# A 2D Lattice Boltzmann Full Analysis of MHD Convective Heat Transfer in Saturated Porous Square Enclosure

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**Abstract:** A thermal lattice Boltzmann model for incompressible flow is developed and extended to investigate the natural convection flow in porous media under the effect of uniform magnetic field. The study shows that the flow behaviour is various parameters dependent. The Rayleigh number (*Ra*), Hartmann number (*Ha*), Darcy number (*Da*) and the medium inclination angle from the horizontal ( $\phi$ ), the magnetic field orientation ( $\psi$ ) and the medium porosity ( $\varepsilon$ ) effects are carried out in wide ranges encountered in industrial and engineering applications. It was found that the flow and temperature patterns change significantly when varying these parameters. To confirm the accuracy in present simulations, the present results are first validated on two test cases with and without magnetic field. A good agreement is observed by comparison with available previous works. It is found also that the lattice Boltzmann method is a reliable tool that gives a great deal of valuable information about the dynamics of buoyancy-driven flows and put on view the physics of the flow under stiff conditions.

**Keywords:** Lattice Boltzmann computer modeling, magnetic fluid, heat transfer, porous media flow, thermal convection.

# Nomenclature

| Magnetic field                 |
|--------------------------------|
| Average overall Nusselt number |
| Discrete lattice velocity      |
| Nusselt number at the hot wall |
| Total external forcing term    |
|                                |

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| g                 | Gravity field                                 |
|-------------------|---|
| u                 | Velocity vector $(u, v)$                      |
| X                 | Lattice node in $(x, y)$ coordinates          |
| $C_S$             | Lattice sound speed                           |
| $f_k, g_k$        | Discrete distribution functions.              |
| Н                 | Height of the enclosure                       |
| k <sub>e</sub>    | Effective thermal conductivity                |
| р                 | Ideal gas pressure $\rho c_s^2$               |
| $S_k$             | Source term                                   |
| Т                 | Temperature field                             |
| $\Delta T$        | Horizontal temperature gradient $T_h - T_c$   |
| $\Delta t$        | Time step                                     |
| $\Delta x$        | Lattice spacing units $(=\Delta y)$           |
| $F_{\varepsilon}$ | Geometric parameter                           |
| Da                | Darcy number                                  |
| На                | Hartmann number                               |
| Pr                | Prandtl number $v/\alpha$                     |
| Ra                | $g\beta\Delta TH^3/\nu\alpha$ Rayleigh number |

# Greek symbols

| 1477                         | Weighting factors                          |
|------------------------------|--|
| Wk                           | weighting factors                          |
| ρ                            | Fluid density (volumetric mass)            |
| υ                            | Kinetic viscosity $=\mu/\rho$              |
| α                            | Thermal diffusivity $k_e / (\rho C_p)_f$ . |
| $	au_{\upsilon}, 	au_{lpha}$ | Relaxation times for $f_k$ and $g_k$       |
| ε                            | Medium porosity                            |
| β                            | Thermal expansion coefficient              |
| $\phi$                       | Angle of inclination of the cavity         |
| Ψ                            | Magnetic field inclination angle           |
| η                            | Structural factor                          |
| Λ                            | Effective averaged heat capacity           |
| κ                            | Medium permeability                        |
|                              |  |

Subscripts Supscripts

| eq   | Equilibrium part          |
|------|---------------------------|
| i, j | Lattice vector components |

| k        | Discrete velocity direction |
|----------|-----------------------------|
| LD,NLD   | Linear and non-linear drags |
| new, old | Time-successive states      |

# 1 Introduction

Natural convection in enclosures depends strongly on many parameters monitoring the flow behaviour in specila industrial situations, namely the Rayleigh and the Prandtl number and the medium inclination angle and its configuration. Moreover, flows in medium packed with porous materials are frequently encountered in many practical applications in fluid mechanic and engineering such as solar power collectors, chemical catalytic reactors, heat exchangers, building thermal insulation, nuclear energy, petroleum reservoir operations, packed-bed catalytic reactors, food processing and so on...

In general, transport phenomena in porous medium involve three scales: the pore scale, the representative elementary volume (REV) scale and the domain scale. The first approach needs much detailed geometric details to reach the local information of the fluid flow. The computational domain size will, however, not be permitted due to the limited computer resources. The REV scale approach is considered as the minimum size scale to determine statistically the macroscopic quantities and is the most adopted in the previous porous media flows studies. This approach, based on some semi-empirical models, is incorporated in the evolution equations by adding forcing term taking account of the porous mediam characteristics. These semi-empirical models are based on the Ergun's experimental investigations to express some geometric parameters linked to the porous mediam porosity.

In the literature, numerous models have been used to simulate flows in porous media, such as the Darcy model, the Brinkman-extended Darcy model, and the Forchheimer-extended Darcy model. The Darcy model (1856) scheme is an empirical law; where the pressure gradient is related to the viscous resistance based on experimental observations.

Although the Darcy model has been widely used to investigate flow in porous media, it was limited to low infiltration velocities. For high velocities, the so-called non-Darcy effects (viscous dissipation due to the solid boundary in the porous matrix and the inertia) are to be considered. The Brinkmann-extended-Darcy model (1947) was developed for accounting for viscous force. However, this model does not show agreement with experimental observations only for high porosity ( $\varepsilon \rightarrow 1$ ), also it presents difficulty to evaluate the equivalent viscosity of the medium that is function of both the porosity and the tortuous character of the medium. The Forchheimer-extended Darcy (1901) model was improved by Vafai and Tien (1981) using a local volume averaging technique to account for the inertia effect. It is currently the most widely used to simulate incompressible steady fluid flows through saturated homogenous and isotropic porous medium. The three mentioned models are, also, not generalized to be applicable for a medium with a variable porosity.

