\n
$$
\psi_i(\delta'\sigma') = \frac{\partial^2}{\partial \delta \partial \sigma} \ln \gamma \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} \sigma^{-1} (\sigma x_i^{-1})^{\delta \mu} \exp \left(-(\sigma x_i^{-1})^{\delta} \right) \left[1 + \delta \ln \left(\sigma x_i^{-1} \right) \left(\mu + (\sigma x_i^{-1})^{\delta} \right) \right]
$$

\nand
\n
$$
\psi_i(\delta'\mu') = \frac{\partial^2}{\partial \delta \partial \sigma} \ln \left(\mu, (\sigma x_i^{-1})^{\delta} \right) = \psi_i^{-2} \sigma^{-1} (\sigma x_i^{-1})^{\delta \mu} \exp \left(-(\sigma x_i^{-1})^{\delta} \right) \left[1 + \delta \ln \left(\sigma x_i^{-1} \right) \left(\mu + (\sigma x_i
$$

$$
\psi_i(\mu'\sigma')=\frac{\partial}{\partial\sigma}\ln\gamma\left(\mu,(\sigma x_i^{-1})^{\delta}\right)=\frac{\delta^2}{\sigma}(\sigma x_i^{-1})^{\delta\mu}\ln\left(\sigma x_i^{-1}\right)\exp\left(-(\sigma x_i^{-1})^{\delta}\right).
$$

Appendix B: Fisher-PS Elements

Differentiating [\(12\)](#page-5-2) with respect to the unknown parameters δ , μ and σ , the elements of the observed Fisher information matrix via PS can be expressed as

$$
S_{11} = \frac{\partial^2 \ln S}{\partial \delta^2} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\delta' \delta') - \psi_i(\delta' \delta')) - (\psi_{i-1}(\delta') - \psi_i(\delta'))^2}{(\psi_{i-1} - \psi_i)^2} \right] + \sum_{i=1}^{m} R_i \psi_i(\delta' \delta'), S_{22} = \frac{\partial^2 \ln S}{\partial \mu^2} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\mu'\mu') - \psi_i(\mu'\mu')) - (\psi_{i-1}(\mu') - \psi_i(\mu'))^2}{(\psi_{i-1} - \psi_i)^2} \right] + \sum_{i=1}^{m} R_i \psi_i(\mu'\mu') - (n+1)\eta'(\mu), S_{33} = \frac{\partial^2 \ln S}{\partial \sigma^2} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\sigma' \sigma') - \psi_i(\sigma' \sigma')) - (\psi_{i-1}(\sigma') - \psi_i(\sigma'))^2}{(\psi_{i-1} - \psi_i)^2} \right] + \sum_{i=1}^{m} R_i \psi_i(\sigma' \sigma'), S_{12} = \frac{\partial^2 \ln S}{\partial \delta \partial \mu} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\delta' \mu') - \psi_i(\delta' \mu')) - (\psi_{i-1}(\delta') - \psi_i(\delta')) (\psi_{i-1}(\mu') - \psi_i(\mu'))}{(\psi_{i-1} - \psi_i)^2} \right] + \sum_{i=1}^{m} R_i \psi_i(\delta' \mu'), S_{13} = \frac{\partial^2 \ln S}{\partial \delta \partial \sigma} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\delta' \sigma') - \psi_i(\delta' \sigma')) - (\psi_{i-1}(\delta') - \psi_i(\delta')) (\psi_{i-1}(\sigma') - \psi_i(\sigma'))}{(\psi_{i-1} - \psi_i)^2} \right] + \sum_{i=1}^{m} R_i \psi_i(\delta' \sigma'),
$$

and

i=1

$$
S_{23} = \frac{\partial^2 \ln S}{\partial \mu \partial \sigma} = \sum_{i=1}^{m+1} \left[\frac{(\psi_{i-1} - \psi_i) (\psi_{i-1}(\mu' \sigma') - \psi_i(\mu' \sigma')) - (\psi_{i-1}(\mu') - \psi_i(\mu')) (\psi_{i-1}(\sigma') - \psi_i(\sigma'))}{(\psi_{i-1} - \psi_i)^2} + \sum_{i=1}^m R_i \psi_i(\mu' \sigma'),
$$

where $\psi_i(\delta)$, $\psi_i(\mu')$, $\psi_i(\sigma')$, $\psi_i(\delta'\delta')$, $\psi_i(\mu'\mu')$, $\psi_i(\sigma'\sigma')$, $\psi_i(\delta'\mu')$, $\psi_i(\delta'\sigma')$ and $\psi_i(\mu'\sigma')$ are obtained in [Section 2.](#page-2-0)