In spite of the several experimental efforts and the numerical simulations based on the semi-empirical models (Amahmid, Hasnaoui et al. (1999); Jiang and Ren (2001); Anwar- Hossain, Wilson (2002); Basak, Roy, et al. (2006); Srivastava and Singh (2010); Hamimid et al. (2011)), flows in porous medium remain of particulars interest and the basic picture stays clouded. In recent years, a new *generalized model* has been adopted by researchers interested by modeling these type-?ows (Nithiarasu, Seetharamu et al. (1997)). The generalized model form is a modified formulation of the Navier-Stokes equations, involving all the fluid forces and the solid matrix drag in the momentum equations. In general, the generalized model presents three pertinent features. First, its similarity to the Navier-Stokes equations allows the transitions to free fluid flow (when the porosity be the unit); second, it presents the flexibility to represent the two extended models (Brinkmanextended Darcy and Forchheimer-extended Darcy models), which are regarded as its limiting forms; and third, this model can be used to solve transient flows in porous media.

A large number of studies have confirmed the earlier developments. Besides, recent books by Nield and Bejan (2006), Ingham and Pop (2005), Vafai (2005) and Pop and Ingham(2001) show that investigating flows in porous medium becomes a classical subject. Furthermore, flows under external magnetic field are of practical interest and have been the subject of many earlier and recent studies for free fluid flows (Gelfgat and Bar-Yosaf (2001), Ece and Büyük (2006)). However, few studies have been conducted to fully investigate the heat transfer in porous medium with/ without the effect of external magnetic field (Grosan, Revnic et al. (2009)) under the numerous controlling parameters.

Furthermore, the study of the motion and heat transfer in electrically conducting fluid has met always with renewed interest due to the many applications in engineering problems such as MHD generators, plasma studies, nuclear reactors, and because of the effect on magnetic fields on the performance of many systems including liquid metals and alloys, mercury amalgams, and blood...

Several numerical simulations have been conducted in the past using conventional numerical method based on discretization of macroscopic equations. Recently, the Lattice Boltzmann Method (LBM) has met with significant success for numerical simulation and modeling of many classical and complex flows (Chen and Doolen (1998), Mezrhab, Jami et al. (2007), Semma, El Ganaoui et al. (2008), Succi

(2001)). The LBM have been used recently to investigate flows in porous media. For citation, Guo and Zhao (2002) use the LB method to investigate Poiseuille flow, Couette flow and lid-driven cavity flow in a saturated porous media, authors used a suitable forcing term early improved by Guo, Zheng et al. (2002) to eliminate the discrete lattice effects in the forcing term used in the LB equation. The developed model is useful in simulating flows in a medium with a variable porosity. It has been observed that the developed model produces satisfactory results for the above cited problems compared with the analytical or the finite-difference solutions. Seta, Takegoshi et al. (2006) used the same approach to investigate flow in porous media in square enclosure. It has been concluded that the LB method preserves more the computational cost than the FD method for the same grid size and gives a good agreement compared to the FE method either for the Brinkman-extended Darcy model and the Brinkman-Forchheimer model. Arab, Semma, Patevron and El-Ganaoui (2009) used a LB based numerical code to read (after special treatment) 2D digital images obtained by a Scanning Electron Microscope technique. The authors concluded on the LB method high level of predictability of heat and mass transfer phenomena in real porous material and to estimate physical properties such as the medium permeability which is hardly estimated experimentally. Chai, Guo et al. (2007) have investigated mixed heat convection in a driven cavity packed with porous media. Authors concluded that compared with traditional numerical methods, LBM offers flexibility, efficiency and outstanding amenability to parallelism when modeling complex flows.

Besides, Roussellet, Niu et al. (2011) used the LB method to investigate heat and fluid flow in a cubical porous medium packed with a set number of balls under a temperature sensitive magnetic field. It was found that heat transfer is enhanced by increasing the magnetic field; however it is reduced by increasing the balls number. Hao, Xinhua and Yongzhi (2011) simulated a multi-component system formed by fluid and magnetic particles using a multiphase LB model, under external magnetic field. Authors concluded that the LB method is so helpful to explore and understand the chainlike particles behavior when applying external magnetic field on a random distribution of particles. Chatterjee and Amiroudine (2011) used a non-isothermal LB model to predict the thermofluidic phenomena in a direct current MHD micropump. It was remarked that flow and heat transfer characteristics depend strongly on Hartmann, Prandtl and Eckert numbers and channel aspect ratios. An excellent agreement is also observed between LB results and experimental, analytical and other available numerical results in the literature. Ece and BÃ1/4vÃ1/4k (2006) have investigated the steady laminar natural-convection flow in an inclined square enclosure heated and cooled from adjacent sides in the presence of a magnetic field. The governing equations based on the stream function, vorticity and temperature

have been solved using the differential quadrature method for various Grashof and Hartman numbers and aspect ratios, inclination of the cavity and magnetic field orientations. Its has been observed that the flow characteristics, therefore the heat transfer rate are affected significantly by the variation of Hartman number, the aspect ratio and the inclination of the enclosure. Zhang, Jin et al. (2010) introduced a LB model to investigate a thermo-sensitive magnetic fluid in porous medium. Authors obtained excellent agreement with previous results and concluded that the LB method is a promising tool for understanding magnetic fluid non-isothermal behaviour in porous media.

Through this literature review, one can remark that the flow patterns and isotherms exhibit *distinctly* different behavior in differentially heated enclosures by varying each monitoring parameter. Additionally, no / very little works has been reported on this topic with full assessment of *all* flow parameters effects, and no focus is made on the *computational cost* in general when treating some heat transfer problem.

In the present paper, a thermal lattice Boltzmann model is developed and used to investigate the dynamic and thermal behavior in porous medium under inclined uniform magnetic field in a square enclosure. The effects of the Rayleigh number, the cavity inclination, the magnetic field magnitude (Hartmann number) and its orientation and the porous matrix effects (Darcy number and the medium porosity) -in wide ranges- on flow and heat transfer are analyzed and tabulated for benchmarking purposes. A simple and efficient accelerating technique is used to improve the convergence process.

# 2 Problem Statement and Solution Method

# 2.1 Configuration Model and Parameterization

The investigated problem is a two-dimensional square enclosure of edge *H* packed with a saturated porous media. The porous material is supposed to be homogeneous and isotropic with constant porosity. The non-slip boundary conditions hold on the four walls. A temperature difference  $\Delta T = T_h - T_c$  is applied between walls parallel to y-direction ( $T=T_h$  for x=0 and  $T = T_c$  for x = H) and zero heat flux is imposed to walls parallel to x-direction. The cavity is clockwise inclined by an angle  $\phi$ . A magnetic field of strength B reigns in the medium. The magnetic field is oriented to angle  $\psi$  from x-axis (Fig. 1). The gravity field reigns in the vertical descendant direction.

For the sake of comparison with previous studies, all predicted quantities are presented in a non-dimensional form. The reference scales  $l_0 = H$ ,  $U_0 = \alpha/H t_0 = H^2/\alpha$ ,  $p_0 = \rho U_0^2$  and  $\Delta T = T_h - T_c$  are used for length, velocity, time pressure and relative temperature respectively. Here  $\alpha$  is the effective thermal diffusivity.



Figure 1: Configuration model

The convective heat transfer is described using the average Nusselt number  $\overline{Nu}$  overall the whole domain and the average Nusselt number  $\overline{Nu}_0$  along the hot wall

$$\overline{Nu} = \frac{1}{\alpha \Delta T / H} \frac{1}{H^2} \int_{0}^{H} \int_{0}^{H} \int_{0}^{H} \left[ uT - \alpha \left( \frac{\partial T}{\partial x} \right) \right] dx dy$$
(1)

$$\overline{Nu}_{0} = \frac{1}{\alpha \Delta T / H} \frac{1}{H} \int_{0}^{H} -\alpha \left. \frac{\partial T}{\partial x} \right|_{x=0} dy$$
<sup>(2)</sup>

The flow is characterized by the Rayleigh number  $(10^4 \le Ra \le 10^7)$ , the Prandtl number (Pr  $\simeq 1$ ), the Darcy number  $(10^{-4} \le Da \le 10^{-2})$ , the Hartmann number  $(0 \le Ha \le 100)$ , the medium porosity  $(0 \le \varepsilon \le 1)$ , the cavity inclination  $(0^\circ \le \varphi \le 90^\circ)$  and the magnetic field orientation  $(0^\circ \le \psi \le 90^\circ)$ , defined as:

$$\begin{cases} Ra = \frac{g\beta\,\Delta T\,H^3}{\nu\alpha}, & \Pr = \frac{\nu}{\alpha}, \\ Da = \frac{\kappa}{H^2} \text{ and } Ha = HB\sqrt{\sigma/\mu} \end{cases}$$
(3)

The convergence criterion for steady state is defined as follows:

$$\left|\frac{\overline{Nu}(t+5000\Delta t)-\overline{Nu}(t)}{\overline{Nu}(t)}\right| \le 10^{-4} \tag{4}$$

#### 2.2 Continuum Formulation and Traditional Solution Methods

The physic of the problem is described as follows: The buoyancy force, acting parallel to the gravity vector, ascends the warm fluid particles which leave the hot wall to replace the cold particles at the upper region, the convective currents push the fluid to circulate near the walls. The movement is enhanced by increasing the temperature gradient, thus, the buoyancy force. Under a magnetic field (Lorentz force), the flow is decelerated and the convective motions are dumped with increasing the magnetic field strength which introduce a control parameter for the convective currents. The flow is governed by the Partial Differential Equations (PDE) that can be solved by using the classical numerical methods in CFD such as Finite Volumes (FV), Finite Elements (FE), Finite Difference (FD) or SPectral (SP) methods or using the new CFD tool, namely the LB method accounting for some considerations that will be shown in details in the following sections.

Under the Boussinesq approximation:  $\rho = \rho_0 (1 - \beta (T - T_\infty))$ ,  $(T_\infty$  is the reference temperature taken here the cold temperature) the Local Thermal Equilibrium assumption between fluid and solid phases and neglecting viscous heat dissipation and compression work done by the pressure, the averaged governing equations at the REV scale for the generalized model can be summarized for an incompressible fluid as follows:

## Continuity

$$\frac{\partial u_i}{\partial x_i} = 0 \tag{5}$$

#### Momentum

$$\frac{\rho_f}{\varepsilon} \left[ \frac{\partial u_i}{\partial t} + \frac{\partial}{\partial x_j} \left( \frac{u_j u_i}{\varepsilon} \right) \right] = -\frac{1}{\varepsilon} \frac{\partial}{\partial x_i} \left( \frac{p}{\varepsilon} \right) + \frac{1}{\varepsilon} \frac{\partial}{\partial x_i} \left( \mu \frac{\partial u_i}{\partial x_i} \right) + \frac{\rho_f}{\varepsilon} F_i$$
(6)

Energy

$$\Lambda \left[ \frac{\partial T}{\partial t} + u_i \frac{\partial T}{\partial x_i} \right] = \frac{\partial}{\partial x_i} \left( k_e \frac{\partial T}{\partial x_i} \right)$$
(7)

$$F_{i} = -\frac{\varepsilon v_{e}}{\kappa} u_{i} - \varepsilon F_{\varepsilon} \sqrt{\frac{u_{i} u_{i}}{\kappa}} u_{i} + \varepsilon g_{i} \beta (T - T_{\infty})$$
(8)

Where  $g_i \equiv (g \sin(\varphi), g \cos(\varphi))$  are the gravity-field components in the x - y system axis and  $\Lambda = \varepsilon(\rho C_p)_f + (1 - \varepsilon)(\rho C_p)_s$ .

Where the subscripts f and s correspond to fluid and solid phases and  $F_i$  is the forcing term components accounting for the porous medium and the buoyancy effects.

The first and second terms of  $F_i$  are the linear (LD) and non-linear (NLD) drags; the last term is the buoyancy force due to the gravity. The effective viscosity  $v_e$  is usually taken equal the fluid kinematic viscosity v.

Assuming the ratio between averaged heat capacity and the fluid heat capacity is the unity, the fluid diffusivity  $\alpha$  is defined as the ratio between the effective conductivity  $k_e$  and the fluid heat capacity  $(\rho C_p)_f$ .

If the medium characteristics (porosity  $\varepsilon$ , diameter of the solid particle  $d_p$ ) are defined, the relationship between the permeability  $\kappa$  and the porosity can be evaluated using the Kozeny-Carman's model as:

$$\kappa = \frac{\varepsilon^3 d_p^2}{36\eta \ (1-\varepsilon)^2} \tag{9}$$

Where  $\eta$  is a structural factor that depends on the particles shape and varies in the range 4< $\eta$ <5 as mentioned in (Alves, Neto et al. (2001). Taking  $\eta$ =4.167, the relation in Eq. (9) meets the Ergun's experimental model established as:

$$\kappa = \frac{\varepsilon^3 d_p^2}{150 \ (1-\varepsilon)^2}, \quad F_{\varepsilon} = \frac{1.75}{\sqrt{150 \varepsilon^3}} \tag{10}$$

 $F_{\varepsilon}$  is a geometric parameter.

Dividing the non-linear drag (NLD) by linear drag (LD), we found that it can be expressed in term of the viscous diffusion velocity v /H modulated by a factor depending on the porous medium characteristics ( $\varepsilon$  and Da) as:

$$\frac{|u|F_{\varepsilon}/\sqrt{\kappa}}{v_e/\kappa} = \frac{|u|}{U_1} \tag{11}$$

where  $U_1 = 7\sqrt{\varepsilon^3/Da} \cdot \frac{v}{H}$ .

Note that such a formula based on the Ergun's model and can give us idea to simplify Eq. (8).

In the presence of a magnetic field **B** oriented to an angle  $\psi$  from the x-axis, an electromagnetic force  $\mathbf{F}_{em}$  (Lorentz force) must be added to the forcing term  $F_i$  and is written as:

$$F_{em-i} = \sigma\left[(B_j u_j) B_i - B^2 u_i\right] \tag{12}$$

where  $\sigma$  is the electrical conductivity of the ?uid and  $B_j$  denotes the magnetic fields components  $B_x = B \cos(\psi)$  and  $B_y = B \sin(\psi)$ . We assume the Joule heating can be neglected since  $Ra > 10^3$  and Ha < 200.

In general case, the cavity is inclined from the horizontal in the clockwise direction by an angle  $\phi$  (Fig. 1). The forcing term of Eq. (8), in its two-dimensional final form, will take the following form:

$$F_{i} = \varepsilon \left( g_{i}\beta(T_{\infty} - T) - \frac{v_{e}}{\kappa} u_{i} - F_{\varepsilon}\sqrt{u_{i}u_{i}/\kappa} u_{i} + \sigma \left[ (B_{j}u_{j})B_{i} - B^{2}u_{i} \right] \right)$$
(13)

The continuity, momentum and energy equations are solved in the lattice Boltzmann space and scaled by the above mentioned reference scales when presented in the following.

#### 2.3 Solution Based on Lattice Boltzmann Method

In the last decades the LB method is considered to to offer progressively an alternative numerical method traditional Computational Fluid Dynamics (CFD) for simulating fluid flows. In the LBM approach, the fluid is modeled by fictitous particle modeled by distribution functions that occupy nodes and transit to neighboring nodes in a streaming phase. The Poisson equation is time consuming and its solution takes typically 80–90% of the CPU time in traditional CFD solvers (Madabhushi and Vanka (1991)), its absence in LBM means that codes are comparatively fast based on time step per grid point. We have found that a D2Q9-D2Q4 lattice is a suitable model for simulating thermal flows, for the raisons that is more stable then the D2Q9-D2Q9 model, it preserves the computational efforts, since the collision step takes around 70% of the CPU time (Djebali and ElGanaoui (2011)).

The evolution of the distribution functions in the D2Q9-D2Q4 lattice model in the presence of source term  $S_k$  is written as follows:

$$\begin{cases} f_k(x',t') - f_k(x,t) = \\ -\left(f_k(x,t) - f_k^{eq}(x,t)\right) / \tau_{\upsilon} + \Delta t \, S_k, \ k = 0,8 \\ g_k(x',t') - g_k(x,t) = \\ -\left(g_k(x,t) - g_k^{eq}(x,t)\right) / \tau_{\alpha}, \quad k = 1,4 \end{cases}$$
(14)

Where  $x' = x + e_k \Delta t$ ,  $t' = t + \Delta t$ , **x** is the lattice site,  $\Delta t$  is the time step,  $\Delta x$  is the lattice grid spacing unit (= $\Delta y$ =1),  $e_k$  discrete lattice velocity, and  $f_k$  and  $g_k$  are the density and temperature distribution functions. The correspondent equilibrium parts  $f_k^{eq}$  and  $g_k^{eq}$  are defined as:

$$\begin{cases} f_k^{eq}(x,t) = \omega_k \rho [1+3 e_k.u + 4.5 (e_k.u)^2 - 1.5 u^2] \\ g_k^{eq}(x,t) = 0.25 T [1+2 e_k.u] \end{cases}$$
(15)

It was demonstrated in (Guo, Zheng et al. (2002)) that the suitable form of the forcing term  $S_k$  for incompressible fluid flow is written as:

$$S_k = w_k \rho \left(1 - \frac{1}{2\tau_v}\right) \left(\frac{e_k \cdot F}{3} + \frac{uF : (e_k e_k - 3I)}{9\varepsilon}\right)$$
(16)

Where  $F \equiv F_i$ , i=1, 2.

The single-relaxation-times  $\tau_v$  and  $\tau_\alpha$  are linked to the kinematic viscosity and the heat diffusivity as

$$\upsilon = \frac{2\tau_{\upsilon} - 1}{6} \frac{\Delta x^2}{\Delta t}, \quad \alpha = \frac{2\tau_{\alpha} - 1}{4} \frac{\Delta x^2}{\Delta t}$$
(17)

 $\omega_k$  are weighting factors and  $e_k$  are the lattice velocity vectors. For the D2Q9 LB model we have:

$$\begin{pmatrix} \omega_k \\ e_{k,x} \\ e_{k,y} \end{pmatrix} = \begin{pmatrix} \frac{4}{9}, & \frac{1}{9}, & \frac{1}{9}, & \frac{1}{9}, & \frac{1}{9}, & \frac{1}{36}, & \frac{1}{36}, & \frac{1}{36}, & \frac{1}{36} \\ 0, & 1, & 0, & -1, & 0, & 1, & -1, & -1, & 1 \\ 0, & 0, & 1, & 0, & -1, & 1, & 1, & -1, & -1 \end{pmatrix}$$
(18)

It is well to mention that the Prandtl number can be linked to the relaxation times in D2Q9-D2Q4 double population approach as:

$$Pr = \frac{2}{3} \frac{\tau_{\upsilon} - 0.5}{\tau_{\alpha} - 0.5} \tag{19}$$

In LB heat and flow modeling philosophy, the macroscopic variables: density, velocity and temperature, are computed as follows:

$$\begin{cases} \rho(x,t) = \sum_{k=0,8} f_k & (1) \\ \rho u(x,t) = \sum_{k=0,8} e_k f_k + \frac{\Delta t}{2} F & (2) \\ T = \sum_{k=1,4} g_k & (3) \end{cases}$$
(20)

We note that in the velocity field computation, we will not use the same procedure typically adopted in Seta, Takegoshi et al. (2006) and Guo and Zhao (2005); that is to take advantage of the quadratic form of Eq. (20.2) to obtain new formulation. Due the complexity of the complexity of Eq. (20.2) in term of the velocity vector (**u**), in our algorithm, a *new-old* technique is adopted, ie to compute  $\mathbf{u}^{new}$  we use  $F(\mathbf{u}^{old})$  (in Eqs. (13) and (16)), where  $\mathbf{u}^{old}$  and  $\mathbf{u}^{new}$  are the velocity fields in two successive iterations *t* and  $t+\Delta t$ . Using this technique in spite of that adopted in

Seta, Takegoshi et al. (2006) and Guo and Zhao (2005), will not have effect on the results since the time-step in LB method is very short.

Finally, to accelerate the steady state convergence, the procedure used in (Premnath, Pattison et al. (2009)) is adopted here. That is by incorporating accelerating parameters  $\gamma_{v}$  and  $\gamma_{\alpha}$  in Eqs. (15-17):

$$\begin{cases} f_k^{eq}(x,t) = \omega_k \rho \left[ 1 + 3 \, e_k . u + \frac{4.5 \, (e_k . u)^2 - 1.5 \, u^2}{\gamma_0} \right] \\ g_k^{eq}(x,t) = 0.25 \, T \left[ 1 + \frac{2 \, e_k . u}{\gamma_\alpha} \right] \end{cases}$$
(21)

and

$$\frac{\nu}{\gamma_{\nu}} = \frac{2\tau_{\nu} - 1}{6} \frac{\Delta x^2}{\Delta t}, \quad \frac{\alpha}{\gamma_{\alpha}} = \frac{2\tau_{\alpha} - 1}{4} \frac{\Delta x^2}{\Delta t}$$
(22)

More details on the application of this technique in thermal flows can be found in (Djebali and ElGanaoui (2011)). The accelerating parameters  $\gamma_{v}$  and  $\gamma_{\alpha}$  are chosen here to be 0.1 for all cases. The kinematic viscosity is taken 0.01, 0.007, 0.003 and 0.002 for *Ra* of the same order of  $10^3$ - $10^4$ ,  $10^5$ ,  $10^6$  and  $10^7$  respectively.

#### 2.4 Boundary conditions treatments

Implementation of boundaries conditions is a very important issue in LBM since it affects the accuracy of the computations. The second-order bounce back boundary rule for the non-equilibrium distribution function proposed by Zou and He (1997) is used to account for the no-slip boundary condition along the four walls as:

$$(f - f^{eq})^{<} = (f - f^{eq})^{>}$$
(23)

where the asterisk "<" and ">" denote inner and outer particles respectively at the wall node.

For the temperature field, the temperature distribution functions at the isothermal walls obey:

$$g^{<} = -g^{>} + 0.5 T_{wall} \tag{24}$$

The adiabatic boundary condition is transferred to Dirichlet-type condition using the conventional second-order finite difference approximation as:

$$q_{wall} \approx -k_e \left(\frac{3g_{wall} - 4g_1 + g_2}{2\Delta x}\right) + O(\Delta x^2)$$
<sup>(25)</sup>

### 3 Results and Analysis

We note that we have validated our thermal LB codes for previously (see the reviews articles Djebali, Sammouda et al. (2010); ElGanaoui and Djebali (2010) and Djebali and ElGanaoui (2011))). The present work defines a step ahead to consider complex situations. Namely the buoyancy-driven flow in air-filled square porous media with heated differentially walls is here considered. The problem was studied in parts previously (Nithiarasu, Seetharamu et al. (1997)) using the FE method and recently (Guo and Zhao (2005)) using the LB method. The authors' results are gathered to the present ones for comparison sake for different Darcy and Rayleigh numbers and medium porosities. The second numerical test is a natural-convection free-fluid flow under a uniform magnetic field; the solution is obtained later by using the ADI (Alternating Direction Implicit) method. The comparisons are indicated by the averaged Nusselt over the computational domain. The stream-function and isotherms contours are also plotted and analyzed.

### 3.1 Test Case 1: Porous Media Flow

By taking  $\varepsilon = 1$ , the Eq. (6) reduces to the standard Navier-Stokes equations for fluid flow. Our results for *Pr*=0.71 and *Da*=10<sup>10</sup> are compared to those of de Vahl Davis (1983) and Le Quéré and Roquefort (1985) under the above mentioned lattice sizes (Table 1). It is found that the present LB thermal model provides satisfactory agreement. The maximum error observed is less than 1%, which is acceptable for engineering applications. The divergence at the insulated walls is of  $O(10^{-7})$  order which confirms the second order differencing in Eq. (25).

| Table  | 1:   | Comparison    | of the   | average  | Nusselt   | number    | with  | de a | - de | Vahl | Davis |
|--------|------|---------------|----------|----------|-----------|-----------|-------|------|------|------|-------|
| (1983) | ) an | nd b- Le Quer | e, and I | De Roque | efort (19 | 85) for P | r=0.7 | 1.   |      |      |       |

|    | Ra      | 10 <sup>3</sup> | 104   | 10 <sup>5</sup> | 106   | 107    |
|----|---------|-----------------|-------|-----------------|-------|--------|
| Nu | а       | 1.118           | 2.243 | 4.519           | 8.800 | -      |
|    | b       | 1.118           | 2.245 | 4.522           | 8.825 | 16.520 |
|    | Present | 1.116           | 2.229 | 4.484           | 8.734 | 16.376 |

The grid sensitivity is also tested to let our code giving accurate predictions. Table 2 shows that the above mentioned grid sizes are the appropriate for the corresponding Rayleigh numbers. Cite for example for  $Ra=10^5$ , the Nusselt number change amount is about 0.09% from the grid size  $90 \times 90$  to  $100 \times 100$ .

In this test we set  $\varepsilon$ =0.4, Pr=1, the Rayleigh number varies from 10<sup>3</sup> to 10<sup>7</sup> and the Darcy parameter takes 10<sup>-4</sup> and 10<sup>-2</sup>. In the computations, we use the lattice sizes ranging from 50 to 150 by step 25 when increasing the Rayleigh numbers from 10<sup>3</sup>

Table 2: Grid sensitivity check based on the average Nusselt number  $\overline{Nu}$  for Pr=0.71.

| Grid          | size | 50×50   | 60×60   | 70×70   | 80×80   | 90×90            | 100×100 |
|---------------|------|---------|---------|---------|---------|------------------|---------|
| Da-           | 104  | 2.2204  | 2.2245  | 2.2273  | 2.2294  |                  |         |
| $\Lambda a =$ | 105  |         |         | 4.4670  | 4.4746  | 4.4802           | 4.4841  |
| Grid          | size | 100×100 | 110×110 | 120×120 | 130×130 | $140 \times 140$ | 150×150 |
| Da-           | 106  | 8.7044  | 8.7183  | 8.7343  | 8.7348  |                  |         |
| Ra=           | 107  |         |         |         | 16.3475 | 16.3662          | 16.3764 |

Table 3: Comparison of the average Nusselt number with c- Guo and Zhao (2005) and d- Nithiarasu, Seetharamu et al. (1997) for Pr=1

| Da               | Ra              |         | <i>ε</i> =0.4 | ε=0.6 |         |       |
|------------------|-----------------|---------|---------------|-------|---------|-------|
| Du               |                 | Present | с             | d     | Present | d     |
|                  | 10 <sup>5</sup> | 1.066   | 1.066         | 1.067 | 1.072   | 1.071 |
| 10 <sup>-4</sup> | 106             | 2.595   | 2.603         | 2.550 | 2.711   | 2.725 |
|                  | 107             | 7.816   | 7.788         | 7.810 | 8.532   | 8.183 |
|                  | $10^{3}$        | 1.008   | 1.008         | 1.010 | 1.013   | 1.015 |
| 10 <sup>-2</sup> | 10 <sup>4</sup> | 1.360   | 1.367         | 1.408 | 1.491   | 1.530 |
|                  | 10 <sup>5</sup> | 2.989   | 2.988         | 2.983 | 3.435   | 3.555 |

Table 4: Comparison of the average Nusselt number  $\overline{Nu}_0$  obtained using the LBM with ADI predictions (Rudraiah, Barron et al. (1995)) for Pr=0.733, symbol "<sup>†</sup>" denotes our results.

|            | <i>Ha</i> =10    |                  |        | <i>Ha</i> =50    |                  |        | <i>Ha</i> =100   |                  |        |
|------------|------------------|------------------|--------|------------------|------------------|--------|------------------|------------------|--------|
| Ra/Pr      | LBM <sup>†</sup> | FVM <sup>†</sup> | ADI    | LBM <sup>†</sup> | FVM <sup>†</sup> | ADI    | LBM <sup>†</sup> | FVM <sup>†</sup> | ADI    |
| $2.10^4$   | 2.2780           | 2.2976           | 2.2234 | 1.0900           | 1.1154           | 1.0856 | 1.0177           | 1.0113           | 1.0110 |
| $2.10^{5}$ | 5.0518           | 4.9865           | 4.8053 | 3.0784           | 3.2901           | 2.8442 | 1.4866           | 1.6430           | 1.4317 |
| $2.10^{6}$ | 9.8852           | 9,7904           | 8.6463 | 8.9326           | 9.0563           | 7.5825 | 6.7142           | 7.2416           | 5.5415 |

to  $10^7$  (respectively). Figure 2 presents the streamline contours and the isotherm lines for  $Da=10^{-4}$  and a Rayleigh number ranging from  $10^5$  to  $10^7$ . It is well observed, qualitatively, that our results agree well with the previous findings. When increasing the Rayleigh number, the flow patterns show an inclined stratification for the temperature fields and the boundary layers become more stretched to the isothermal walls. Quantitatively, the averaged Nusselt number is tabulated in Table 3 for different Da and Ra. The present predicted results are gathered to available referenced results based on different numerical methods.



Figure 2: Dynamic (a) and thermal (b) structures for  $\varepsilon = 0.4$ , Pr = 1,  $Da = 10^{-4}$ .

In modeling porous media flows, it is important to know the ratio NLD/LD, which determines the limit of using the two above mentioned models for porous media flows. In convection flows, the characteristic velocity is  $U_0 = \sqrt{g\beta\Delta TH}$ , the ratio NLD/LD as defined in Eq. (11) expressed as function of flow, medium and fluid parameters reads:

$$\frac{NLD}{LD} = \frac{1}{7} \sqrt{\frac{Ra}{Pr} \frac{Da}{\varepsilon^3}}$$
(26)

A computation is performed for  $Ra=10^4$ ,  $Da=10^{-4}$ , Pr=1 and  $\varepsilon$ =0.9, leading to NLD/LD=0.196. It has been shown that the present generalized model with and without NLD term (ie setting  $F_{\varepsilon}$ =0 in Eq. (8)) does not show significant difference.

#### 3.2 Test Case 2: Free-fluid Flow under Vertical Magnetic Field

The following section consists of simulating free fluid flow in a square cavity heated and cooled on side walls and insulated on the horizontal walls, previously investigated by Rudraiah, Barron et al. (1995). The fluid flow is subjected to the effects of buoyancy and a vertical (descendent) magnetic field. The heat transfer is quantified by the averaged Nusselt number  $\overline{Nu}_0$  along the hot wall for a wide range of parameters (14660  $\leq Ra \leq$  1466000,  $0 \leq Ha \leq$  100, Pr=0.733). The present numerical solutions are summarized in Table 4 and compared to Rudraiah's results using the ADI (Alternating Direction Implicit) method. To check the justness of our results for the average Nusselt number, a test is made using the Finite Volume method. We have remarked that the present LB results agree well with those of the FVM ones. Our codes give also patterns of the streamlines and isotherms very similar to the Ece and Büyük (2006)'s results. However their numerical results are found to be under estimated by unity.

The force-ratio of the buoyancy to the electromagnetic ones is proportional to  $Ra/Ha^2$ . It is well known that the Lorentz force reduces velocities and dumps the convection currents and heat transfer. Accordingly, major effects are observed between the cases: with/without Lorentz force. In the studied ranges of the monitoring number, the buoyancy force is more effective as  $Ra > 10^4$  (since  $Ra/Ha^2 \gg 1$ ), the rise of the Nusselt number is more expressed as shown in Tab. 3. See for example for Ha=100, the Nusselt number rise from Ra=146600 to 1466000 is about 46% and it is about 352% from Ra=146600 to 1466000 since magnetic force dumps convective current then heat transfer, but it has minor effects for high Rayleigh numbers since  $Ra/Ha^2 \gg 1$ .

Figures 3(a) and 3(b) show the streamlines and isotherms contours for different inclination angles for both the cavity and the magnetic field at  $Ra=10^5$ . The magnetic force is expressed as  $F_{em} = -\sigma B^2 u_x$ , then it opposes to the convective currents. We see for example, for Ha=10 a thermal stratification is well established by increasing the Rayleigh number to 1466000. However, increasing the Hartmann number to 100, the isotherms contours undergo a counter-clockwise rotation, meaning that only a vertical flowing is allowed.

# 3.3 Porous Media Flow under Magnetic Field

In this section the combined effect of porous medium and external magnetic force on flow pattern is considered. A parametric study exploring the parameters effects is proposed based on three axes: first, the effect of the Rayleigh number ( $10^4$  to  $10^6$ ) and the cavity inclination ( $0^\circ$  to  $90^\circ$ ), second, the effect of the Darcy number ( $10^{-4}$  to  $10^{-2}$ ) and the medium porosity (0.4 to 0.8), and last, the effect of the Hartmann number (10 to 100) and the magnetic field inclination ( $0^\circ$  to  $90^\circ$ ). The Prandtl number is chosen to be 1.

The numerical simulations are carried out based on the same conditions presented in section 2.4.

**Rayleigh Number and Cavity Inclination Effects:** To account for this combined effect in the porous medium in the presence magnetic field, we set  $\varepsilon$ =0.4, Da=10<sup>-2</sup>, Ha=50 and  $\psi$ =0°. As shown in Figs. 4(a) and 4(b), variations of the Rayleigh number and the cavity inclination have important effects on dynamic and thermal fields structures. For  $\phi$ =0°, increasing the buoyancy force (*Ra*) enhances the convective



Figure 3: Dynamic (a) and thermal (b) structures for free fluid flow for *Pr*=0.733 and  $\phi$ =0°



Figure 4: Dynamic (a) and thermal (b) structures for Pr=1,  $Da=10^{-2}$ ,  $\varepsilon=0.4$ , Ha=50, and  $\psi=0^{\circ}$ .

currents dumped (or suppressed) by the magnetic force effect for low Rayleigh numbers. The isotherms become stretched near the isothermal walls and equally spaced at the cavity core leading to a fully established stratification. For high cavity inclination ( $\phi$ =90°) in the counter-clockwise direction, the flow pattern is more complex due to the Rayleigh-Bénard phenomenon: the heat transfer is purely conductive for Ra=10<sup>4</sup> and a pair and two-pair-counter-rotating cells are formed for (respectively) Ra=10<sup>5</sup> and 10<sup>6</sup>, compared to free fluid flow in enclosure.

The flow pattern is more illustrated when plotting the velocity components at midheight and mid-width (Fig. 5). With increasing the Rayleigh number, the x-velocity magnitude increases and its maximums locations displace to the horizontal adiabatic walls. The same behaviour is presented for the y-velocity with a maximum location moving near the isotherm walls. similarly, increasing the inclination angle reduces the velocity components for lowers Rayleigh numbers (due to the conductive regime) but raises the velocity components for high Rayleigh number (due to the Rayleigh-Bénard convection). The averaged Nusselt number at the isothermal wall for  $Ra=10^6$  is 5.0647, 5.4169 and 4.3969 for respectively  $\phi=0^\circ$ , 45° and 90°.

**Darcy Number and Medium Porosity Effects:** In this part we choose  $Ra=10^5$ , Ha=50 and  $\phi = \psi = 0^\circ$ . The flow structure is for all a single clockwise rotating cell. As for the previous investigation, the effects of the Darcy number and the medium porosity are significant. With decreasing the Darcy number (logarithmically), the infiltration velocity in the medium decreases considerably, the thermal behavior tends to take a conductive mode signature.

The presence of the magnetic field results in decreasing the heat transfer compared to the case of flow in porous media without external force and forming in somewhat a diagonal-acting region as shown in Figs. 7(a) and 7(b). On the other hand, increasing the medium porosity enhances slightly the convective currents near the insulated walls, resulting in a small rotation of the isotherms and diagonally-extending the elliptic cell at the core.

In general, for the chosen dimensionless parameters there are no significant changes in the flow and thermal behaviors when varying the medium porosity under the present magnetic field magnitude. The change should be more expressed for low Hartmann number, since increasing the medium porosity results in a free fluid flow.

As we can see, also, in Fig. 6, the flow presents a symmetric pattern relative to the cavity center. For a fixed Darcy number, increasing the medium porosity raises the maximum value of u(0.5,y) and v(x,0.5).

However, increasing the Darcy number reduces effectively the velocity components strength: as for  $\varepsilon$ =0.8, the x-velocity and its y-location are 13.5501(0.91),



Figure 5: Velocities profiles at the horizontal and vertical mid-plans for different Rayleigh numbers and cavity inclinations for  $Da=10^{-2}$ ,  $\varepsilon=0.4$ , and Ha=50.



Figure 6: Velocities profiles at the horizontal and vertical mid-plans for different Darcy numbers and medium porosities for  $Ra=10^5$ ,  $\varphi=0^\circ$ , and Ha=50.



Figure 7: Dynamic (a) and thermal (b) structures for  $Ra=10^5$ ,  $\phi=0^\circ$ , Pr=1, Ha=50 and  $\psi=0^\circ$ .



Figure 8: Effect of the Darcy number on thermal structure for  $Da=10^{-4}$ ,  $10^{-3}$  and  $10^{-2}$  (from left to right). For  $Ra=10^5$ ,  $\phi=0^\circ$ , Pr=1, Ha=50 and  $\psi=0^\circ$ .  $\varepsilon=0.4$ : solid line,  $\varepsilon=0.6$ : dashed line and  $\varepsilon=0.8$ : dash-doted line.



Figure 9: Velocities profiles at the horizontal and vertical mid-plans for different Hartmann numbers and magnetic field orientations for  $Ra=10^5$ ,  $\varphi=0^\circ$ ,  $Da=10^{-2}$  and  $\varepsilon=0.4$ .

9.2687(0.93) and 2.6161(0.97) for respectively  $Da=10^{-4}$ ,  $10^{-3}$  and  $10^{-2}$ . Then, their location moves gradually towards the wall. The behaviour is the same for the y-velocity component: the y-velocity and its x-location are: 13.9512(0.08), 9.9380(0.06) and 2.5143(0.05) for  $Da=10^{-4}$ ,  $10^{-3}$  and  $10^{-2}$  respectively. More-



Figure 10: Dynamic (a) and thermal (b) structures for  $Ra=10^5$ ,  $\phi=0^\circ$ , Pr=1,  $Da=10^{-2}$  and  $\varepsilon=0.4$ 

over, the porosity effect is found to be suppressed with increasing Darcy number: for low Darcy number, the medium porosity has a modest effect, but has little effect for high Darcy number. This behaviour is well demonstrated in Fig. 8, that by decreasing the medium porosity, the thermal structure undergoes a counterclockwise rotation. At the same time, increasing the Darcy number, the porosity effect becomes minority.

The averaged Nusselt number at the isothermal wall for  $Da=10^{-2}$  is 1.8854, 1.9742 and 2.0305 for respectively  $\varepsilon=0.4$ , 0.6 and 0.8.

**Hartmann Number and Magnetic Field Inclination Effects:** In this part we choose  $Ra=10^5$ ,  $\phi=0^\circ$ ,  $Da=10^{-2}$  and  $\varepsilon=0.4$ . As it can be seen in Fig. 9, the inclination angle variation (of the magnetic field) has no effects on mid-plan velocity traces for low Hartmann number (Ha<10); the behaviour joins those presented in Fig. 6 ( $Da=10^{-2}$ ). However, for high Hartmann numbers, increasing the angle  $\psi$ , there will be a balance between the suppressed rate in the x-velocity and recompensed part in the y-component, that is due to the duality  $sin(\psi)-cos(\psi)$ . For Ha=100, the Nusselt number at isothermal walls is 1.2069, 1.3088 and 1.2096 for respectively  $\psi=0^\circ$ ,  $45^\circ$  and  $90^\circ$ .

In Fig. 10(a) and 10(b), one can say that the magnetic field strength and inclination have the significant effect on the dynamic structure. The thermal structure seems to be indifferent to the magnetic field inclination. This is confirmed by the quasi constant heat transfer for the three Hartmann number values. The relative Nusselt number variation is less than 3%, obtained for Ha=50. When the magnetic field is applied in 'x+' direction the central eddy is extended in the vertical direction and slows down with increasing the Hartman number. When the magnetic field is applied diagonally, the dynamic structure becomes more extended diagonally. When the magnetic field is applied in the 'y+' direction the dynamic central eddy becomes extended horizontally and two small vortices appear in the core region. Increasing more the Hartmann number, the isotherms becomes equally spaced yielding to a diagonal thermal stratification.

# 4 Conclusion

Several numerical simulations have been conducted in the past by using conventional numerical method based on discretization of macroscopic equations. Dealing with transfers in complex media, mostly, numerical studies in CFD suffer from many difficulties, such as stability, accuracy, computational cost, memory requirements...

Recently, the Lattice Boltzmann Method (LBM) has met with significant success for numerical simulation and modeling of many classical and complex flows. In

recent works of the authors, investigations shown the validity and the accuracy for the based LBM classes of methods for solving flow dynamic, and extended development to thermal LBM provided results for coupled heat and dynamic fields noticeably involving solid/liquid transition.

LB method is found to be more practical at least for saving computational time and easy incorporating source terms, like for this study investigating heat and fluid flow under buoyancy and external inclined magnetic forces.

This paper provides a step ahead on the validation and confirmation of potential use of the LBM class of methods for stiff applications.

Two degrees of complex conditions has been considered in the present paper to fully investigating the dynamic and thermal behavior in porous medium, flow under uniform magnetic field and their combination in a square enclosure.

The flow and thermal patterns depend strongly on the Rayleigh number the Darcy parameter and the cavity inclination, however it depend marginally on the medium porosity under moderate Hartmann number. Increasing the Hartmann number results in suppressing the convective currents inside the cavity and then reducing greatly the heat transfer rate quantified by the help of Nusselt number along heated/cooled wall and overall the medium. The magnetic field inclination affects strongly the dynamic structure; however, no significant effects for the temperature field have been remarked.

Its is found through this study, that the LB method is a reliable tool for investigating MHD convective heat transfer in confined space. Additionally, this computational technique is so simple for coding, treating boundary conditions, accounting for complex physics such as external magnetic force and porous matrix, and particularly preserving computational cost.

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